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Interplanetary Program To Optimize Simulated Trajectories (IPOST)

Volume IV - Sample Cases

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1.0 INTRODUCTION

The Interplanetary Program to Optimize Simulated Trajectories (IPOST) is intended to support many analysis phases, from early interplanetary feasibility studies through spacecraft development and operations. The IPOST output provides information for sizing and understanding mission impacts related to propulsion, guidance, communications, sensor/actuators, payload, and other dynamic and geometric environments.

Much of the overall architecture for IPOST has been derived from the Program to Optimize Simulated Trajectories (POST). Indeed certain POST parameters and capabilities have been incorporated into IPOST to aid in POST-IPOST user compatibility. IPOST has extended trajectory capabilities to target planets and other celestial bodies with intermediate and velocity correction maneuvers. IPOST capabilities and limitations are summarized in Table 1-1.

| FEATURE | CAPABILITY |
|------------------------|---|
| Optimization method | Explicit (Master/subproblems), Implicit (collocation) |
| Optimization algorithm | NPSOL · |
| Optimization | ΔV magnitude, mass, time, |
| parameter* | |
| Maximum controls | 25 (Master), 45 (subproblems), 1700 (collocation) |
| Control parameters* | Values of event criteria, ΔV , arrival conditions, thrust, |
| Maximum targets | 25 (Master), 45 (subproblems), 1700 (collocation) |
| Target parameters* | Time, position, velocity, orbital conditions, |
| Targeting method | NPSOL, Newton-Raphson, special Onestep |
| Sensitivity matrix | Finite differencing, analytic for special interplanetary |
| | targeting |
| Maximum events | 100 |
| Event criteria* | Time, distance, speed, closest approach, |
| Event activities | Info, impulsive AV, launch, orbit insertion, mass |
| | jettison |
| Maximum maneuvers/ | 15 |
| subproblems | |
| Trajectory propagation | Conic, Onestep, Multiconic, Encke, Cowell, implicit |
| Planetary bodies | Sun, nine planets, Earth's moon, any user-defined bodies |
| Ephemeris | Analytic, precision (JPL) |
| Trajectory | Central body, perturbing bodies, radiation pressure, |
| perturbations | J2, aerodynamics, thrust |
| Input/Output frames | Ecliptic or planet equator, Mean 1950 or Mean 2000 |
| * User selectable | |
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Table 1 - 1. IPOST Features/Capabilities

IPOST, along with members of its family, such as POST and IPREP, can analyze and support almost every activity associated with space exploration (Figure 1-1).

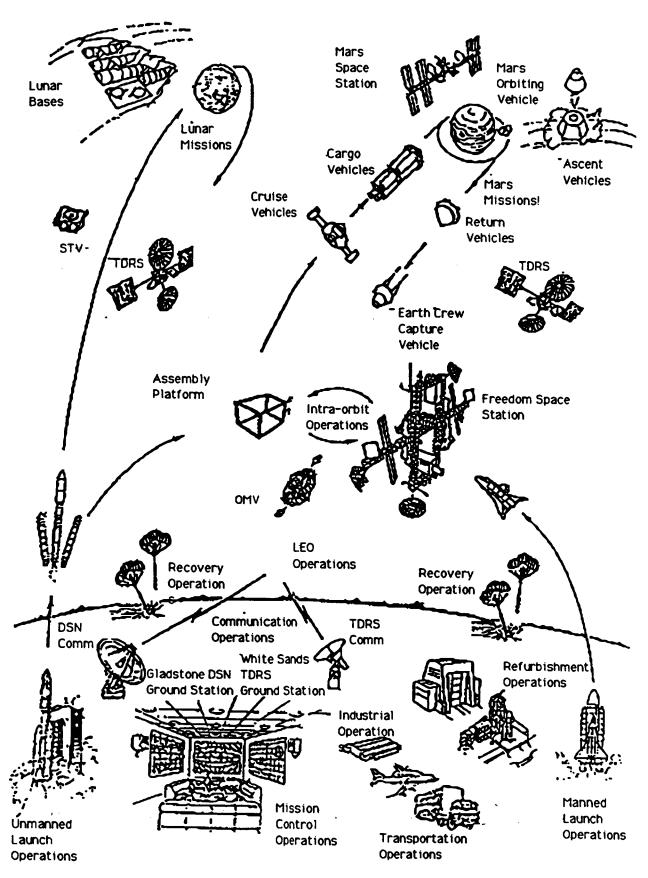


Figure 1 - 1. Space Exploration Infrastructure

IPOST is event driven. That is, the user defines a sequence of events which are executed in the simulation process. The events can be triggered by different criteria, such as absolute or relative time, distance from a body, or propellant consumption. At the event times, various activities can be initiated or terminated, such as employing a different thrust steering law, changing trajectory propagators or propagation step size, performing an impulsive delta velocity maneuver or jettisoning a probe or stage.

The time period between two contiguous events is called a phase. Trajectory propagation takes place in each phase. Five types of propagators are available (listed in order of increasing accuracy and decreasing computational speed): Conic, Onestep, Multiconic, Encke, Cowell. Propagator selection depends upon user needs, such as simple fast simulations for parametric feasibility analysis, or precision detailed trajectories to support subsystem design.

IPOST can run a single trajectory simulation or it can run multiple simulations. For multiple simulations, one can run a parametric scan and/or an optimization mode. The search mode will vary one parameter, such as planetary arrival time, over a specified interval and increment size, and perform a simulation (or optimization) for each search parameter value.

The optimization mode will optimize a user cost/objective function, such as maximum mass that can be placed in a desired orbit, subject to user-specified constraints. The constraint variables, such as periapsis altitude or orbital inclination, are called dependent variables or target parameters. The parameters which are free to vary, such as maneuver delta velocity (ΔV), are called independent variables or control parameters. As part of, or instead of, optimization, trajectory targeting can be performed. In this case, there is no cost function and the IPOST problem reduces to finding a set of control parameter values that meet specified target parameter conditions.

Generalized targeting and optimization uses the Stanford NPSOL algorithm. For certain types of problems, a trajectory decomposition method is available. There is a master optimization process which requires that the trajectory be divided into legs or sub-problems. Each sub-problem is an optimization problem in itself, containing controls, constraints and an (optional) objective function. A special application of decomposition is the Interplanetary Targeting and Optimization Option (ITOO). This technique uses analytical partials generated during nominal trajectory propagation to determine minimum ΔV (or mass) trajectories, usually for gravity assist (swingby) missions.

In addition to the classic method of explicit optimization, there exists an option to perform implicit optimization using the collocation method. In this case, each phase is divided into independent segments which are allowed to vary subject to intersegment continuity and the equations of motion. Optimization using collocation is less sensitive to faulty initial guesses, but requires much greater CP time than explicit optimization to achieve the same level of accuracy.

IPOST input is via three namelists: \$TOP, \$TRAJ and \$TAB. \$TOP contains a description of the targeting and optimization problem. It must be input first. \$TRAJ contains data that describes each mission event/phase. It must follow \$TOP, and there must be one \$TRAJ for each event. \$TAB is used to input tabular data such as thrust vs. time or drag coefficient vs. mach number and angle of attack. Input and output units are metric.

2.0 APPLICATIONS

Examples of mission applications are shown in Table 2 - 1. They illustrate some of the diverse IPOST model capabilities, including lunar, interplanetary, orbital, thrusting (impulsive, low, high), and gravity assist.

The typical IPOST application is usually in the form of run sequences which compare various mission options. These analysis threads build on each other, culminating in a reference mission which is used to support detailed system design and analysis. Table 2 - 2 illustrates representative mission threads which exercise key IPOST capabilities.

For example, in the Comet Rendezvous thread, each case is actually several runs of IPOST to generate parametric data such that mission decisions and refinements can be made. The sequence of multiple runs per case feeds each succeeding case with each case becoming more realistic in terms of model fidelity, and encompassing more system objectives and constraints.

The first step in the Comet Rendezvous thread is to define mission requirements (necessary conditions) and goals (desired conditions), as well as any known constraints, such as technology status. In this thread, a mission requirement would be to successfully rendezvous with a specific comet in a specific time frame. A mission goal might be to collect data on planets or bodies that are encountered during the interplanetary trajectory from Earth to the comet. A mission constraint might be the availability of a Cesium ion thrust engine powered by solar arrays, which provide limits on power/thrust levels and on specific impulse.

The first case is an approximate impulsive ΔV solution using a Venus gravity assist. This examines coarse energy requirements, benefits of gravity assist, and optimum mission opportunities (launch-arrival dates with payload/launch mass sensitivities). The mission may be analyzed as separate phases, e.g., Earth to Venus, Venus to comet approach, rendezvous and stationkeeping.

The second case models a low thrust mission using a single thrust segment with variable steering and variable throttle. Implicit optimization (collocation) is used. This recognizes the coarseness of the initial guess, and provides rapid solution searches. A determination is made whether available technology is sufficient to provide the required payload mass at comet rendezvous.

As mission knowledge evolves, the third case introduces multiple coast/thrust segments. These added degrees of freedom provide more flexible, and more realistic, mission solutions. The optimization method can be implicit or explicit (with master-subproblems), depending upon how many, and what level, of mission decisions need to be made. This would include interplanetary and close encounter geometries, flight times, subsystem performance, etc.

| | MISSION DURATION | PLANETARY BODIES | ACTIVITIES | SIMULATION | OPTIMIZATION |
|--|---------------------|-------------------------------------|--|---|---|
| | 5 years | Earth Jupiter Saturn | Launch, Midcourse ΔV, Gravity assist | E-J-S, 1 Step, 6 Phases | Minimize to total AV, 2 subproblems |
| | 4.2 years | Earth Venus Jupiter | Launch, Midcourse AV, Gravity assist, Probe | E-V-E-E-J, 1 Step, 9 Phases | Minimize total ∆V, 4 subproblems |
| | 4 days | Earth Moon (Sun) | Launch, Midcourse AV, Orbit insertion | E-M, 1 Step, 3 Phases | Maximize final mass, Master problem only |
| | 5 months | Earth Venus | Launch, Solar Power, Low Thrust, Orbit Insertion | E-V, 6 Phases | Maximize final mass, Collocation, 5 seg/phase |
| | 3 years | Earth Mars | Launch (E,M), Midcourse AV, Orbit Insertion | E-M-M-E, 1 Step,Conic, 6 Phases | Minimize initial mass, 3 subproblems |
| SATURN ORBITER WITH NUCLEAR PROPULSION | 4 years | Earth Saturn | Launch, Nuclear Power, Medium Thrust. Orbit Insertion | E-S, 1 Step, Encke, Cowell, 5 Phases | Maximize final mass, 2 subproblems |
| | 2.3 years | Earth Venus Comet Asteroid | Launch, Midcourse AV, Gravity Assist, Flyby, Rendezvous | E-V-A-C, 7 Phases | Minimize total AV, Collocation, 3 seg/phases |
| | | | | 7 | |

Table 2 - 1 IPOST SAMPLE CASES

The final case provides an end-to-end precision optimized reference trajectory for system analyses and subsystem design support. Science and mission objectives can be assessed with a high degree of confidence.

- Lunar Mission Thread
 - L1 Earth departure to lunar orbit with patched conic
 - L2 Space Station to moon with free return
 - L3 Space Station with finite burn escape to libration point
- Voyager II Thread
 - V1 EJS portion with ITOO (analytic partials)
 - V2 EJSUN with finite differences partials
- Comet Rendezvous with Solar Electric Propulsion Thread
 - C1 Approximate impulsive ΔV (DSM) with Venus gravity assist.
 - C2 Single thrust segment, simple collocation
 - C3 Multiple thrust segments, complex collocation
 - C4 Explicit optimization comparison
- Human Mission to Mars Thread
 - M1 EM launch/arrival date search, simple aerocapture
 - M2 MVE return leg optimization, Earth orbit capture
 - M3 Mars surface ascent to orbit (MAV design)
 - M4 EMMVE round-trip optimization

| | Bodies | Propagator(s) | Forces | Optimization method | | | | | | |
|-----------|--|--|------------|---|--|--|--|--|--|--|
| L1 | E-Moon | Conic | • | M | | | | | | |
| L2 | SS-Moon-E | 1-step | SB, J2 | M | | | | | | |
| L3 | E - L1 | Multiconic, Cowell | DB, HT | MS(2) | | | | | | |
| V1 | E-J-S | 1-step, Conic | SB | MS(3) + ITOO | | | | | | |
| V2 | E-J-S-U-N | 1-step | SB | MS(5) | | | | | | |
| C1 | E-V-C | 1-step, Conic | SB | MS(2) | | | | | | |
| C2 | E-C | nseg = 1 | DB, LT | collocation | | | | | | |
| C3 | E-C | nseg = 6 | DB, LT, SP | collocation | | | | | | |
| C4 | E-C | Encke | DB, LT, SP | M | | | | | | |
| M1 | E - M | 1-step | SB | Search | | | | | | |
| M2 | M-V-E | 1-step | SB | MS(2) | | | | | | |
| M3 | M | Cowell | HT, A | M | | | | | | |
| M4 | E-M-M-V-E | 1-step, Encke | SB, J2 | MS(3) | | | | | | |
| J2 = 2 | erodynamics] Jonal (J2) High thrust | LT = Low thrust SP = Solar pred SB = Secondary | ssure M = | Disturbing body Master only Master + Sub(s) | | | | | | |

Table 2 - 2. Example Mission Threads

3.0 SAMPLE CASES

The following sample cases illustrate detailed mission applications of IPOST. These are by no means intended to cover all capabilities nor are they realistic in every detail, but they do provide meaningful examples for constructing and understanding mission applications. There are 8 case discussions, four include both IPOST input and output, and the last four cases include only IPOST input.

The first sample case is a Voyager 2 mission which illustrates a Master-Subproblem formulation. The second sample case is a manned Mars mission that shows a complete round-trip. The third sample case is a Lunar mission which departs from Space Station Freedom and terminates with an insertion into lunar orbit. The fourth sample case illustrates optimization using collocation for an Earth-Jupiter mission.

The fifth case illustrates trajectory simulation with no targeting or optimization. The sixth case is a version of Voyager 2 with subproblem optimization. The seventh case shows a classic Hohmann transfer problem using finite thrust and collocation. The eighth case is a low thrust mission to Jupiter.

3.1 VOYAGER 2

The Voyager 2 case illustrates a master subproblem formulation and multiple planetary encounters. Only the Earth-Jupiter-Saturn phase of Voyager is performed. The simulation has 8 events, starting in Earth park orbit and ending with a Saturn flyby. Total impulsive delta V is minimized in the master problem. The two subproblems target each of two legs, Earth to Jupiter and Jupiter to Saturn.

In setting up an IPOST problem, the trajectory simulation is defined first, as opposed to the optimization process, because it describes the primary mission.

The first \$TRAJ namelist is event 5. This utilizes parameters such as S/C mass and propulsion characteristics. The initial date of July 31, 1977 precedes the actual Voyager launch date. The S/C is placed in a circular orbit about Earth, and trajectory propagation will use conic, or two-body, equations of motion.

The second event (#10) is triggered by a flight time of 20 days. The 1STEP propagator is activated in connection with activation of the LAUNCH mode. Hence, Voyager orbits the Earth for 20 days and then is impulsively injected onto an escape hyperbola. Using flight time as a control parameter would allow variation of initial launch date. For 1STEP, the primary body is the Sun and Earth is the secondary body.

The third event (#15) is initiated after a flight time of 20 days from the launch event. At this point, the S/C is well outside of the Earth's sphere of influence. The secondary body is now defined as Jupiter for 1STEP propagation. The reference body for trajectory calculations is also set to Jupiter.

At event 20, the triggering criteria is mission time. The intended value is Jupiter closest approach time which is not specified explicitly, but indirectly through the optimization process. A conic propagator is used with Jupiter as the primary body.

One day later, at event 23, an impulsive trajectory correction maneuver is executed. 1STEP is reactivated as the propagator as the vehicle flies away from Jupiter. The combination of gravity assist and midcourse correction will set up the trajectory for the flight towards Saturn.

The fifth event (#25) occurs 300 days after the midcourse maneuver. The secondary body for 1STEP is switched to Saturn, as is the reference body. A general rule of thumb is that planetary sphere's of influence for 1STEP (and Multiconic) are about 20 days for small inner planets (Mercury to Mars) and 200 days for large outer planets (Jupiter to Neptune).

The next event (#30) is Saturn's closest approach, on August 25, 1981. It occurs 1467 days after Earth park orbit escape.

A final event (#90) is used as a "dummy" event, and coincides with the previous event. This event is needed because final event computations are done only on the "minus" side of the event. The namelist specification of "NONE" means no more input follows; that is, this is the end of IPOST problem specification.

We now return to the optimization definition, or \$TOP namelist. The NPSOL algorithm is used with finite difference perturbations being calculated internally by NPSOL. This is the normal mode, as opposed to the user specifying perturbations. A maximum of 10 iterations is allowed for master problem optimization and 600 iterations for each subproblem targeting process. A subproblem targeting iteration is typically much shorter than a master problem iteration because the latter must solve all subproblems successfully.

The master problem controls are Jupiter closest approach time (defined as the criterion of event 20), B dot T and B dot R of the Jupiter approach, or incoming, hyperbola (defined as the 2nd and 3rd dependent variables of subproblem 1). In addition to the initial guesses for control values, the upper and lower bounds, and weighting values are important inputs. These define the performance manifold and often mean the difference between problem convergence and divergence. The objective function is the sum of all delta V magnitudes, which in this case corresponds to the launch/escape maneuver at Earth plus the Jupiter midcourse correction.

The two subproblems are defined next. The first subproblem ends at event 20 (Jupiter closest approach) and the second subproblem ends at event 30 (Saturn closest approach). IPOST automatically assumes that subproblems are non-overlapping. Both subproblems use a Newton-Raphson targeting technique, as opposed to subproblem optimization with NPSOL.

The control variables for subproblem 1 are the V-infinity vector of the Earth departure hyperbola. Controls for subproblem 2 are the ΔV components after Jupiter flyby. As in the master problem, important inputs are the control initial guesses (USUB), bounds (INDSLB and INDSUB), and weightings (WGTS).

The constraint or target variables for subproblem 1 are time from periapsis, B dot T and B dot R at Jupiter. For subproblem 2 the constraints are time from periapsis, B dot T and closest approach distance at Saturn. The use of B dot T as a control parameter (with loose bounds) at Saturn affects orbit inclination as well as which side of Saturn the S/C flies by. B dot T and B dot R are often used because of their stability in the targeting and optimization process. The choice of constraint parameters for subproblem 2 reflect termination of the mission at Saturn flyby. For the actual Voyager mission, which continues on to Uranus and Neptune, the constraint parameter types at Saturn would have been identical to those at Jupiter.

Because IPRINT was not input, the default value of IPRINT = 0 is used. This will result in only summary information of the master problem, plus the final trajectory, being output. Except for well tested production runs, it is recommended that more detailed levels of print be exercised.

The first page of output, after the Namelist echo, summarizes IPOST input, including initial conditions, event summary, targeting and optimization definition, master-subproblem structure, and NPSOL options.

The next page of output completes NPSOL parameter definition and then prints an iteration summary for each major (master level) iteration. This includes the objective function value (sum of delta V) and other conditions of the optimization process. Of some interest are the number of objective function evaluations (NFUN) and the condition number of the Jacobian (COND T). This problem does not have any nonlinear constraints, only control bounds, but if it did, the value of the nonlinear constraint norm is displayed, as well as the constraint values.

As the iterations progress, certain key parameters should be monitored. These are the objective function value (which should decrease), the condition numbers of the Hessian and Jacobian (which should remain small), and the value of the nonlinear constraint norm (which should decrease). Also of interest are the convergence indicators at the right side of the summary. When all these flags are "T", then successful optimization has been achieved (according to NPSOL). One cautionary note is that reliance on a few indicators, such as the convergence flags, can be misleading. It is important to examine all measures, including the final solution.

The iteration summary continues until page 4 of the output, where a maximum iteration limit has been reached (INFORM = 4). NPSOL is exited, and the final trajectory is displayed. Conditions at each event are output, including the minus and plus sides of each impulsive maneuver. At the end of each subproblem, a final iteration summary is displayed. In this case, Subproblem 1 convergence is summarized between trajectory blocks for event 15 and event 20 (Jupiter closest approach), and Subproblem 2 is summarized just before event 30 (Saturn closest approach).

The last solution has a total ΔV of 7.27 km/s, reduced from the initial solution of 7.67 km/s. Jupiter closest approach time is 711.9 days from launch, and B dot T, B dot R were selected as 1898747 km, 130453 km.

Finally, a master problem summary output is given which includes the number of iterations and CPU time. A valid solution may or may not meet all convergence criteria. Only the user, with adequate engineering experience, can make that judgment.

```
ipost - interplanetary post simulation. version 2.18 , dated 03-05-90.
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= 3*10, 3*23,

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= 720., 3.d7, 2.d6,
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" 20, 23,
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= 20.,
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# tdurp',
# 20.
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= 3,
= 'conic',
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event criteria data - 531b 345
general data - 224b 148
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= 'lstep',
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                                                                                      = 23,
= 'tdurp',
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= 'timrfl',
= 1487.,
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= 'tdurp',
= 300.,
= 0,6,
                                          = 'conic',
= 5,0,
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= 'tdurp',
= 0.,
= 'none',
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9.34871650060D+07
                                                                                                                                                                                                                                                                                                                                               master problem optimization parameter master problem optimization algorithm
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                                                                                      initial body and frame of reference initial state
                                                                                                            6.5630000000000+03
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                                                                                                                                                                                                                                                                                                                                   ***targeting/optimization inputs***
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-0.50000E-04
                                                                                                                                                                                           - metric, output units
                                                                              calendar date ... 1977 Jul 31,
                                                                                                                                                                              2.29812686681D+01
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OPTIONS file

BEGIN OPTIONS FOR NPSOL 4.0

VERIFY LEVEL
DERIV LEVEL
DERIV LEVEL
O
DIFFERENCE INTERVAL
MAJOR ITERATIONS LIMIT
30
MAJOR PRINT LEVEL
NONLINEAR FEASIBILITY TOLERANCE
HESSIAN
COLD START

₽

Calls to NPOPTN

major iteration limit = 30

NPSOL --- Version 4.05 Nov 1989

Parameters

| Linear constraints Variablesstep limit | 0 3 2.00E+00 | Linear feasibility 5.96E-08 Infinite bound size 1.00E+20 Infinite step size 1.00E+20 | 5.96E-08 1.00E+20 1.00E+20 | COLD startcrash tolerance |
|--|-------------------------|--|----------------------------------|---------------------------|
| Nonlinear constraints Nonlinear Jacobian vars Nonlinear objectiv vars EPS (machine precision) | 0 3 3 3.55E-15 | Optimality tolerance Nonlinear feasibility Linesearch tolerance Derivative level | 1.00E-06 3.00E-07 9.00E-01 | Function precision |
| Major iterations limit. Minor iterations limit. RUN loaded from file | 30 00 0 | Major print level Minor print level RUN to be saved on file | 20 0 0 | Save frequency |
| Difference interval 1.00E-04 | 1.00E-04 | Central diffce interval | 5.11E-05 | |
| Workspace provided is To solve problem we need | IW(| 2500), W(770500). 9), W(60). | | |

0

31

1.00E-02

9.90E-14

The user sets 0 out of 3 objective gradient elements. Each iteration, 3 gradient elements will be estimated numerically.

Nonlinear objective value = 7.672923E+00

Values of the constraints and their predicted status

0 1.000000E+00 0 1.000000E+00 7.080000E+01 Variables

0

2.8E+00 2.8E+00 2.E+02 2.E+02 0.E+00 T FT ۳ 0 0 8 7.308022E+00 1 1 3.7E-03 Major iteration

Nonlinear objective value = 7.308022E+00

Values of the constraints and their predicted status

0 1.000052E+00 0 1.040315E+00 Variables 7.079876E+01

3 2.9E-01 2.9E-01 4.E+02 4.E+02 0.E+00 T FT 0 10 7.304856E+00 0 2 1 2.3E-01 Major iteration

7.304856E+00 Nonlinear objective value =

Values of the constraints and their predicted status

0 0 9.825305E-01 7.081255E+01 0 1.039087E+00 Variables

| 302 |
|--|
| Nonlinear objective value $\approx 7.302548E+00$ |
| values of the Constraints and the Predicted Status |
| Variables 7.085144E+01 0 1.039036E+00 0 1.001594E+00 0 |
| |
| Major iteration 4 *==================================== |
| Nonlinear objective value = 7.297528E+00 |
| Values of the constraints and their predicted status |
| Variables 7.093058E+01 0 1.040861E+00 0 1.023273E+00 0 |
| |
| Major Iteration 5 ==================================== |
| Nonlinear objective value = $7.275443E+00$ |
| Values of the constraints and their predicted status |
| Variables 7.116154E+01 |

3 4.6E+00 4.6E+00 3.E+02 3.E+02 0.E+00 T FT

0

21 7.273502E+00 0

Major iteration 6

7.273502E+00

Nonlinear objective value =

| Values of the constraints and their predicted status |
|---|
| Variables 7.118782E+01 0 1.049873E+00 0 1.014660E+00 0 |
| |
| Major iteration 7 ==================================== |
| Nonlinear objective value = $7.271064E+00$ |
| Values of the constraints and their predicted status |
| Variables 7.119375E+01 O 1.050102E+00 O 1.009663E+00 O |
| |
| Major iteration 8 ==================================== |
| Nonlinear objective value = 7.270613E+00 |
| Values of the constraints and their predicted status |
| Variables 7.119852E+01 |
| |
| Major iteration 9 ==================================== |
| Nonlinear objective value = 7.270559E+00 |
| Values of the constraints and their predicted status |

| | 0 | |
|-----------|--------------|-------------|
| | 00 | 11 11 11 11 |
| | 1.007911E+00 | 11 |
| | 9100 | 11 11 |
| | - | 11 11 11 |
| | 0 | |
| | 1.049746E+00 | |
| | 0 | ## H H :: |
| Variables | 7.119208E+01 | |

| | 11 1 4.0E-01 33 7.269980E+00 0 0 3 3.0E+00 6.E•01 6.E+01 0.E+00 T FT C | | | |
|--------------------|--|--|--|---|
| | 6.E•01 | | | |
| | 3.0E+00 | | | |
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| | 0 | +00 | icte | 1.0 |
| | 00+ | 9980E | pred | 0 |
| | 7.269980E | Nonlinear objective value = 7.269980E+00 | Values of the constraints and their predicted status | riables 7.118672E+01 0 1.049732E+00 0 1.008100E+00 |
| | 33 | alue | ints | 1.04 |
| 11 | 11 | ve v | stra | 0 |
| tion | 4.0E-(| b ject i | he cor | 5+01 |
| era | : - | ıro | of ti | .s (672) |
| Major iteration 11 | 11 | Nonlinea | Values | Variables 7.1186 |

ပ 9.4E+00 9.4E+00 1.E+02 1.E+02 0.E+00 T FT Values of the constraints and their predicted status ~ 0 7.269251E+00 0 36 7.269251E+00 Nonlinear objective value = Major iteration 12

7.119253E+01 0 1.049898E+00 0 1.009001E+00 0 Variables

= 0.100000000E+07 =-0.368944343E-12 conic mean2000 = mean2000 = conic SCMASS = propid : propid epoch fpa = 0.656300000E+04 = 0.779323387E+01 = 0.000000000E+00 = 0.656300000E+04 = 0.184860000E+03 = 0.656300000E+04
= 0.779323387E+01 υ FJ 0.8064 1.050 1.009 = timili = ecliptic Residual ecliptic 0.E+00 T time H II 0.00000000E+00 0.0000000E+00 0.0000000E+00 radius speed radius speed 2.E+02 argp rperi altit Lagr multiplier critr frame critr frame = 0.000000000E+00 = 0.000000000E+00 = 0.000000000E+00 = 0.656300000E+04 = 0.000000000E+04 2.E+02 0.000000000 20.00000000 earth 0.000000000E+00 7.7E+00 NGRAD Upper bound earth 72.00000 16.58842 15.47173 n n H H 7.7E+00 11 11 tdurp tdurp idbody rapoap 23 0 z vz inc tfp 2 2 2 1.009167E+00 70.00000 0.0000000E+00 0.0000000E+00 constraints and their predicted status 11 = 0.000000000E+00 = 0.779323387E+01 = 0.88945237E-15 = 0.000000000E+00 = 0.184860000E+03 = 0.000000000E+00 m NEON improved upon. Julian =2443355.50000000 Lower bound =-0.287517165E+04 =-0.700558795E+01 =2443375.50000000 0 7.269194 7.269194E+00 14 0 = earth earth 0 7.269194E+00 II þ 6 MAJITS 1.049907E+00 Current point cannot Ħ 71.19363 1.049907 1.009167 julian secid Value eccen truan alta value secid earth earth ٧٧ S long > 11 final conditions for phase 41 = 0.656300000E+04 = 0.000000000E+00 = 0.18486000E+03 = 0.000000000E+00 Nonlinear objective value nonlinear objective state relative to idbody: x =-0.589969126E+04 38 = 7 31 1977 0.00 primid = earth timrfl = 0.000000000E+00 0.00 = 0.200000000E+02 INFORM 0.341412237E+01 State ***************** ም ም ም ም ም 0 = 8 20 1977 2.2E-01 Major iteration phase. 7.119363E+01 the = earth ī Exit NPSOL o Variables ΑP Variable Values primid timrf1 Final meaan VARBL VARBL VARBL altp SHA ×

| execution date and time F | Fri Oct | 23 | | | | | page 2 |
|---|------------------------------------|---|--------------------------------|--|----------------------------------|---|---|
| <pre>sma = 0.656300000E+04 meaan =-0.154018047E+03 altp = 0.184860000E+03 lat = 0.000000000E+00</pre> | eccen truan alta long | = 0.93848152E-15 =-0.154018047E+03 = 0.18486000E+03 =-0.114591559E+03 | inc típ rapoap longp | = 0.000000000E+00 =-0.262011247E-01 = 0.656300000E+04 = 0.000000000E+00 | argp rperi altit | = 0.000000000E+00 = 0.656300000E+04 = 0.184860000E+03 | anlong = 0.000000000E+00 vperi = 0.779323387E+01 period = 0.529132654E+04 |
| initial conditions for ph | phase 1 | O before launch | maneuver | | | | |
| = 8 20 1977 0.00 d = sun | julian secid | =2443375.50000000 = earth | tdurp idbody | = 20.00000000 = earth | critr frame | <pre>= timrfl = ecliptic</pre> | propid = 1step epoch = mean2000 |
| = 0.589969126E+04 = 0.341412237E+01 = 0.65630000E+04 n =-0.154018047E+03 | | =-0.287517165E+04 =-0.700558795E+01 = 0.977989025E-12 =-0.154018047E+03 | z vz inc tfp | = 0.000000000E+00 = 0.000000000E+00 = 0.000000000E+00 =-0.262011247E-01 | radius speed argp rperi | = 0.656300000E+04 = 0.779323387E+01 = 0.000000000E+00 = 0.656300000E+04 | scmass = 0.100000000E+07 fpa =-0.368944343E-12 anlong = 0.000000000E+00 vperi = 0.779323387E+01 |
| launch maneuver print k dvx = 0.000000000E+00 thrust = 0.20000000E+06 | block dvy spi | = 0.00000000E+00 = 0.48000000E+03 | dvz dmass | = 0.000000000E+00 = 0.786526125E+06 | dvmag ⊌prop | = 0.726903802E+01 = 0.213473875E+06 | tburn = 0.363451901E+05 |
| initial conditions for pha | se] | O after launch mai | maneuver | | | | |
| date = 8 20 1977 0.00 primid = sun timrf1 = 0.20000000E+02 | jullan secid | =2443375.50000000 = earth | tdurp idbody | = 0.00000000 = earth | critr frame | = timrfl = ecliptic | propid = 1step epoch = mean2000 |
| 9 # # # # | earth y vy eccen truan | =-0.363079018E+04 = 0.113982302E+02 = 0.273547253E+01 = 0.932129933E-10 | z vz inc tfp | =-0.860353840E+03 = 0.502743918E+01 = 0.210140784E+02 = 0.820447591E-14 | radius speed argp rperi | = 0.656300000E+04 = 0.150622719E+02 = 0.338557485E+03 = 0.656300000E+04 | scmass = 0.213473875E+06 fpa = 0.678730369E-10 anlong = 0.346214360E+03 vperi = 0.150622719E+02 |
| ming Asymptoc = 0.184860 = 0.962867 = 0.105403 | vinfm btheta ra | = 0.102665986E+02 = 0.146505405E+02 = 0.313596327E+02 | vinfx bdt dec | = 0.845879397E+01 = 0.931560777E+04 = 0.152334011E+02 | vinfy bdr altit | = 0.515509334E+01 = 0.243531091E+04 = 0.18486000E+03 | vinfz = 0.269756621E+01 hypta = 0.685574849E+02 |
| tping tping | vinfm btheta ra | = 0.102665986E+02 = 0.335159352E-10 = 0.477356494E+02 | vinfx bdt dec | = 0.228372219E+01 = 0.962867007E+04 = 0.210140784E+02 | vinfy bdr altit | = 0.930772076E+01 = 0.563241978E-08 = 0.184860000E+03 | vinfz = 0.368157486E+01 hypta = 0.000000000E+00 |
| state relative primary body: x = 0.12721712E+09 y vx = 0.241195310E+02 vy sma =-0.764065373E+09 ecc argp = 0.358595914E+03 anl | y y vy eccen anlong | =-0.820339672E+08 = 0.363332875E+02 = 0.119808406E+01 = 0.327199149E+03 | z vz inc meaan | =-0.436792502E+04 = 0.502764333E+01 = 0.657694804E+01 = 0.826427088E-01 | | | |
| final conditions for phase | se 10 | | | | | | |
| date = 9 9 1977 0.00 primid = sun timrfl = 0.400000000E+02 | | =2443395.50000000 = earth | tdurp idbody | = 20.00000000 = earth | critr frame | <pre>tdurp ecliptic</pre> | propid = 1step epoch = mean2000 |
| state relative to idbody: x = 0.37600157E+07 vx = 0.203173312E+01 sma = -0.43902809E+04 meaan = 0.23819227E+06 Incoming Asymptote altp = 0.9305843E+05 | earth y vy eccen truan vinfm | = 0.158739624E+08 = 0.882694248E+01 = 0.244520940E+02 = 0.920041723E+02 = 0.969696358E+01 | z vz inc tfp vinfx | = 0.624537138E+07 = 0.346898945E+01 = 0.209861894E+02 = 0.208244417E+02 = 0.279784107E+01 = 0.779784107E+01 | radius speed argp rperi | = 0.174678263E+08 = 0.969931652E+01 = 0.354658935E+03 = 0.994140853E+05 = 0.862309935E+01 | scmass = 0.213473875E+06 fpa = 0.896603749E+02 anlong = 0.350247545E+03 vperi = 0.101019848E+02 vinfz = 0.344170678E+01 by the s = 0.344170678E+01 |
| H | | | Í | • | į | ; | |

```
= 0.346814804E+01
= 0.000000000E+00
                                    vinfz
hypta
                                = 0.882480269E+01
= 0.207680044E+04
= 0.174614482E+08
             = 0.174614482E+08
                               vinfy
bdr
altit
           altit
                             = 0.203123344E+01
= 0.103545572E+06
= 0.209561280E+02
        0.207889236E+02
           H
                           vinfx
bdt
dec
        dec
                       vinfm = 0.969696358E+01
btheta = 0.114902014E+01
ra = 0.724091512E+02
    0.720238854E+02
      H
= 0.940311026E+02

# Asymptote

= 0.930359453E+05

= 0.103566397E+06

= 0.940311026E+02
c3 = (
Outgoing A
altp = (
bmag = (
c3 = (
```

| | | | | | | 90E+09 | 55E+02 | 67E+02 | 27E+09 | | 76E+02 | 82E+08 | 92E+09 | | 58E+02 | 96E+08 | 92E+09 | | | | | |
|------------------------------------|--|------------------------------|--------------------------------|---|------------------------|-------------------|-------------------|-------------------|----------------------|-----------------|---------------------|---------------------|-------------------|-----------------|-----------------------|--------------------------|-------------------|--------------------------------|-------------------|-------------------|-------------------|-------------------|
| | | | = tdurp | = ecliptic | | = 0.776871690E+09 | Ħ | = 0.601522267E+02 | = 0.450324327E+09 | | = 0.353394476E+02 | =-0.603414482E+08 | = 0.776800292E+09 | | = 0.353465658E+02 | =-0.603525296E+08 | = 0.776800292E+09 | | | | | |
| | | | critr | frame | | radius | speed | argp | rperi | | vinfy | bdr | altit | | vinfy | bdr | altit | | | | | |
| | = 0.624480435E+07 = 0.347024635E+01 = 0.546372471E+01 = 0.149709769E+01 | | ■ 0.00000000 | idbody = jupiter | | = 0.116229646E+08 | = 0.318606692E+01 | = 0.886012383E+01 | =-0.176328142E+03 | | = 0.216174356E+02 | = 0.446337319E+09 | = 0.439766997E+01 | | * 0.216060613E+02 | = 0.446335820E+09 | = 0.439516837E+01 | - 0 434400415E407 | - 0.62460433E+0/ | = 0.34/024635E+01 | = 0.5463/24/IE+01 | = 0.149709769E+Ul |
| | z vz inc meaan | | tdurp | idbody | | 2 | 7.7 | inc | tfp | | vinfx | bdt | dec | | vinfx | bdt | dec | | 7 | 2 . | 1nc | meaan |
| m. | =-0.192526118E+08 = 0.37689989EE+02 = 0.72268983E+00 = 0.327174715E+03 | | julian =2443395.50000000 | <pre># jupiter</pre> | | =-0.775239332E+09 | = 0.353434449E+02 | = 0.613754382E+04 | =-0.545779220E+02 | | = 0.415492509E+02 | =-0.769927828E+01 | = 0.585455258E+02 | | = 0.415492509E+02 | =-0.770070079E+01 | = 0.585506623E+02 | 0 1005361106100 | =-0.192320116E+U6 | = 0.376899896E+02 | = 0.722689833E+00 | = 0.327174715E+03 |
| ri Oct | dy: sun y vy eccen anlong | ase 15 | julian | secid | jupiter | | ^ | eccen | truan | | vinfm | btheta | ra | | vinfm | btheta | r.a | dy: sun | > | ٧٧ | eccen | anlong |
| execution date and time Fri Oct 23 | state relative primary body: sun x = 0.150285280E+09 y vx = 0.850190251E+01 vy sma = 0.540629909E+09 eccen argp = 0.122731869E+02 anlong | initial conditions for phase | $e_{\rm i} = 9 + 91977 + 0.00$ | primid = sun timrf1 = 0.40000000E+02 | te relative to idbody: | = 0.489745562E+08 | = 0.216184244E+02 | =-0.733840318E+05 | an =-0.494219226E+06 | oming Asymptote | D = 0.450252929E+09 | T = 0.450397705E+09 | = 0.172634025E+04 | going Asymptote | 5 = 0.450252929E + 09 | $\tau = 0.450397705E+09$ | = 0.172634025E+04 | ite relative primary body: sun | = 0.130283280E+09 | = 0.850190251E+01 | = 0.540629909E+09 | |
| exe | state x vx vx sma argp | init | date | prin tim | stat | × | × > | SER | meas | Ince | alti | pmac | c3 | Oute | 3 altr | bmac | C3 | state | × | × > | Sma | argp |

scmass = 0.213473875E+06 fpa =-0.545703154E+02 anlong = 0.268106570E+03 vperi = 0.415560211E+02

propid = 1step epoch = mean2000 = 0.318593345E+01 = 0.899906647E+02

vinfz hypta = 0.318412471E+01 = 0.000000000E+00

vinfz hypta

| final conditions for phase 15 | se 15 | | | | | | |
|--|---------------------------------------|---|-----------------|--|----------------|------------------------------------|------------------------------------|
| date = 7 12 1979 22.47 julian = 244 primid = sun | julian secid | =2444067.43630849 tdurp = jupiter idbody | tdurp 1dbody | tdurp = 671.93630849 1dbody = jupiter | critr frame | <pre>= timrfl = ecliptic</pre> | propid = 1step epoch = mean2000 |
| timrfl = 0.711936308E+03 | 41014 | | | | | | |
| x = 0.433346698E+06 | , , , , , , , , , , , , , , , , , , , | = 0.555192933E+06 | 2 | =-0.910720487E+05 | radius | radius = 0.710156794E+06 | scmass = 0.213473875E+06 |
| vx =-0.160812524E+02 | ν, | = 0.124780486E+02 | 2 ^ | =-0.428381733E+00 | speed | = 0.203590738E+02 | fpa =-0.800349572E-02 |
| sma =-0.219524281E+07 | eccen | = 0.132349806E+01 | inc | = 0.746726841E+01 | argp | = 0.260688481E+03 | anlong = $0.151430683E+03$ |
| meaan =-0.169603607E-02 | truan | =-0.140507246E-01 | tfp | =-0.990053290E-04 | rperi | = 0.710156782E+06 | vper1 = 0.203590739E+02 |
| Incoming Asymptote | | | | | | | |
| altp = 0.638758782E+06 | vinfm | • | vinfx | =-0.429597088E+00 | vinfy | = 0.753775941E+01 | |
| bmag = 0.190322247E+07 | btheta = 0 | | bdt | = 0.189874637E+07 | bdr | = 0.130453055E+06 | hypta = 0.409244977E+02 |
| | ra | = 0.932619112E+02 | qec | =-0.635421746E+01 | altit | = 0.638758794E+06 | |
| Outgoing Asymptote | | | | | | | |
| altp = 0.638758782E+06 | vinfm = 0 | • | vinfx | =-0.743241371E+01 | vinfy | =-0.143864811E+01 | 11 |
| | btheta = 0 | | bdt | = 0.189363550E+07 | bdr | = 0.190788873E+06 | hypta = $0.000000000E+00$ |
| | ra | =-0.106626238E+03 | dec | = 0.476825608E+01 | altit | = 0.638758794E+06 | |
| state relative primary body: sun | ody: sun | | | | | | |
| × =-0.590802760E+09 | · >- | 0 | 2 | = 0.109528856E+08 | | | |
| vx =-0.250125686E+02 | ^ | = 0.338743411E+01 | 2 ^ | =-0.190899988E+00 | | | |
| sma =-0.436025897E+09 | eccen = 0 | • | inc | = 0.206538027E+01 | | | |
| argp = 0.749073322E+02 | anlong = 0 | = 0.340181580E+03 | meaan | = 0.663792506E+02 | | | |

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| page 4 | .710156794E+06 scmass = 0.213473875E+06 .203590738E+02 fpa =-0.800349572E-02 .260688481E+03 anlong = 0.151430683E+03 .710156782E+06 vperi = 0.203590739E+02 | .753775941E+01 vinfz =-0.840759004E+00 .130453055E+06 hypta = 0.409244977E+02 .638758794E+06 | -0.143864811E+01 vinfz = 0.631477984E+00 0.190788873E+06 hypta = 0.000000000E+00 0.638758794E+06 | | | rp propid = conic tic epoch = mean2000 | 143478225E+07 scmass = 0.213473875E+06 153069144E+02 fpa = 0.488279481E+02 260688481E+03 anlong = 0.151430683E+03 710156782E+06 vper1 = 0.203590739E+02 | 775941E+01 vinfz =-0.840759004E+00 453055E+06 hypta = 0.409244977E+02 338425E+07 | 43864811E+01 vinfz = 0.631477984E+00 90788873E+06 hypta = 0.00000000E+00 36338425E+07 | | | rp propid = 1step tic epoch = mean2000 | 0.143478225E+07 scmass = 0.213473875E+06 0.153069144E+02 fpa = 0.488279481E+02 0.260688481E+03 anlong = 0.151430683E+03 0.710156782E+06 vper1 = 0.203590739E+02 | 155507307-0 |
|--------|--|--|--|---|----------------------------|---|--|--|---|--|----------------------------|---|--|--------------------------|
| | N 11 11 11 | 11 11 | # 11 # | | | r = tdurp e = ecliptio | | = 0.753 = 0.130 = 0.136 | = 0.1 | | | r = tdurp e = ecliptic | 11 V2 | # |
| | | vinfy bdr altit | vinfy bdr altit | | | critr frame | radiu speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | critr frame | radius speed argp rperi | 7 |
| | =-0.910720487E+05 =-0.428381733E+00 = 0.746726841E+01 =-0.990053290E-04 | =-0.429597088E+00 = 0.189874637E+07 =-0.635421746E+01 | =-0.743241371E+01 = 0.189363550E+07 = 0.476825608E+01 | = 0.109528856E+08 =-0.190899988E+00 = 0.206538027E+01 = 0.663792506E+02 | | = 1.00000000 = jupiter | =-0.508351063E+05 = 0.851749155E+00 = 0.746726841E+01 = 0.999900995E+00 | =-0.429597088E+00 = 0.189874637E+07 =-0.635421746E+01 | =-0.743241371E+01 = 0.189363550E+07 = 0.476825608E+01 | = 0.110136302E+08 = 0.108898104E+01 = 0.248596821E+01 = 0.485978921E+02 | | = 1.00000000 = jupiter | =-0.508351063E+05 = 0.851749155E+00 = 0.746726841E+01 = 0.999900995E+00 | 0 1467243515-03 |
| | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | tdurp idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | maneuver | tdurp 1dbody | z vz inc tfp | ; |
| 4 | Jupiter y = 0.55192933 vy = 0.124780486 eccen = 0.132349806 truan =-0.140507246 | vinfm = 0.759666021E+01 btheta = 0.393032065E+01 ra = 0.932619112E+02 | vinfm = 0 btheta = 0 ra =-0 | ~ > > o a | ie 20 | julian =2444068.43630849 secid = sun | <pre>jupiter y</pre> | vinfm = 0.759666021E+01 btheta = 0.393032065E+01 ra = 0.932619112E+02 | vinfm = btheta = ra | ry body: sun y = 0.535409868E+09 vy =-0.819466808E+01 eccen = 0.260368657E+01 anlong = 0.119411006E+03 | ase 23 before impuls | julia | Jupiter y = 0.100077151E+07 vy = 0.908046614E+00 eccen = 0.132349806E+01 truan = 0.834908744E+02 | lock |
| | in m m di | | Outgoing Asymptone altp = 0.638758782E+06 bmag = 0.190322247E+07 c3 = 0.577092463E+02 | =-0.590807760E+02 x =-0.250125686E+02 ma =-0.436025897E+09 rgp = 0.749073322E+02 | final conditions for phase | 25 | 2 " " " " | incoming Asymptote altp = 0.638758782E+06 bmag = 0.190322247E+07 c3 = 0.577092463E+02 | cgoing Asymptoice tp = 0.638758782E+06 ag = 0.19032247E+07 = 0.577092463E+02 | state relative to secondal x = 0.593034070E+09 vx = 0.241741362E+09 sma = 0.338523905E+09 argp = 0.338523905E+03 | initial conditions for pha | 2 | state relative to ideogy: x =-0.102687501E+07 vx =-0.152561988E+07 meaan = 0.171290593E+02 | impuls maneuver print bl |

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| ass = 0.213466820E+06 = 0.488281129E+02 ong = 0.151432351E+03 ri = 0.203591082E+02 | z =-0.840687472E+00 a = 0.409239162E+02 | z = 0.631382611E+00 a = 0.000000000E+00 | | | id = 1step h = mean2000 | ss = 0.213466820E+06 = 0.870742963E+02 ng = 0.325193209E+03 i = 0.977102314E+01 | z = 0.826847133E+00 a = 0.802372049E+02 | z = 0.618636011E+00 a = 0.000000000E+00 | | | ld = 1step n = mean2000 | ss = 0.213466820E+06 =-0.880253179E+02 ng = 0.102299021E+03 i = 0.119476806E+02 z = 0.552383113E+00 |
|---|--|---|---|----------------------------|---|--|---|---|--|------------------------------|---|--|
| scmas fpa anlon vperi | vinf hypt | vinfa | | | propic | scma fpa anlo | vinf hypt | vinf hypt | | | propic epoch | scmass fpa anlong vperi |
| = 0.143478225E+07 = 0.153068623E+02 = 0.260686214E+03 = 0.710150836E+06 | = 0.753767121E+01 = 0.130430044E+06 = 0.136338425E+07 | =-0.143863407E+01 = 0.190775284E+06 = 0.136338425E+07 | | | = tdurp = ecliptic | = 0.210937806E+09 = 0.830601351E+01 = 0.399346646E+02 = 0.915221005E+07 | =-0.344279315E+01 =-0.637349842E+06 = 0.210866408E+09 | =-0.758924362E+00 =-0.964954632E+06 = 0.210866408E+09 | | | <pre>= tdurp = ecliptic</pre> | = 0.454527721E+09 = 0.117468421E+02 = 0.292373562E+01 = 0.153987855E+08 |
| radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | critr frame | radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | critr frame | radius speed argp rperi |
| =-0.508351063E+05 = 0.851602431E+00 = 0.746650342E+01 = 0.999905525E+00 | =-0.42942880E+00 = 0.189876154E+07 =-0.635376275E+01 | =-0.743231726E+01 = 0.189365049E+07 = 0.476760027E+01 | = 0.110136302E+08 = 0.108883431E+01 = 0.248561659E+01 = 0.485974250E+02 | | = 300.00000000 = jupiter | = 0.167864915E+08 = 0.624257848E+00 = 0.173329246E+03 = 0.289154191E+03 | =-0.743318183E+01 =-0.108427236E+08 = 0.576370769E+01 | =-0.817496277E+01 =-0.108184903E+08 = 0.430912103E+01 | = 0.328818838E+08 = 0.770292069E+00 = 0.256989943E+01 = 0.719129706E+01 | | = 0.00000000 = saturn | =-0.213492406E+08 = 0.552717232E+00 = 0.269841380E+01 =-0.447017053E+03 =-0.113674760E+02 |
| z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | tdurp idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | t durp i dbody | z vz inc tfp vinfx |
| <pre>jupiter y</pre> | vinfm = 0,75965526E+01 btheta = 0.392959822E+01 ra = 0.932606748E+02 | 55 | y: sun y = 0.535409868E+09 y =-0.819464346E+01 eccen = 0.260367099E+01 anlong = 0.119408289E+03 | , 23 | julian =2444368.43630849 secid = jupiter | jupiter y ==0.301360930E+08 vy ==0.767464927E+00 eccen = 0.589728383E+01 truan = 0.968242418E+02 | vinfm = 0.823338891E+01 btheta =-0.176635948E+03 ra =-0.155148057E+03 | | y: sun y = 0.229413788E+09 y =-0.125491850E+02 eccen = 0.129348410E+01 anlong = 0.11969447E+03 | se 25 | julian =2444368.43630849 secid = saturn | saturn y = 0.126641919E+09 vy =-0.288227647E+01 eccen = 0.569607410E+02 truan =-0.890306541E+02 vinfm = 0.117397370E+02 |
| | Asymptote 0.638752836E+06 0.190323603E+07 | going Asymptote p = 0.638752836E+06 g = 0.190323603E+07 = 0.577076519E+02 | state relative primary body: | final conditions for phase | ate = 5 8 1980 22.47 rimid = sun | = 0.10129551E+04 elative to idbody: =-0.208098024E+09 =-0.824688791E+01 =-0.186883390E+07 = 0.630628788E+04 | ng Asymptoce = 0.908081205E+07 = 0.108614396E+08 = 0.677886930E+02 | Egoing Asymptote Lp = 0.908081205E+07 ag = 0.108614396E+08 = 0.677886930E+02 | state relative primary body: | initial conditions for phase | date = 5 8 1980 22.47 primid = sun timrf1 = 0.101293631E+04 | relative to idbody: = 0.436006288E+09 =-0.113743257E+02 =-0.275171223E+06 =-0.944095269E+05 ng Asymptote = 0.153387855E+08 |

| =-0.247182878E+05 hypta = 0.889940664E+02 = 0.454467721E+09 | = 0.551393273E+00 = 0.000000000E+00 |
|---|--|
| hypta | vinfz hypta |
| =-0.247182878E+05 = 0.454467721E+09 | =-0.327816061E+01 =-0.506185198E+05 = 0.454467721E+09 |
| bdr altit | vinfy bdr altit |
| = 0.156715216E+08 bdr =-0.247182878E+05 h = 0.269690121E+01 altit = 0.454467721E+09 | =-0.112592652E+02 = 0.156714593E+08 = 0.269206494E+01 |
| bdt dec | vinfx bdt dec |
| DMAG = 0.1350/15411E+08 btheta =-0.903710839E-01 bdt c3 = 0.137821425E+03 ra =-0.165781050E+03 dec Outgoing Asymptote | 55E+08 vinfm = 0.117397370E+02 vinfx =-0.112592652E+02 vinfy =-0.327816061E+01 vinfz = 0.551393273E+00 |
| omag = 0.136/13411E+08 c3 = 0.137821425E+03 Outgoing Asymptote | = 0.1533878 = 0.1567154 = 0.1378214 |
| omag c3 Outgo | altp bmag c3 |

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| | r se | | critr = tdurp |
|---|---|---|---|
| = 0.328118838E+08 = 0.770292069E+00 = 0.256989943E+01 = 0.719129706E+01 | = 474.06369151 c = saturn = 0.141744757E+06 r =-0.111465811E+02 s = 0.602120192E+02 a =-0.621887707E-04 r =-0.102574128E+02 v = 0.206142240E+06 b | = 0.275339599E+01 =-0.122575319E+01 = 0.372457905E+06 =-0.564389236E+02 = 0.610647598E+08 =-0.110387217E+02 = 0.332341103E+02 = 0.216645061E+03 | = 0.00000000 = saturn = 0.14174475E+06 =-0.111465811E+02 = 0.602120192E+02 =-0.621887707E-04 =-0.102574128E+02 = 0.206142240E+06 = 0.275339599E+01 =-0.122575319E+01 =-0.122575319E+01 =-0.122575319E+01 =-0.564389236E+06 = 0.372457905E+06 = 0.372457905E+06 = 0.372457905E+06 = 0.372457905E+06 = 0.372457905E+06 = 0.372457905E+06 = 0.372457905E+06 = 0.37247799E+08 |
| y: sun y = 0.229413788E+09 z vy =-0.125491850E+02 vz eccen = 0.129348410E+01 inc anlong = 0.119694447E+03 meaan | 44842.50000000 aturn .404454447E+05 .117929374E+02 .160733463E+01 .342173925E-01 .107305177E+02 | =-0.163139777E+0 ifm = 0.107305177E+0 ieta =-0.260199533E+0 sun =-0.150496956E+0 =-0.212817024E+0 :en = 0.570065114E+0 ong = 0.154617110E+0 | 130 |
| state relative primary body: x =-0.974184351E+09 y vx =-0.126002267E+02 vy sma =-0.256300375E+10 ec argp = 0.351055672E+03 ar final conditions for phase | te = 8 26 1981 0.00 Imid = sun mrf1 = 0.148700000E+04 ate relative to idbody: =-0.1352863E+06 =-0.151987656E+02 a =-0.329365722E+06 aan =-0.100297619E-01 coming Asymptote tp = 0.14467811E+06 aq = 0.414467811E+06 | = 0.115144010E+03 and Asymptote = 0.140035208E+06 = 0.414467811E+06 = 0.115144010E+03 = 0.115144010E+03 =-0.137454390E+02 =-0.137454390E+02 =-0.130483133E+09 = 0.130483133E+09 = 0.130483133E+09 | final conditions for phase date = 8 26 1981 0.00 juprimid = sun timefil = 0.148700000E+04 state relative to idbody: sax = -0.1352826E+06 y vx = -0.1352826E+06 y sma = -0.1352826E+06 y sma = -0.100297619E-01 tr Incoming Asymptote altp = 0.14467811E+06 bt c3 = 0.115144010E+03 rastate relative primary body: x = -0.137454390E+02 vy sma = -0.137454390E+02 vy sma = -0.137454390E+02 vy |

esn = 90.000 fesn= 90.000 time= 2.44484250D+06 normal termination cpu = 43.180 seconds

90.0 0.726919361E+01

dvsum

objective function name phase value

output ...

•*• npsol

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| | name | phase | variables value | residual | name | phase | constraints value | residual |
|-------|---------------------------|----------------------|---|--|------|-------|----------------------|----------|
| 3.2.1 | critr depsvl depsvl | 20.0 20.0 20.0 | 20.0 0.71193631E+03 20.0 0.18987465E+07 20.0 0.13045306E+06 | 0.00000000E+00 0.12067911-152 0.12067911-152 | | | | |
| | | | | | | | | |
| tot | al numbet | r of ite | number of iterations | = 14 | | | | |
| tot | al number | r of rel | oaded fn evals | = 12 | | | | |
| tot | total number | r of fun | nction evaluations | = 108 | | | | |
| tot | al cpu ti | # # | cpu time = 5434.930 seconds | | | | | |
| | | | | | | | | |

3.2 MANNED MARS

The manned Mars case is launched from Earth park orbit, performs a Venus gravity assist, orbits into a high elliptic Mars orbit, remains in orbit for two months, then launches back to Earth where the S/C inserts into an elliptical holding orbit. The simulation has 13 events with a total mission time of 610 days. This mission is a pure targeting case with no master controls, constraints, or objective function. All targeting is done on the subproblem level. Each subproblem is full rank (number of controls = number of constraints).

To understand this case we begin with the simulation, or first \$TRAJ input. At event 5, the initial conditions are specified, such as a S/C mass of 10000000 kg and an initial circular park orbit of 6878 radius.

The next event (#10) performs an impulsive launch maneuver, .5 days later, to insert the S/C on an Earth escape hyperbola. The 1STEP propagator is activated to account for 3 body motion (Earth-Sun-S/C). The S/C will leave Earth and begin its journey toward Mars, via Venus.

At event 20, 40 days after park orbit escape, the secondary body for 1STEP is changed to Venus (from Earth). The reference body (IDBODY) for target calculations is also switched to Venus.

Events 25 and 30 are simultaneous, but contiguous events. Event 25 is triggered by a mission flight time of 190 days. This is intended to correspond to Venus closest approach. Event 30 performs an impulsive midcourse correction.

At event 35, 40 days after Venus closest approach, the secondary body and reference body are changed to Mars.

Event 40 and 45 are simultaneous contiguous events. Event 40 corresponds to Mars closest approach, 350 days after Earth escape. Event 45 performs an impulsive orbit insertion into a highly elliptical Mars orbit whose inclination is the same as the approach hyperbola. The propagator is switched to a simple conic. At this point subsequent events could have simulated a Mars surface descent and subsequent ascent. However, for test case simplicity, only the 60 day orbital phase is simulated.

At event 50, after a two month stay in orbit, the S/C is inserted into an escape trajectory towards Earth. The 1STEP propagator is reactivated with Mars as the secondary body (and the Sun as primary). After 40 days, event 60 switches the secondary body and target reference body to Earth.

The final 3 events (#65, #70, #75) are all simultaneous contiguous events. Event 65 corresponds to Earth closest approach after a total mission time of 610 days. Event 70 performs an impulsive orbit insertion into a highly elliptical holding orbit about Earth. The orbit might be typical of a staging orbit which transfers crew and material to and from the low Earth Space Station orbit. Event 75 exists to allow conditions after the orbit insertion (before event 75) to be used as output values.

We now return to the optimization formulation, or \$TOP. No optimization algorithm was selected and only subproblem targeting will be done. Forward differences are specified for the finite differencing construction of the Jacobian. The maximum subproblem targeting iterations is 300.

The 3 subproblems all use the Newton-Raphson targeting algorithm. The subproblems correspond to Earth-Venus, Venus-Mars, Mars-Earth legs. The first subproblem varies escape V-infinity to achieve desired B dot T, B dot R, TFP at Venus closest approach. The second subproblem varies Venus midcourse delta V to achieve desired closest approach distance, time, and B dot T at Mars. The third subproblem varies Mars escape V-infinity to achieve desired closest approach distance, time, and B dot T at Earth return.

The output for this case is straightforward.

The final trajectory is displayed, corresponding to each event in the specified simulation input, along with the subproblem summary output (achieved by setting ISUB (i) = 1 in \$TOP). Of particular note are the conditions before and after each maneuver. The final S/C mass at Earth return is 70404 kg, reduced from an initial mass of 1 million kg in Earth park orbit.

```
1,1,2,2,2,3,3,3,
'vinfxo','vinfyo','vinfzo','dvx','dvy','dvz',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfyo','vinfzo',
'vinfxo','vinfxo','vinfzo',
'vinfxo','vinfxo','vinfzo','dvx','dvx','dvz',
'vinfxo','vinfxo','vinfzo','dvx','dvx','dvz',
'vinfxo','vinfxo','vinfzo','dvx','dvx','dvz','
'vinfxo','vinfxo','vinfzo','dvx','dvx','dvz','
'vinfxo','vinfxo','vinfzo','dvx','dvx','dvz','
'vinfxo','vinfxo','vinfzo','dvx','dvx','dvz','
'vinfxo','vinfxo','vinfzo','vinfzo','dvx','dvx','dvx','dvz','
'vinfxo','vinfxo','vinfzo','vinfzo','
'vinfxo','vinfxo','vinfzo','vinfzo','
'vinfxo','vinfxo','vinfzo','vinfzo','
'vinfxo','vinfxo','vinfxo','vinfzo','
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i p o s t - interplanetary post simulation. version 2.18 , dated 03-05-90. \rho \$ t \, op
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      1,1,1,2,2,2,3,3,3, 'rperi','tfp',
'bdti','bdri','tfp','bdti',
25,25,40,40,40,65,65,65,
= 9789.20,-810.461,0.3880.0.,5190.08,6878.0.,16882.4,
= 10000.,-600.,-001,4000.,-001,5500.,7000.,-001,17000.,
= 9820.,-820.,-001,3850.,-001,5150.,6850.,-001,16400.,
- 9020.,-800.,-001,3900.,-001,5150.,6900.,-001,17000.,
                                                                                                         earth-mars roundtrip mission via venus flyby on out-bound leg. initial inputs from iprep
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      " nraph', 'nraph', 'nraph',
" 25, 40, 65,
" 1.40,
" 1.40,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  ipbody = 3,0,
idfram = 'ecliptic','mean2000',
teboch = 'julian',
                                                                                                                                                                                                                                                                                                                    'forward'
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c
c ini(
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pštraj
c exited venus soi, change secondary body, input body
c
                                                                                                                                                pŝtraj
c exited earth soi, change secondary, input body
c
                                                                                                                                                                                                                                                              p$traj
c on the way to mars, do impulse correction
c
               thrust = 2.d5,
inputx = 'conic',
x = 6878.,0.,0.,0.,0.,0.,
                                                                                                                                                                                                             p$traj
c venus closest approach
c
                                                                                             -1.,
480.,
6878.,
- 6878.,
                                                                                                                                                                                                                                                                                                                                                                                               p$traj
c mars closest approach
c
                                                         = 10,
= 'timrf1',
= .5,
= 'launch',
                                                                                                                                                                                                                                                                                           = 30,
= 5htdurp,
= 0.0d0,
= 'impuls',
= 0., 0.,0.,
                                                                                                                                                                                                                                         = 25,
= 6htimrf1,
= 168.,
                                                                                                                                                                                                                                                                                         event
critr
value
mantyp
dvx
                                                          event
critr
value
mantyp
inch
inc
spi
rperi
rapoap
iprop
iprop
                                                                                                                                                                          event
critr
value
ipbody
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critr
value
ipbody
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p$traj
c exited mars soi, change secondary, input body
c
                                                                                                  pštraj
c depart mars 60 days after arrival
c
                                                                                                                                                                                                                                        p$traj
c earth closest approach
c
                                                                                                                                     60.,
1 launch',
1 36327.,
1 3880.,
1 1step',
= 40,
= 6htimrf1,
= 323.,
                                           45,
5htdurp,
0.
0.orbins',
36327.,
3880.,
-1.
                                                                                                                                                                                                                                                                                                          70,
5htdurp,
0.d0,
78036,
6878.
                                                                                                                         = 50,
= 5htdurp,
                                                                                                                                                                                                                                                                 = 65,
= 6htimrf1,
= 583.,
event = 40,
critr = 6htimrf.
value = 323.,
$
p$traj
c orbit insertion
                                                                                                                                                                                                                                                                                   p$traj
c orbit insertion
c
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critr
value
mantyp
rapoap
rperi
inc
$
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critr
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critr
value
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rapoap
rperi
inc
ipc
iprop
                                                                                                                                                                                                                                                                event
critr
value
```

c final event for print out
c event = 75,
critr = 5htdurp,
value = 0.d0,
namist = 'none',

*** core requirements for problem 1 are ***

Parameter octal decimal event criteria data - 332b 218

table data - 34b 28

```
propagator
                                                                                 -3.84577196748D+03
                                                                                                                                                                            listed
listed
listed
listed
confc
confc
listed
listed
listed
                                                                  , ecliptic, mean2000
                                                         hr 0 min 0.0000 secs
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0.10000E-03
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0.10000E+01
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launch
none
none
orbins
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impuls
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                                                                                vinfzo
10
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                                                                                                                          1.26559269107D+08
2.28755234840D+01
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0.97892E+04 -0.81046E+03
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0.10000E-03
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                                                                                                                                                                                                                                                                                                       master problem optimization algorithm
                                                                                                                                                                                                                                                                                                                                               master problem target/dep parameters
                                                                                                                                                                                                                                                                                                                       master prob. control/indep parameters
                                                         calendar date ...2010 nov 21, initial body and frame of reference
                                                                                                                                                                                                                                                                                              ***targeting/optimization inputs***
                                                                                                                                                                                                                                                                                                                                                                                                                                                                            0.38800E+04
0.10000E+01
                                                                                                                                             metric, output units
execution date and time Fri Oct
                                        initial epoch
julian date ...2455522.0000
                                                                                                                                                                                                                                                                                                                                                                 total number of subproblems is
                                                                                                                                                                                                                                                                                                                                                                                        10
                                                                                                                                                                                                                                                                                                                                                                                 vinfxo
                                                                                                                                                                                                                                                                                                                                                                                                                                                             rperi
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timrf1
                                *** trajectory inputs ***
               **** ipost input summary
                                                                                                                                                                                                                                                                                                                                                          name
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                                                                                                                                                                                                                                                                                                                                                                                 subproblem controls
                                                                                                                                                                                                                                                                                                                                                                                                            at events
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                                                                                                                                                                                                                                                                                                                                                                                                                                             subproblem controls
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                                                                                                                                                                                                                                                                                                                                                                                                  subproblem targets
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                                                                                                                   initial state,
                                                                          initial state
                                                                                   cartesian
                                                                                                                                                    event summary
                                                                                                                                            units
                                                                                                                                                                   5.000
25.000
33.000
34.000
44.000
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60.000
65.000
                                                                                                   conic
                                                                                                                                                             number
```

| | propid = conic epoch = mean2000 | scmass = 0.100000000E+07 fpa =-0.38166552E-12 anlong = 0.000000000E+00 vper1 = 0.76126840E+01 period = 0.567680811E+04 |
|--|---|--|
| | * time * ecliptic | radius = 0.687800000E+04 speed = 0.761268440E+01 argp = 0.0000000000E+00 rperi = 0.687800000E+04 altit = 0.499860000E+03 |
| | critr frame | radius speed argp rperi altit |
| 1.5 | tdurp = 0.0000000 critr = time idbody = earth frame = eclipti | - 0.000000000E+00 - 0.0000000000E+00 - 0.0000000000E+00 - 0.68780000E+04 - 0.0000000000E+04 - 0.576965101E-03 - 0.193959703E-02 |
| vinfzo 50 bdti 0.16882E+05 0.10000E+01 | tdurp idbody | z vz inc tfp rapoap longp z vz inc meaan |
| vinfyo tfp 65 30E+04 0.00000E+00 | <pre>date =11 21 2010 12.00 julian =2455522.0000000 tdurp = primid = earth</pre> | y = 0.0000000000000000000000000000000000 |
| 3 vinfxo 50 rperi 65 0.6878 | 2.00 J | 24-04-04-04-04-04-04-04-04-04-04-04-04-04 |
| subproblem number 3 subproblem controls at event subproblem targets at events subproblem values with tolerance | <pre>date =11 21 2010 12.00 julian primid = earth timrfl = 0.0000000000E+00 state relative to idbody: earth</pre> | x = 0.68780000E+04 y = 0.0000000E+04 y = 0.00000000E+04 y = 0.00000000E+04 eccen = 0.000000000E+04 eccen = 0.000000000E+03 alta = 0.000000000E+03 alta = 0.000000000E+03 long = 0.763136841E+08 y = 0.253845882E+02 vy = 0.253110443E+09 eccen = 0.27105943E+03 anlong = 0.271059443E+03 anlong = 0.271059443E+03 anlong = 0.271059443E+03 anlong = 0.271059444444444444444444444444444444444444 |

execution date and time Fri Oct 23

final conditions for phase 5

| propid = conic epoch = mean2000 scmass = 0.100000000E+07 fpa =-0.35622124E-12 anlong = 0.00000000E+00 vperi = 0.761268440E+01 period = 0.567680811E+04 | propid = 1step epoch = mean2000 scmass = 0.100000000E+07 fpa =-0.356222124E-12 anlong = 0.00000000E+00 vperi = 0.761268440E+01 tburn = 0.222640080E+05 | propid = 1step epoch = mean2000 scmass = 0.388307751E+06 fpa = -0.94907517E-11 anlong = 0.24913596E+03 vperi = 0.120654860E+02 vinfz = 0.189439804E+00 hypta = 0.485940357E+02 vinfz = 0.151398411E+01 hypta = 0.000000000E+00 |
|--|---|--|
| <pre>timrfl = ecliptic s = 0.687800000E+04 = 0.761268440E+01 = 0.000000000E+00 = 0.499860000E+03</pre> | = timrfl = ecliptic s = 0.68780000E+04 = 0.761268440E+01 = 0.00000000E+00 = 0.687800000E+04 = 0.445280160E+04 = 0.388307751E+06 | = timrf1 = ecliptic = 0.687800000E+04 = 0.120654860E+02 = 0.318594036E+03 = 0.687800000E+04 = 0.687801470E+01 = 0.420384317E+04 = 0.49986000E+03 = 0.49986000E+03 |
| critr frame radiu speed argp rperi altit | critr frame radius speed argp rperi dvmag | critr frame radiu speed argp argp vinfy bdr altit altit |
| - earth - 0.00000000000000000000000000000000000 | - earth - 0.000000000E+00 - 0.000000000E+00 - 0.00000000E+00 0.256303804E-01 - 0.00000000E+00 | - earth 0.126439311E+04 -0.251531798E+01 -0.161377276E+02 -0.13179715E+01 -0.131297115E+01 -0.146437321E+05 -0.199306976E+01 -0.199306976E+01 -0.152351957E+05 -0.161377276E+02 -0.161377276E+02 -0.508353695E+04 -0.508353695E+04 -0.251597190E+01 -0.709169299E+01 |
| tdurp idbody z vz vz tinc tapoap longp inc meaan | tdurp tdurp idbody z vz inc tfp dvz dwz | maneuver 1 tdbody 2 vz 1 inc 1 tfp 1 vinfx 2 bdt 2 bdt 3 dec 1 vinfx 0 bdt 0 bdt 1 vz 1 vz 1 vz 0 meaan |
| an =245522.50000000 d = sun h ==0.438121172E+04 ==0.38481077E+01 n = 0.347400286E-15 n ==0.146432324E+03 ==0.146432324E+03 ==0.14632324E+03 ==0.14591559E+03 dy: sun ==0.17209403E+09 ==0.917019882E+01 n ==0.418966590E+03 ng ==0.105179580E+03 | 10 before launch = 245552.50000000 = earth =-0.438121172E+04 =-0.586841077E+01 = 0.683258405E-12 =-0.140432324E+03 = 0.00000000E+00 = 0.480000000E+00 | 10 after launch n = 245552.500000 = earth =-0.326417341E+0 =-0.15528008E+0 =-0.15196734E+0 =-0.1519196734E+0 =-0.1519196734E+0 =-0.1519196734E+0 =-0.1519196734E+0 =-0.544701982E+0 =-0.544701982E+0 =-0.179009054E-1 =-0.17210520E+0 =-0.17210520E+0 =-0.17210520E+0 =-0.17210520E+0 =-0.17210520E+0 =-0.17210520E+0 =-0.17210520E+0 =-0.17210520E+0 |
| juli seci eart y vy ecce trua alta alta long ry bo vy vy vy vy vy vy vy vy ecce trua alta alta alta alta alta alta vy vy vy vy vy vy vy vy vy vy vy vy vy | secid secid y y y y vy eccen truan block dvy | ase juli juli yy yy yy yy yy yy |
| date = 11 22 2010 0.00 juli primid = earth seci- state relative to idbody: earth seci- x = 0.484919775E+01 y vx = 0.687800000E+04 ecce- meaan = 0.687800000E+04 ecce- meaan = 0.68780000E+04 ecce- meaan = 0.69780000E+03 alth secient s | initial conditions for phase date = 11 22 2010 0.00 juprimid = sun state relative to idbody: eax x = -0.530206260E+04 y vx = 0.484919775E+01 vy sma = 0.687800000E+04 ecq meaan =-0.140432324E+03 trilaunch maneuver print blockdvx = 0.200000000E+00 dyy | initial conditions for phase date =11 22 2010 0.00 jull primid = sun section in the state =11 22 2010 0.00 jull primid = sun state relative to idbody: ear x =-0.592058832E+04 y vx =-0.592058832E+04 y vx =-0.592058832E+01 vy sma = 0.499860000E+01 tru Incoming Asymptote = 0.49986000E+03 vin bmay = 0.152351957E+05 bth collection in the state relative primary body: x = 0.296700250E+02 raste relative primary body: x = 0.29670250E+02 raste relative primary body: x = 0.298333316E+08 y sma = 0.993630316E+08 eccaargp = 0.164108951E+03 anlary |

Oct

Fri

time

Pue

date

| meaan =-0.168050387E+01 truan ~-0.811720352E+00 tfp Incoming Asymptote | truan | =-0.811720352E+00 | tfp | 0.852656040E-04 | rperi | = 0.745953352E+04 | =-0.852656040E-04 rperi = 0.745953352E+04 vperi = 0.143459980E+02 | 0.5 |
|--|-----------------------|---|---------------------|--|-----------------------|---|---|-----|
| altp = 0.140753352E+04 vinfm = 0.108953526E+02 vinfx = 0.100969617E+02 vinfy =-0.409384683E+01 vinfz =-0.221602862E-01 bmag = 0.9882202753E+04 btmeta =-0.473303294E+01 bdt = 0.978853423E+04 bdr =-0.810445840E+03 hypta = 0.744311480E+02 c3 = 0.118708708E+03 ra =-0.220702583E+02 dec =-0.116535168E+00 altit = 0.140612375E+04 outgoing Asymptote | vinfm btheta ra | = 0.108953526E+02 =-0.473303294E+01 =-0.220702583E+02 | vinfx bdt dec | <pre>= 0.100969617E+02 = 0.978853423E+04 =-0.116535168E+00</pre> | vinfy bdr altit | =-0.409384683E+01 =-0.810445840E+03 = 0.140612375E+04 | vinfz =-0.221602862E hypta = 0.744311480E | 01 |

| execution date and time Fri | Oct | 23 | | | | | | page 4 |
|--|---|--|-------------------------|--|----------------------------------|--|---------------------------------|--|
| altp = 0.140753352E+04 bmag = 0.982202753E+04 c3 = 0.118708708E+03 | vinfm btheta ra | = 0.108953526E+02 =-0.399342539E+01 = 0.955508898E+01 | vinfx bdt dec | - 0.107510861E+02 - 0.979818012E+04 0.254523061E+01 | vinfy bdr altit | = 0.169963345E+01 =-0.684025682E+03 = 0.140812375E+04 | vinfz =- hypta = | 0.483841312E+00 0.000000000E+00 |
| x = 0.103560979E+09 y vx = 0.246445190E+02 y sma = 0.158796701E+09 ecc argp = 0.208467739E+03 anl | y vy eccen anlong | 0.328492345E+08 - 0.315505174E+02 - 0.456578464E+00 - 0.637486442E+02 | z vz inc meaan | 0.642620342E+07 0.487464857E+00 - 0.342386879E+01 - 0.274846183E+02 | | | | |
| initial conditions for phase | 8 | 2 | | | | | | |
| subproblem iteration 20 | final | icnvgd = 1 | | | | | | |
| subp. ind. vars. 4.88927835E | 1835E+0(| 1 +00-1.86355420E+00 1.5 | 51398411E | 3 E+00 | | | | |
| subp. dep. vars. 9.78853 6.65774 subproblem number 2 | 1 .78853423E+03-8 .65774332E-01-1 | 2 .10445840E+02-8. .51598210E-02 8. | 52656040 | 0E-05 0E-05 | | | | |
| initial conditions for phase | 7 | 2 | | | | | | |
| final conditions for phase | - 25 | | | | | | | |
| = 5 8 2011 12.00 d = sun 1 = 0.168000000E+03 | julian | =2455690.00000000 = venus | tdurp 1dbody | . 0.00000000 | critr frame | <pre>tdurb ecliptic</pre> | propid = epoch = | 1step mean2000 |
| | venus y vy eccen truan | 0.737709393E+04 0.167884287E+01 0.372583555E+01 0.811720352E+00 | z vz inc tfp | = 0.591387009E+03 =-0.342414513E+00 = 0.473446410E+01 =-0.852656040E-04 | radius speed argp rperi | = 0.746012375E+04 = 0.143457578E+02 = 0.106980891E+03 = 0.745953352E+04 | fpa = | 0.388307751E+06 -0.639960672E+00 0.156522518E+03 0.143459980E+02 |
| Incoming Asymptote altp = 0.140753352E+04 bmag = 0.982202753E+04 c3 = 0.118708708E+03 | vinfm btheta ra | = 0.108953526E+02 =-0.473303294E+01 =-0.220702583E+02 | vinfx bdt dec | = 0.100969617E+02 = 0.978853423E+04 =-0.116535168E+00 | vinfy bdr altit | 0.409384683E+01 0.810445840E+03 0.140812375E+04 | vinfz = hypta = | 0.221602862E-01 - 0.744311480E+02 |
| oing Asymptote = 0.140753352E+04 = 0.982202753E+04 = 0.118708708E+03 | vinfm btheta ra | = 0.108953526E+02 =-0.399342539E+01 = 0.955508898E+01 | vinfx bdt dec | = 0.107510861E+02 = 0.979818012E+04 =-0.254523061E+01 | vinfy bdr altit | = 0.169963345E+01 =-0.684025682E+03 = 0.140812375E+04 | vinfz =- hypta = | -0.483841312E+00 0.000000000E+00 |
| state relative primary box x = 0.103560979E+09 vx = 0.246445190E+02 sma = 0.158796701E+09 argp = 0.208467739E+03 | ody: sun y vy eccen anlong | 0.328492345E+08 -0.315505174E+02 -0.456578464E+00 | z vz inc meaan | =-0.642620342E+07 =-0.487464857E+00 = 0.342386879E+01 = 0.274846183E+02 | | | | |
| initial conditions for phase | ase 30 | before impuls | maneuver | | | | | |
| 7 | julian secid | =2455690.00000000 = venus | tdurp idbody | = 0.00000000 = venus | critr frame | <pre>= tdurp = ecliptic</pre> | propid = | 1step mean2000 |
| state relative to idbody: x =-0.939251327E+03 vx = 0.142430687E+02 sma =-0.273660439E+04 meaan =-0.168050387E+01 | venus y vy eccen truan | =-0.737709393E+04 =-0.167884287E+01 = 0.372583555E+01 =-0.811720352E+00 | z vz inc tfp | = 0.591387009E+03 =-0.342414513E+00 = 0.473446410E+01 =-0.852656040E-04 | radius speed argp rperi | = 0.746012375E+04 = 0.143457578E+02 = 0.106980891E+03 = 0.745953352E+04 | scmass = fpa = anlong = vperi = | = 0.388307751E+06 =-0.639960672E+00 = 0.156522518E+03 = 0.143459980E+02 |
| | | | | | | | | |

| =-0.518018869E-02 dvmag = 0.157742921E-01 tburn = 0.306263995E+02 = 0.129908194E+04 wprop = 0.387008669E+06 | | propid = 1step epoch * mean2000 | = 0.591387009E+03 radius = 0.746012375E+04 scmass = 0.387008669E+06 =-0.347594702E+00 speed = 0.143417541E+02 fma ==0.529478E1E+00 |
|--|---|--|---|
| = 0.157742921E-01 | | 0.00000000 critr = tdurp is frame = ecliptic | s = 0.746012375E+04 = 0.143417531E+02 |
| dvmag Wprop | | critr | radiu speed |
| =-0.518018869E-02 = 0.129908194E+04 | | = 0.00000000 | = 0.591387009E+03 =-0.347594702E+00 |
| dvz dmass | euver | tdurp idbody | 2 2 2 2 |
| =-0.302675298E-02 dvz = 0.480000000E+03 dmass = | 30 after impuls man | an =2455690.00000000 d = venus | =-0.737709393E+04 z =-0.168186962E+01 vz |
| block dvy spi | hase | juli seci | : venu y |
| <pre>impuls maneuver print block dvx ==0.14587869E-01 dvy thrust = 0.200000000E+06 spi</pre> | initial conditions for phase 30 after impuls maneuver | date = 5 8 2011 12.00 julian =2455690.0000000 tdurp = 0 primid = sun secid = venus idbody = venus timrfl = 0.168000000E+03 | <pre>state relative to idbody: venus x =-0.939251327E+03 y vx = 0.142284799E+02 vy</pre> |

| execution date and time F | Fr1 Oct | 23 | | | | | page 5 |
|---|--|--|-------------------------|--|----------------------------------|---|--|
| | eccen | = 0.371662461E+01 =-0.790517914E+00 | inc tfp | = 0.474105451E+01 =-0.831197619E-04 | argp rperi | = 0.107231532E+03 = 0.745956425E+04 | anlong = 0.156249743E+03 vperi = 0.143319810E+02 |
| | vinfm btheta | = 0.108769062E+02 =-0.473916092E+01 =-0.221326942E+02 | vinfx bdt dec | - 0.100754007E+02 - 0.979550811E+04 0.134136753E+00 | vinfy bdr altit | 0.409789471E+01 0.812078101E+03 - 0.140812375E+04 | vinfz =-0.254642063E-01 hypta = 0.743915812E+02 |
| o i i o . | vin bth | = 0.108769062E+02 =-0.398605354E+01 = 0.957644254E+01 | vinfx bdt dec | - 0.107321883E+02 - 0.980533575E+04 0.256897396E+01 | vinfy bdr altit | = 0.169986571E+01 =-0.683257506E+03 = 0.140812375E+04 | vinfz =-0.487525043E+00 hypta = 0.000000000E+00 |
| state relative primary body: x = 0.103560979E+09 y vx = 0.246299302E+02 vy sma = 0.158624976E+09 ecc argp = 0.208286225E+03 anl | y y vy eccen anlong | =-0.328492345E+08 = 0.315474907E+02 = 0.455979490E+00 = 0.638971570E+02 | z vz inc meaan | 0.642620342E+07 0.492645046E+00 0.342253349E+01 0.275486293E+02 | | | |
| final conditions for phase | ie 30 | | | | | | |
| id = sun f1 = 0.208000000E+03 | | =2455730.00000000 | tdurp 1dbody | = 40.00000000 | critr frame | <pre>tdurp ecliptic</pre> | propid = 1step epoch = mean2000 |
| | y vy eccen truan | = 0.903579853E+07 = 0.667951334E+01 = 0.957736372E+04 = 0.816689582E+02 | z vz inc tfp | 0.237216236E+07 0.965469220E+00 0.273625023E+01 0.275138972E+02 | radius speed argp rperi | = 0.498487764E+08 = 0.207477282E+02 = 0.192893179E+03 = 0.722715348E+07 | scmass = 0.387008669E+06 fpa = 0.816630390E+02 anlong = 0.958880603E+02 vperi = 0.207495805E+02 |
| Incoming Asymptote altp = 0.722110148E+07 bmag = 0.722790812E+07 c3 = 0.430455193E+03 | vinfm btheta ra | = 0.207474141E+02 = 0.610713378E+00 = 0.187894745E+02 | vinfx bdt dec | = 0.196204726E+02 = 0.722749753E+07 =-0.266727651E+01 | vinfy bdr altit | 0.667533188E+010.770405191E+050.498427244E+08 | vinfz =-0.965500511E+00 hypta = 0.899940176E+02 |
| oing Asymptone = 0.722110148E+07 = 0.722790812E+07 = 0.430455193E+03 | vin bth | = 0.207474141E+02 = 0.611270731E+00 = 0.188002098E+02 | vinfx bdt dec | = 0.196190788E+02 = 0.722749678E+07 =-0.266714892E+01 | vinfy bdr altit | 0.667943389E+010.771108257E+050.498427244E+08 | vinfz =-0.965454360E+00 hypta = 0.000000000E+00 |
| state relative primary box x = 0.123825196E+09 vx =-0.575163219E+01 sma = 0.172088150E+09 argp = 0.221411371E+03 | ody: sun y vy eccen anlong | = 0.870181568E+08 = 0.307835144E+02 = 0.427685649E+00 | z vz inc meaan | -0.562413535E+07 -0.829003904E+00 -0.338609689E+01 -0.501923109E+02 | | | |
| initial conditions for ph | phase 3 | 35 | | | | | |
| date = 6 17 2011 12.00 primid = sun timrfl = 0.208000000E+03 | julian secid | =2455730.00000000 = mars | tdurp 1dbody | = 0.00000000 = mars | critr frame | <pre>tdurp ecliptic</pre> | propid = 1step epoch = mean2000 |
| rela 1 0 1 1 0 1 1 0 0 1 1 1 0 0 1 1 1 1 1 1 | y vy eccen truan | =-0.450091738E+08 = 0.952183309E+01 = 0.292804740E+05 =-0.829830577E+02 | z vz inc tfp | =-0.418356853E+07 = 0.430262841E-01 = 0.150384887E+03 =-0.602144383E+02 | radius speed argp rperi | = 0.655751275E+08 = 0.125099738E+02 = 0.270400715E+03 = 0.801280918E+07 | scmass = 0.387008669E+06 fpa =-0.829811156E+02 anlong = 0.499118207E+02 vperi = 0.125103488E+02 |
| Incoming Asymptore altp = 0.800941198E+07 bmag = 0.801308284E+07 c3 = 0.156498137E+03 | vinfm btheta ra | = 0.125099216E+02 = 0.150385483E+03 = 0.495651526E+02 | vinfx bdt dec | = 0.811367384E+01 =-0.696633183E+07 = 0.197053866E+00 | vinfy bdr altit | = 0.952179516E+01 = 0.395976229E+07 = 0.655717303E+08 | vinfz = 0.430245223E-01 hypta = 0.899980432E+02 |
| Outgoing Asymptote altp = 0.800941198E+07 | vinfm | = 0.125099216E+02 | vinfx | = 0.811423831E+01 | vinfy | = 0.952131222E+01 | vinfz = 0.434467758E-01 |

```
- 0.00000000E+00
             hypta
           = 0.395976087E+07
= 0.655717303E+08
           bdr
altit
        --0.696633264E+07
- 0.198987810E+00
                                                             =-0.562413535E+07
= 0.829003904E+00
= 0.338609689E+01
= 0.501923109E+02
                                                               z
vz
inc
meaan
        bdt
dec
bmag = 0.801308284E+07 btheta = 0.150385495E+03

c3 = 0.156498137E+03 ra = 0.495637180E+02

state relative primary body: sun

x = 0.12385219E+09 y = 0.870181568E+08

vx =-0.575162219E+01 vy = 0.307835144E+02

sma = 0.172088150E+09 eccen = 0.427685649E+00

argp = 0.221411371E+03 anlong = 0.740056455E+02
```

final conditions for phase 35

| | | | <pre>propid = conic epoch = mean2000</pre> | <pre>* 0.219065841E+03 radius = 0.388086085E+04 scmass = 0.387008669E+06 * 0.629314835E+00 speed = 0.707171967E+01 fpa =-0.269970313E-02</pre> |
|---|--|--|--|--|
| = 0.397735071E+01 altit = 0.483660847E+03 | | | 0.00000000 critr = tdurp frame = ecliptic | <pre>* 0.219065841E+03 radius = 0.388086085E+04 * 0.629314835E+00 speed = 0.707171967E+01</pre> |
| altit | | | critr frame | radiu |
| = 0.397735071E+01 | = 0.576011729E+07 = 0.116651544E+01 = 0.359534798E+01 = 0.122469476E+03 | | = mars | = 0.219065841E+03 = 0.629314835E+00 |
| qec | z vz inc meaan | neuver | tdurp idbody | 2 A |
| - 0.458758002E+02 dec | = 0.235261746E+09 z = 0.371924357E+01 vz = 0.491122390E+00 inc = 0.754917109E+02 meaan | 5 before orbins ma | =2455845.00000000 = sun | =-0.268195846E+04 z = 0.510840155E+01 vz |
| ra V: Sun | y vy eccen anlong | se 4 | julian secid | y vy |
| = 0.279376795E+02 ra | x =-0.338137002E+08 y = vx =-0.182143713E+02 vy = sma = 0.172476669E+09 eccen = argp = 0.226479289E+03 anlong = | initial conditions for phase 45 before orbins maneuver | date =10 10 2011 12.00 julian =2455845.0000000 tdurp primid = mars secid = sun idbody state relative to idbody: mare | = 0.279646024E+04 |
| c3 stat | x vx sma argp | init | date prim | ×× |

| execution | date and time | Fri Oct | 23 | | | | | L bage |
|--|---|-----------------------------------|---|--|---|---|---|--|
| sma meaan | =-0.153299371E+04 =-0.655473392E-02 | eccen | = 0.353155693E+01 =-0.346415439E-02 | inc tfp | = 0.604937751E+01 =-0.384028891E-06 | argp rperi | = 0.323901798E+02 = 0.388000000E+04 | <pre>anlong = 0.283955165E+03 vperl = 0.707171967E+01</pre> |
| orbins dvx thrust | maneuver print b =-0.145887869E-01 = 0.20000000E+06 | block dvy spi | -0.302675298E-02 | dvz daass | =-0.518018869E-02 = 0.164541093E+06 | dvmag wprop | = 0.260621089E+01 = 0.222467576E+06 | tburn = 0.504309171E+04 |
| initial | conditions for | phase 45 | after orbins | maneuver | | | | |
| date primid timrfl | T * * | jullan secid | =2455845.00000000 | tdurp 1dbody | mars 0.00000000000000000000000000000000000 | critr frame | <pre>= tdurp * ecliptic</pre> | propid = conic epoch = mean2000 |
| state r x vx sma meaan altp | 4000000 | y vy vy eccen truan alta lond | -0.268119410E+04 -0.322621981E+01 -0.806998781E+00 -0.804571863E-15 -0.32929800E+05 | z vz inc tfp rapoap longp | - 0.219038125E+03 - 0.397436432E+00 - 0.604937751E+01 - 0.731596672E-18 - 0.36327000E+05 - 0.286478898E+03 | radius speed argp rperi altit | - 0.388000000E+04 - 0.446609975E+01 - 0.323901798E+02 - 0.3880000000E+03 | scmass = 0.222467576E+06 fpa ==0.381666562E-12 anlong = 0.283955165E+03 vper1 = 0.446609975E+01 period = 0.865410237E+05 |
| x x vx vx sma | 0.3381370 0.2000123 0.1863651 0.2374995 | | | z vz inc meaan | 0.576011726E+070.934637042E+000.277885896E+010.128078496E+03 | | | |
| final | conditions for phase | se 45 | | | | | | |
| ⊽∺ | =12 9 2011 12.00 = mars = 0.383000000E+03 | julian secid | =2455905.00000000 | tdurp 1dbody | = 60.00000000 = mars | critr frame | <pre>tdurp ecliptic</pre> | propid = conic epoch = mean2000 |
| state r x x vx vx sma | relative to idbody: =-0.174242594E+05 = 0.129920633E+01 = 0.201035000E+05 =-0.351984804E+02 | mars y vy eccen truan | = 0.534144104E+03 =-0.102879184E+01 = 0.806998781E+00 =-0.138018007E+03 | z vz inc tfp | 0.177839432E+04 - 0.107327232E+00 - 0.604937751E+01 0.97933144E-01 | radius speed argp | 0.175229224E+050.166068325E+010.323901798E+020.388000000E+04 | scmass = 0.222467576E+06 fpa =-0.534531795E+02 anlong = 0.283955165E+03 vperi = 0.446609975E+01 |
| | = 0.482800000E+03 = 0.0000000000E+00 | alta long | | rapoap longp | = 0.363270000E+05 = 0.286478898E+03 | | - 0.141257224E+05 | # T3 |
| | =-0.1442165E+09 =-0.174003685E+02 =-0.220101204E+03 | y vy eccen anlong | | z vz inc meaan | = 0.770694762E+07 = 0.311697669E+00 = 0.198999094E+01 =-0.168813507E+03 | | | |
| initial | conditions for ph | ase 50 | before launch | maneuver | | | | |
| 몆 | =12 9 2011 12.00 = sun | Jul sec | =2455905.00000000 = mars | tdurp 1dbody | = 60.00000000 = mars | critr frame | <pre>tdurp ecliptic</pre> | propid = 1step epoch = mean2000 |
| state r x vx sma meaan | relative to 1000y: =-0.1742594E+05 =-0.129920633E+01 = 0.201035000E+05 =-0.351984804E+02 | y vy eccen truan | = 0.534144104E+03 =-0.102879184E+01 = 0.806998781E+00 =-0.138018007E+03 | z vz inc tfp | =-0.177839432E+04 = 0.107327232E+00 = 0.604937751E+01 =-0.979331444E-01 | radius speed argp rperi | = 0.17529224E+05 = 0.166068325E+01 = 0.323901798E+02 = 0.388000000E+04 | scmass = 0.222467576E+06 fpa =-0.534531795E+02 anlong = 0.283955165E+03 vperi = 0.446609975E+01 |
| launch dvx thrust | maneuver print b =-0.145887869E-01 = 0.200000000E+06 | block dvy spi | =-0.302675298E-02 = 0.480000000E+03 | dvz dmass | =-0.518018869E-02 = 0.118648304E+06 | dvmag wprop | = 0.358749107E+01 = 0.103819271E+06 | tburn = 0.399050221E+04 |

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initial conditions for phase 50 after launch maneuver

| propid = 1step epoch = mean2000 | scmass = 0.103819271E+06 fpa =-0.172131619E-09 anlong = 0.230471824E+03 vper1 = 0.805359082E+01 | vinfz = 0.666886960E+00 hypta = 0.781654038E+02 | vinfz = 0.728139046E+00 hypta = 0.000000000E+00 | | | propid = 1step epoch = mean2000 | scmass = 0.103819271E+06 fpa = 0.891446927E+02 anlong = 0.139665486E+03 vper1 = 0.729044665E+01 | vinfz = 0.678943538E+00 hypta = 0.898673611E+02 | vinfz = 0.645524762E+00 hypta = 0.00000000E+00 | | | <pre>propid = 1step epoch * mean2000</pre> | scmass = 0.103819271E+06 |
|--------------------------------------|--|---|---|---|---------------------------|------------------------------------|--|---|---|--|------------------------------|---|---------------------------------------|
| <pre>= tdurp = ecliptic</pre> | s = 0.388000000E+04 = 0.805359082E+01 = 0.348165404E+03 = 0.388000000E+04 | =-0.581451596E+01 = 0.214615796E+03 = 0.482800000E+03 | =-0.413715562E+01 =-0.179589667E-08 = 0.48280000E+03 | | | <pre>tdurp ecliptic</pre> | s = 0.234253337E+08 = 0.727384023E+01 = 0.84757867E+02 = 0.34882216E+06 | =-0.464380902E+01 =-0.348461716E+06 = 0.234219365E+08 | =-0.464793259E+01 =-0.348462754E+06 = 0.234219365E+08 | | | = tdurp = ecliptic | . = 0.114553064E+09 |
| critr frame | radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | critr frame | radius speed argp rperi | vinfy bdr altit | vinfy bdr altít | | | critr frame | radius |
| = 0.00000000 | =-0.885817392E+02 = 0.877470951E+00 = 0.639142809E+01 =-0.201412605E-13 | = 0.292071129E+01 = 0.477246193E+04 = 0.585180749E+01 | = 0.501374565E+01 = 0.477728509E+04 = 0.639142809E+01 | = 0.770863743E+07 = 0.108184139E+01 = 0.383356774E+01 =-0.771008284E+02 | | = 40.00000000 = mars | = 0.242582832E+07 = 0.645548932E+00 = 0.947842140E+02 = 0.372663101E+02 | = 0.555690279E+01 =-0.292932592E+05 = 0.535599592E+01 | = 0.555743786E+01 =-0.292809055E+05 = 0.509165016E+01 | = 0.104263493E+08 = 0.609935752E+00 = 0.352537246E+01 =-0.868798376E+02 | | = 0.00000000 = earth | = 0.104298645E+08 |
| tdurp 1dbody | z vz inc típ | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | tdurp 1dbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | tdurp 1dbody | N |
| =2455905.00000000 | =-0.242577039E+04 =-0.625959852E+01 = 0.487597776E+01 =-0.206957351E-09 | = 0.654093942E+01 = 0.257483466E+01 =-0.633289928E+02 | = 0.654093942E+01 =-0.215388652E-10 =-0.547790228E+02 | = 0.198913706E+09 =-0.184188742E+02 = 0.297775446E+00 = 0.980212618E+02 | | =2455945.00000000 | =-0.149251718E+08 =-0.464809298E+01 = 0.431968600E+03 = 0.892773168E+02 | = 0.727358887E+01 =-0.948052429E+02 =-0.398849297E+02 | = 0.727358887E+01 =-0.948032116E+02 =-0.399099546E+02 | * 0.132317242E+09 *-0.221008314E+02 = 0.286340551E+00 * 0.953199762E+02 | | =2455945.00000000 = earth | = 0.190575515E+07 |
| julian secid | mars y vy eccen truan | vinfm btheta ra | vinfm btheta ra | y y vy eccen anlong | e 50 | jul sec | mars y vy eccen truan | vinfm btheta ra | vin bth | y y vy eccen anlong | ase 60 | julian secid | earth Y |
| =12 9 201 d = sun 1 = 0.383000 | | | 6000 | state relative primary body: 3 x =-0.144207268E+09 y vx =-0.137088037E+02 y sma = 0.240662237E+09 ecc. argp = 0.139186832E+03 anl | final conditions for phas | * * * * | ⊣ 1 | 5 | ucgoing Asymptone 1tp = 0.345485016E+0 mag = 0.349690810E+0 0.529050951E+0 | are feature primary =-0.182292745E+0 =-0.788523682E+0 a = 0.211970237E+0 gp = 0.167354273E+0 | initial conditions for phase | date = 1 18 2012 12.00 primid = sun timrf1 = 0.42300000E+03 | relative to idbod =-0.114061345E+0 |

fpa =-0.666317000E+02 anlong = 0.162094779E+03 vper1 = 0.207016606E+02 - 0.207014049E+02 - 0.843450076E+02 - 0.454357735E+08 . . speed argp rperi = 0.610586295E+00 = 0.174136625E+02 =-0.587928657E+02 vz inc tfp =-0.818599076E+01 = 0.488496640E+05 =-0.666327767E+02 vy eccen truan vx = 0.190043391E+02 sma =-0.930133391E+03 meaan =-0.647756922E+07 Incoming Asymptote

| 6 əbed | vinfz = 0.610591689E+00 hypta = 0.899988271E+02 | vinfz = 0.610339279E+00 hypta = 0.000000000E+00 | | | propid = 1step epoch = mean2000 | scmass = 0.103819271E+06 fpa =-0.368042702E-02 anlong = 0.788281155E+02 vper1 = 0.117866853E+02 | vinfz =-0.204967097E+01 hypta = 0.443116145E+02 | vinfz =-0.107291524E+00 hypta = 0.00000000E+00 | | | | | | | | propid = 1step epoch = mean2000 |
|-------------------------|---|---|---|--------------------------|---|--|--|--|--|------------------------------|-------------------------|------------------------|---|------------------------------|----------------------------|---|
| | =-0.818595464E+01 =-0.135374523E+08 = 0.114546686E+09 | -0.818521453E+01 -0.135375023E+08 -0.114546686E+09 | | | = timrf1 | s = 0.687887535E+04 = 0.117866853E+02 = 0.221319779E+03 = 0.687887532E+04 | =-0.119651454E+01 =-0.609533276E+03 = 0.500735349E+03 | - 0.465823139E+01 - 0.722751805E+04 - 0.500735349E+03 | | | | | | | | <pre># tdurp # ecliptic</pre> |
| | vinfy bdr altit | vinfy bdr altit | | | critr frame | radiu speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | | | | | | critr frame |
| | 0.190041714E+020.433731647E+080.169020826E+01 | - 0.190044983E+02 - 0.433731491E+08 - 0.168950934E+01 | - 0.104263493E+08 - 0.609935752E+00 - 0.352537246E+01 0.868798376E+02 | | = 160.00000000 = earth | 0.194506645E+04 0.379163000E+01 - 0.253602065E+02 0.744374105E-06 | - 0.417156720E+01 - 0.168824044E+05 0.252813304E+02 | <pre>= 0.115071279E+01 = 0.152692531E+05 =-0.128095029E+01</pre> | = 0.294353651E+04 =-0.379222870E+01 = 0.553136848E+01 =-0.106296698E+01 | | | 9 6E-01 | 9 4E+04 2E-03 | | | - 0.00000000 - earth |
| | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | tdurp idbody | z VZ Inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | | .28139046 | .68824044 | | | tdurp idbody |
| Oct 23 | vinfm = 0.207012368E+02 btheta =-0.173339706E+02 ra =-0.233037267E+02 | vinfm = 0.207012368E+02 btheta =-0.173340367E+02 rr =-0.233018445E+02 | = 0.132317242E+09 =-0.221008314E+02 en = 0.286340551E+00 ong = 0.953199762E+02 | 0 | julian =2456105.00000000 secid = earth | =-0.586397149E+04 = 0.608449291E+01 en = 0.139752415E+01 an =-0.631396077E-02 | fm = 0.479945529E+01 eta =-0.206774582E+01 =-0.160042755E+02 | fm = 0.479945529E+01 eta = 0.253299735E+02 = 0.481547288E+02 | sun =-0.151476745E+09 = 0.863663485E+01 en = 0.807965674E+00 ong = 0.951203674E+02 | 9 | al icnvgd = 1 | 8 -4.13715562E+00 7 | 8 7.44374105E-07 1 7.44374105E-07-4 | 65 | 10 | lan =2456105.00000000 id = earth :h |
| Fr1 0 | 8 vin 8 bth 3 ra | 8 vinfr 8 bthet 3 ra | body: sun 9 y 1 vy 9 eccen 3 anlong | ase 60 | 0 julia secid | | 3 vinfm 5 btheta 2 ra | vin bth | ay: ay an] | phase | 1 final | 7 .01374565E+00 | .87887532E+03- | phase | ase 65 | <pre>pullan secid secid y: earth</pre> |
| execution date and time | altp = 0.454293953E+0 bmag = 0.454367036E+0 c3 = 0.428541206E+0 Outgoing Asymptote | altp = 0.454293953E+0 bmag = 0.454367036E+0 c3 = 0.428541206E+0 | scare ferative primary body: su x =-0.18292745E+09 y vx =-0.788523682E+01 vy sma = 0.211970237E+09 eccen argp = 0.167354273E+03 anlon | final conditions for pho | date = 6 26 2012 12.00 primid = sun timrf1 = 0.583000000E+03 etate relation to idhodu | | 2 | | scace relative primary box x = 0.135426994E+08 vx = 0.385420732E+02 sma = 0.776899225E+09 argp = 0.196756036E+03 | initial conditions for phase | subproblem iteration 31 | subp. ind. vars. 5.013 | subp. dep. vars. 6.876 -8.753 | initial conditions for phase | final conditions for phase | <pre>date</pre> |

| fpa =-0.103819271E+06 fpa =-0.368042702E-02 anlong = 0.788281155E+02 vperi = 0.117866853E+02 | vinfz =-0.204967097E+01 hypta = 0.443116145E+02 | vinfz =-0.107291524E+00 hypta = 0.00000000E+00 |
|---|--|---|
| | | |
| radius = 0.687887535E+04 speed = 0.117866853E+02 argp = 0.221319779E+03 rper1 = 0.687887532E+04 | vinfy =-0.119651454E+01 bdr =-0.609531276E+03 altit = 0.500735349E+03 | <pre>= 0.465823139E+01 = 0.722751805E+04 = 0.500735349E+03</pre> |
| radius speed argp rperi | vinfy bdr altit | vinfy bdr altit |
| =-0.194506645E+04 =-0.379163000E+01 = 0.253602065E+02 =-0.744374105E-06 | <pre>- 0.417156720E+01 - 0.168824044E+050.252813304E+02</pre> | 0.479945529E+01 vinfx = 0.115071279E+01 vinfy = 0.465823139E+01 0.253299735E+02 bdt = 0.152692531E+05 bdr = 0.722751805E+04 0.481547288E+02 dec =-0.128095029E+01 altit = 0.500735349E+03 |
| z vz inc tfp | vinfx bdt dec | vinfx bdt dec |
| =-0.586397149E+04 = 0.608449291E+01 = 0.139752415E+01 =-0.631396077E-02 | = 0.479945529E+01 vinfx =-0.206774582E+01 bdt =-0.160042755E+02 dec | |
| y vy eccen truan | vinfm btheta ra | vinfm btheta ra |
| x = 0.302481089E+04 y ==0.58639714 vx = 0.935566338E+01 vy = 0.60844929 sma ==0.173042955E+05 eccen = 0.13975241 mean ==0.102203474E=02 truan ==0.63139607 Incoming Asymptote | altp = 0.500735324E+03 vinfm = bmag = 0.168934043E+05 btheta = 0.30347710E+02 ra = 0.0tgoing Asymptote | altp = 0.500735324E+03 v bmag = 0.168934043E+05 b c3 = 0.230347710E+02 r |
| vx sma meaan Incom | altp bmag c3 Outgo | altp bmag c3 |

| state relative primary body: x = 0.13542694E+08 y vx = 0.385420732E+02 vy sma = 0.776899225E+09 ecc argp = 0.196756036E+03 anl | ody: sun y vy eccen anlong | =-0.151476745E+09 = 0.863663485E+01 = 0.807965674E+00 | z vz inc meaan | = 0.294353651E+04 =-0.379222870E+01 = 0.553136848E+01 =-0.106296698E+01 | | | order of the control |
|--|--|--|-------------------------|--|----------------------------------|--|---|
| initial conditions for phase | | 70 before orbins n | maneuver | | | | |
| date = 6 26 2012 12.00 primid = sun state relative to idbody: | julian secid | =2456105.00000000 = earth | tdurp | = 0.00000000 = earth | critr frame | <pre>= tdurp = ecliptic</pre> | propid = 1step epoch = mean2000 |
| x = 0.302481089E+04 vx = 0.93556338E+01 sma =-0.173042955E+05 meaan =-0.102203474E-02 | | =-0.586397149E+04 = 0.608449291E+01 = 0.139752415E+01 =-0.631396077E-02 | z vz inc tfp | =-0.194506645E+04 =-0.379163000E+01 = 0.253602065E+02 =-0.744374105E-06 | radius speed argp rperi | = 0.687887535E+04 = 0.117866853E+02 = 0.221319779E+03 = 0.687800000E+04 | scmass = 0.103819271E+06 fpa =-0.368042702E-02 anlong = 0.788281155E+02 vper1 = 0.117866853E+02 |
| orbins maneuver print block dvx =-0.145887869E-01 dvy thrust = 0.20000000E+06 spi | block dvy spi | =-0.302675298E-02 = 0.480000000E+03 | dvz dmass | 0.518018869E-02 - 0.277942906E+05 | dvmag wprop | = 0.146671222E+01 = 0.760249809E+05 | tburn = 0.761357577E+03 |
| initial conditions for phase | | 70 after orbins ma | maneuver | | | | |
| final conditions for phase | se 70 | | | | | | |
| date = 6 26 2012 12.00 primid = sun timrfi = 0.583000000E+03 | | =2456105.00000000 = earth | tdurp idbody | = 0.00000000 = earth | critr frame | <pre>tdurp ecliptic</pre> | propid = 1step epoch = mean2000 |
| sma = 0.424570000E+03 | y vy eccen | =-0.586283403E+04 = 0.532814871E+01 = 0.838000801E+00 | 2 | =-0.194506277E+04 =-0.331991825E+01 = 0.253602065E+02 | radius | N N I | N N |
| | | | tfp rapoap longp | = 0.171818575E-13 = 0.78036000E+05 = 0.286478898E+03 | alyprineri | - 0.68780000E+03 - 0.68780000E+04 - 0.499860000E+03 | aniong = 0.188281155E+02 vper1 = 0.103207361E+02 period = 0.870632575E+05 |
| state relative primary body: x = 0.135426997E+08 y vx = 0.373782697E+02 y sma = 0.482542864E+09 ecc argp = 0.196592887E+03 anl | y y vy eccen anlong | =-0.151476744E+09 = 0.788029065E+01 = 0.690201821E+00 = 0.951215847E+02 | z vz inc meaan | = 0.294354020E+04 =-0.332051695E+01 = 0.500277705E+01 =-0.222790525E+01 | | | |
| initial conditions for phase | ase 75 | | | | | | |

55.390 seconds

total cpu time =

75.000

esn = 75.000 fesn= time= 2.45610500D+06 normal termination cpu = 55.380 seconds

3.3 LUNAR ORBITER

This case examines flight from a low Earth orbit (LEO) into a low lunar orbit. It has a master-subproblem formulation, and minimizes total ΔV .

The simulation starts with a specified Cartesian state vector at Earth (which corresponds to circular orbit of 6878 km radius). An impulsive maneuver is identified. The conic propagator is activated with Earth as the primary body. At a mission time specified as an optimization control, an impulsive midcourse correction is applied, at which time the primary and reference bodies are switched to the Moon. 3 days after Earth orbit escape, the S/C arrives at lunar closest approach and inserts into lunar orbit.

The optimization defines NPSOL as the optimization algorithm using finite difference perturbations computed internally by NPSOL. 50 iterations are allowed for the master problem and 200 iterations each for the 2 subproblems. The master control parameters are the Earth escape delta V components and the mission times of the midcourse maneuver and lunar closest approach.

The first subproblem varies midcourse ΔV to achieve desired hyperbolic conditions (closest approach distance, inclination, time from periapsis) at lunar arrival. The second subproblem varies lunar insertion ΔV , applied at hyperbolic periapsis, to achieve desired lunar orbit conditions (periapsis and apoapsis radii, and inclination).

The output echoes the namelist \$TOP and all \$TRAJ namelists. A summary of the problem is given, and execution output begins with a summary of each iteration of each subproblem for master iteration 0. Following the first converged iteration (13) of subproblem 2 is the summary of master iteration 0. The sequence repeats for all master iterations. Only master iterations 0, 1, 2, and the final iteration (13) are shown. After the iteration summary is displayed, the final trajectory simulation is output.

The total ΔV was 3.968 km/s, reduced from 4.058 km/s for the initial guess. Note that the iteration summaries display the <u>weighted</u> objective function value. The midcourse maneuver time has been moved from 2.39 days to 1.50 days, the lower control bound. Lunar closest approach time has been moved from 3.00 days to 3.5 days, the upper control bound.

```
i p o s t - interplanetary post simulation. version 2.18 , dated 03-05-90.
p$top
c
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       = 1,1,1, 2,2,2,
= 'dvx','dvy','dvz','dvy','dvz',
= 3*15, 3*2,
= .029158, -.007079, -.007728, .442687,-.790124,-.090804,
= .029158, -.007079, -.007728, .0, -1.0,0.,
= 6*2.,
= 6*2.,
= 6*1.d-5,
                                                                                                                                                                                                                                                                      30, 475224, 1.293166, 1.320728, 2.39376, 3.0, 20., 20., 24.9, 35., ..., .5, .5, 1.50, 2.5, ...
                                                                                                                                                                                                                                      'dvx','dvy','dvz', 'critr','critr',
1,1,1,15,30,
1,2,3,4,5,
                                 c civil space test case for lunar missions c during the period of march 1995 c using patched conic initial conditions c from lprep
                                                                                                                                                                                                    c master problem controls c vary initial velocity at loi from leo
                                                                                                                                                                                                                                                                                                                                           minimize the delta-v at the soi
                                                                                                                                                                                                                                                                                                                                                                                                                                                            'nraph','nraph',
30, 35,
1.0d0,
1.0d0,
                                                                                                                                                                  'autopert',
                                                                                                                                                                                                                                                                                                   = 1., .5, .
= 3., 2., 2
= 5*.0001,
                                                                                            " 'npsol',
                                                                                                                                                                                                                                                                                                                                                                     , wnsap,
                                                                                                                                                                                                                                                                                                                                                                                                                                    c subproblem setup
c
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c controls
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             npi
```

```
= 'cartes',
= 3709.62, -5603.24, -1466.03, 6.099613, 3.186706, 3.254626,
= 'impuls',
= 1,1,1, 2,2,2,
= 'rperi','inc','tfp','rperi','rapoap','inc'
= 3*30,3*35,
                                   c earth escape...use launch maneuver
                                                                                                                                                                              = 'eartheq','mean2000',
= 'julian',
                                                                                                                                                                                                                                                                                                                                                                          p$traj
event = 20,
critr = 'tdurp',
value = 0.d0,
idbody = 10,
ipbody = 10,
idfram = 'bodyeq','mean2000',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  p$traj
c final impulse to circularize
event = 32,
critr = 'tdurp',
icoord = 3,
value = 0.40,
                                                                                                                                                    = 1,
= 2450004.3,
                                                                                                                                                                                                                                = 2,
= 'conic'
                                                                                                                                                                                                                                                                                                     pstraj
event = 15,
critr = 'timrfl',
mantyp = 'impuls',
icoord = 2,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                    pstraj
event = 30,
critr = 'timrfl',
value = 3.0,
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= 1.d-7,
                                                                                                                                                  event
juldat
idbody
idfram
iepoch
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lcoord
iprop
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depsub
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p$traj
```

mantyp = 'impuls',

straj
 event = 35,
 critr = 'tdurp',
 value = 0.,

\$
p\$traj
 c i hope we are done
 event = 75,
 critr = 'tdurp',
 value = 0.00,
 namlst = 'none',
 \$
}

*** core requirements for problem 1 are ***

parameter octal decimal event criteria data - 456b 302
general data - 152b 106
table data - 20b 16

execution date and time Thu Oct

```
propagator
                                                                                         -1.4660300000000+03
3.254626000000+00
4.98051222686D-01
-4.62494638841D-01
                                                                                                                                                 2.02671364462D+03
1.71936831591D+00
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                                                       19 hr 11 min 60.0000 secs 3, earth , eartheg,
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0.10000E-01
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none
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                                                                                       -5.603240000000+03
3.186706000000+00
6.73340314442D-07
0.0000000000000+00
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3.20902105104D+01
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0.10000E-01
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master problem optimization parameter dvsum
master problem optimization algorithm - npsol
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1.40218765146D+08 5
-4.58141704386D+00 3
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                                 initial epoch juste ...2450004.3000 justan date ...2450004.3000 calendar date ...1995 oct 13, 1 initial body and frame of reference initial state
                                                                                        3.7096200000000+03
6.099613000000+00
6.87799118809D+03
5.71001203235D+00
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0.18380E+04
0.10000E-01
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0.18380E+04
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event summary
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30.000
32.000
75.000
                                                                                                                                                                                                                                                                                                                                                                                    1.000
1.000
1.000
15.000
                                                                                                                 conic
                                                                                                                                                                                                            1.000
                                                                                                                                                                                                 number
                                                                                                                                                                                                                                                                                                                                                                             evtnum
                                                                                                                                                                                                                                                                                                                                                                                                                                                                       evtnum
```

OPTIONS file

BEGIN OPTIONS FOR NPSOL 4.0

1.E-4 30 10 3.E-7 1.E-6 NO VERIFY LEVEL
DERIV LEVEL
DIFFERENCE INTERVAL
MAJOR ITERATIONS LIMIT
MAJOR PRINT LEVEL
NONLINEAR FEASIBILITY TOLERANCE
OPTIMALITY TOLERANCE
HESSIAN
COLD START

Calls to NPOPTN

major iteration limit = 50

NPSOL --- Version 4.05

Parameters

COLD start....... 1.00E-02 Function precision.... Verify level..... Save frequency..... 5.96E-08 1.00E+20 1.00E+20 1.00E-06 3.00E-07 9.00E-01 000 Central diffice interval 5.11E-05 Linear feasibility.....
Infinite bound size....
Infinite step size.... Optimality tolerance...
Nonlinear feasibility..
Linesearch tolerance...
Derivative level...... Major print level..... Minor print level..... RUN to be saved on file 0 5 2.00E+00 0 5 5 3.55E-15 50 Difference interval.... 1.00E-04 Step limit...... Nonlinear constraints.. Nonlinear Jacobian vars Nonlinear objectiv vars EPS (machine precision) Linear constraints..... Major iterations limit. Minor iterations limit. RUN loaded from file...

0

9.90E-14

51

W(770500). 2500), 15), Workspace provided is IW(To solve problem we need IW(

out of

'n 0

The user sets Each iteration,

ut of 5 objective gradient elements. gradient elements will be estimated numerically.

| | | | | | | | | | | propid = conic epoch = mean 2000 | scmass = 0.100000000E+07 fpa = 0.000000000E+00 anlong = 0.327159590E+03 vper1 = 0.000000000E+00 | tburn = 0.305607534E+04 | propid = conic |
|----------------------------|--|------------|--|----------|-------------|--|-------------|--------------|------------|---------------------------------------|--|--|----------------|
| Cond I Conv 0.E+00 F IF | | | 0.E+00 T FF C 0.E+00 F FF C 0.E+00 T T FF C 0.E+00 T T FF C 0.E+00 T T T T C 0.E+00 T T T T T T T T T T T T T T T T T T | | Residual | 0.1783E-01 0.3340E-01 0.3600E-01 0.0000E+00 | | | | = time = eartheq | = 0.000000000E+00 = 0.000000000E+00 = 0.000000000E+00 | = 0.305607534E+01 = 0.999688416E+06 | = time |
| H Cond Hz | .72506383D+00 | | 1. E+00 1. E+00 1. E+01 1. E+01 1. E+03 1. E+03 1. E+04 1. E+04 1. E+04 1. E+04 1. E+03 1. | | multiplier | 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.1593707 | | | | 00 critr frame | 04 radius 01 speed 02 argp 00 rperi | 01 dvmag 03 wprop | 00 critr |
| Gz Cond H +00 1.E+00 | 9.72506 | | .1E+01 4.E+05 .3E+01 1.E+06 .8E+01 3.E+06 .4E+00 4.E+06 .2E+00 1.E+04 .2E+00 6.E+04 .2E+00 6.E+04 .3E+00 6.E+05 .3E+00 7.E+05 .3E+00 8.E+05 .3E+00 8.E+05 .3E+00 8.E+05 | D = 15 | Lagr | 00+ | | | | 0.00000000 th | 46603000E+04 25462600E+01 85362330E+02 00000000E+00 | .122005899E+01 | 0.00000000 |
| Gf Norm Gz +00 0.0E+00 | iteration = .03229038D+01 | *uo | | SO NGRAD | Upper bound | 0.1000000 0.1000000 0.10000000 0.1000000E+00 | | | . | = ear | -0.14 -0.32 -0.28 | 1 I | ι ρ. |
| Norm Gf 0.0E+00 | 1.032 | raphson | | | | | į | | maneuve |) tdurp idbody | 4 z 1 vz 6 inc 0 tfp | 1 dvz 7 dmas: | 0 tdurp |
| Lin Nz | 70+01 50+00 | newton | | NEUN | r bound | 0.333333E-01 0.250000E-01 0.250000E-01 0.6024096E-01 | nodn þa | | s I nd | 000000 | 000E+0, 600E+0) 314E-0 | 456E+0 | 000000 |
| e Bnd 1 5 | ations 21802457D+01 62112485D+00 | verg in | 222222222222222222222222222222222222222 | 16 | Lower | | improved | .396790 | tore impul | 50004.30000000 oon | 0.560324000E+04 0.318670600E+01 0.673340314E-06 | .133205456E+0; | 50004.30000000 |
| Objectiv | lcul 1. | d 1 | | MAJITS . | ě | 0.8216976E-01 0.6660273E-01 0.6100295E-01 0.6024096E-01 | not be | | l bet | =24 = = | | | -24 |
| - | ction c 864D+0] 379D+00 | s control | | 9 • | Value | .82169 .66602 .61002 .60240 | nt cannot | e value | phase | | eart y vy ecce | block dvy spi | julian |
| Nfun 1 | e in function ca 1.22121864D+01 9.26737379D+00 | •tt | 2017 2017 2017 2017 2017 2017 2017 2017 | INFORM | State | FR 111 19 00 00 00 00 00 00 00 00 00 00 00 00 00 | ent point | ject i | for | 19.20 | 1dbody 000E+04 300E+01 119E+04 109E+02 | print 293E+01 300E+07 | 5 19.20 |
| Step 0.0E+00 | livergence errors 1 errors 9 | **error** | 1.8E-03 0.0E+00 2.1E-03 1.4E-01 1.6E-01 1.0E+000 1.0E+000 1.0 | phase. I | St | | L - Current | nonlinear ob | conditions | 0 13 1995 earth | relative to idbody: = 0.37096200E+04 = 0.609961300E+01 = 0.687799119E+04 =-0.264989909E+02 | maneuver print b 0.246509293E+01 0.100000000E+07 | 0 13 1995 |
| Itn ItOP 0 5 | s - di fon e fon e | • | 11111111111111111111111111111111111111 | Exit NP | Variable | VARBL 1 VARBL 2 VARBL 3 VARBL 4 VARBL 5 | Exit NPSOL | 0 | initial c | date =1 primid = 0 | | uls ust = | date =1 |
| Ħ | t t | | | EX | Va | 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | Ä | F1 | 1 1 | da Pr | x x tt x x x x x x x x x x x x x x x x | Amp dvx thr | d d |

| execution date and time T | Thu Oct | 29 | | | | | page 2 |
|---|------------------------------------|--|---------------------------------|---|----------------------------------|--|---|
| id = earth f1 = 0.000000000E+00 | e e | moon n | idbody | = earth | frame | = eartheq | epoch = mean2000 |
| scare relative to ldbody: x = 0.370962000E+04 vx = 0.856470593E+01 sma = 0.188927030E+06 meaan =-0.851281492E-03 altp = 0.000000000E+03 lat = 0.000000000E+03 | : earth y vy eccen truan alta long | =-0.560324000E+04 = 0.451876056E+01 = 0.963594514E+00 =-0.171730805E+00 = 0.364597940E+06 = 0.229183118E+03 | z vz inc tfp rapoap | 0.146603000E+04 0.447468499E+01 0.2286496717E+02 0.223670677E-04 0.370976080E+06 | radius speed argp rperi | - 0.687799557E+04 - 0.106675297E+02 - 0.333217561E+03 - 0.687798040E+04 | scmass = 0.999688416E+06 fpa =-0.84273430E-01 anlong = 0.327676481E+03 vperi = 0.106675417E+02 period = 0.817244684E+06 |
| =-0.759006979E+05 = 0.951205607E+01 =-0.380733699E+02 = 0.346372413E+03 | y vy eccen anlong | | z vz inc meaan | =-0.131479114E+06 = 0.444468661E+01 = 0.237655305E+02 =-0.389913692E+06 | | | |
| final conditions for phase | 3e 1 | | | | | | |
| =10 d = ea 1 = 0. | julian secid | =2450005.80000000 ≠ moon | tdurp idbody | = 1.50000000 = earth | critr frame | <pre>timrf1 = eartheq</pre> | propid = conic epoch = mean2000 |
| te relat =-0. | | = 0.218931354E+06 = 0.805702796E+00 | | = 0.717762941E+05 = 0.179884081E+00 | radius speed | = 0.248859453E+06 = 0.104575649E+01 | scmass = $0.999688416E+06$ fpa = $0.736246009F+02$ |
| = 0.188927030E+06 n = 0.570885381E+02 = 0.499840405E+03 = 0.000000000E+00 | ⊕ th ≰ i | | inc tfp rapoap longp | 0.280496717E+020.149997763E+010.370976080E+060.630253575E+03 | | = 0.333217561E+03 = 0.687798040E+04 = 0.242481313E+06 | ong ri lod |
| ve to second 90857658E+05 17050107E+00 35511541E+04 10765779E+03 | lary body: y vy eccen anlong | /: moon =-0.162488384E+06 = 0.89772776E+00 = 0.264422074E+01 = 0.592438130E+02 | z vz inc meaan | 0.554224461E+05 - 0.252849089E+00 - 0.535655879E+02 0.177537257E+04 | | | |
| initial conditions for pho- | phase 1 | 15 before impuls ma | maneuver | | | | |
| =10 id = ea | julian | =2450005.80000000 = moon | tdurp idbody | = 1.50000000 = earth | critr frame | <pre>= timrf1 = eartheq</pre> | propid = conic epoch = mean2000 |
| =-0.9406515295405 =-0.6419434295+00 = 0.1889270305+06 = 0.570885381E+02 | | = 0.218931354E+06 = 0.805702796E+00 = 0.963594514E+00 = 0.168950122E+03 | z vz inc tfp | = 0.717762941E+05 = 0.179884081E+00 = 0.280496717E+02 = 0.149997763E+01 | radius speed argp rperi | = 0.248859453E+06 = 0.104575649E+01 = 0.333217561E+03 = 0.687798040E+04 | scmass = 0.999688416E+06 fpa = 0.736246009E+02 anlong = 0.327676481E+03 vper1 = 0.106675417E+02 |
| <pre>impuls maneuver print bl dvx *-0.274819515E-01 thrust * 0.10000000E+07</pre> | dvy spi | =-0.214944086E-01 = 0.100000000E+07 | dvz dmass | = 0.382630952E-01 = 0.527859218E+01 | dvmag wprop | = 0.517815770E-01 = 0.999683137E+06 | tburn = 0.517654427E+02 |
| initial conditions for pha | se 1 | 5 after impuls | maneuver | | | | |
| final conditions for phase | e 15 | | | | | | |
| date =10 15 1995 7.20 primid = earth timrfl = 0.15000000E+01 | julian secid | =2450005.80000000 = moon | tdurp | = 0.00000000 = earth | critr frame | <pre>= tdurp = eartheq</pre> | propid = conic epoch = mean2000 |
| tate | earth y | = 0.218931354E+06 | N | - 0.717762941E+05 | radius | = 0.248859453E+06 | scmass = 0.999683137E+06 |

×

| page 3 | anlong = 0.342787237E+03 vperi = 0.997295182E+01 period = 0.827278788E+06 | | | propid = conic epoch = mean2000 | scmass = 0.999683137E+06 fpa =-0.884802786E+02 anlong = 0.243298919E+03 vperi = 0.249328026E+01 | vinfz =-0.795543808E-01 hypta = 0.412702068E+02 | vinfz = 0.254510832E+00 hypta = 0.412702068E+02 | | | propid = conic epoch = mean2000 | scmass = 0.999683137E+06 fpa =-0.383159621E-01 anlong = 0.243295862E+03 vperi = 0.249328026E+03 | vinfz =-0.795543919E-01 hypta = 0.412702068E+02 | vinfz = 0.254510830E+00 hypta = 0.412702068E+02 | |
|--------------|--|--|------------------------|--|--|---|---|--|----------------------|---|--|---|---|---|
| | = 0.320308678E+03 = 0.785013748E+04 = 0.242481313E+06 | | | = tdurp = bodyeq | = 0.178559611E+06 = 0.967708529E+00 = 0.300827185E+03 = 0.183800683E+04 | =-0.673507087E+00 = 0.128482567E+04 1 = 0.176821521E+06 | =-0.550859624E+00 = 0.253339542E+03 = 0.176821521E+06 | | | = timrfl F = bodyeq | = 0.183800755E+04 = 0.249327985E+01 = 0.300827182E+03 = 0.183800683E+04 | =-0.673472415E+00 v = 0.128482565E+04 F = 0.999175488E+02 | =-0.550897883E+00 v = 0.253339604E+03 h = 0.999175488E+02 | |
| | argp rperi altit | | | critr frame | radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | critr frame | radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | |
| | 0.21595786E+020.150528909E+010.373090482E+060.630253575E+03 | 0.554224461E+05 -0.291112184E+00 -0.282013955E+02 0.167144329E+04 | | 0.00000000 = moon = | = 0.138631727E+05 =-0.818931114E-01 = 0.160000013E+02 =-0.200000999E+01 | =-0.649310548E+00 = 0.470871314E+04 =-0.486055149E+01 | = 0.716465488E+00 = 0.487427692E+04 = 0.157280446E+02 | 0.213371395E+05 0.112162056E+00 - 0.682936048E+01 - 0.565958086E+02 | | 2.00000000 | 0.435350032E+03 - 0.351880260E+00 - 0.160000013E+02 0.999438825E-05 | =-0.649346509E+00 = 0.470871315E+04 =-0.486055217E+01 | = 0.716436071E+00 = 0.487427692E+04 = 0.157280445E+02 | =-0.375184198E+05 = 0.360845359E+00 = 0.319956731E+02 |
| | inc tfp rapoap longp | z vz inc meaan | | tdurp 1dbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | | tdurp idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | vz inc |
| 59 | = 0.958785506E+00 = 0.168108968E+03 = 0.366712342E+06 = 0.401070457E+03 | * | 20 | =2450005.80000000 = earth | = 0.131335948E+06 =-0.694433710E+00 = 0.133048215E+01 =-0.137187113E+03 | = 0.938906217E+00 = 0.152622669E+02 =-0.133952082E+03 | H II II | H II # R | | =2450007.80000000 = earth | =-0.157497959E+03 =-0.246469328E+01 = 0.133048215E+01 =-0.671145151E-01 | = 0.938906217E+00 = 0.152622667E+02 =-0.133955141E+03 | * " " | : ear.0.399028725E+06 =-0.236826329E+01 = 0.270586764E+01 |
| time Thu Oct | eccen truan alta long | y y vy eccen anlong | e s | | y vy eccen truan | vinfm btheta ra | vinfm btheta ra | ry bouy y vy eccen anlong | 5 20 | julian secid | y vy eccen truan | vinfm btheta ra | _ rd : | . . |
| date and | - 0.190470310E+06 - 0.565958086E+02 - 0.147199748E+04 - 0.00000000E+00 | -0.490857658E+05 y -0.289568155E+00 vy -0.556159178E+04 eccen -0.358243518E+03 anlong | l conditions for phase | =10 15 1995 7.20 = moon = 0.15000000E+01 | | , , , , , | = 0.99168289E+02 = 0.488085612E+04 = 0.881544884E+00 | 0.179790760E+05 0.240181669E+00 0.190470310E+06 | conditions for phase | =10 17 1995 7.20 = moon = 0.350000000E+01 | = 0.17874576E+04 y = 0.133834579E+00 vy =-0.556159178E+04 eccel n =-0.835248487E-02 truam | = 0.488085612E+04 = 0.488085612E+04 = 0.881544884E+00 | = 0.999168289E+02 = 0.488085612E+04 = 0.881544884E+00 | = 0.247748464E+05 = 0.110257493E+01 =-0.802132375E+05 |
| execution | sma meaan altp lat state | | initia | date primid timrfl | | altp bmag c3 Outgoi | | 3 | final | date primid timrfi | X X X X X X X X X X X X X X X X X X X | altp bmag c3 | י משי | N X X X X X X X X X X X X X X X X X X X |

initial conditions for phase 30

phase

for

conditions

= 0.999683137E+06 =-0.383159621E-01 = 0.243295862E+03 = 0.249328026E+01 s = 0.999595468E+06 =-0.125208332E-03 y = 0.243295870E+03 = 0.163324385E+01 d = 0.707092718E+04 = 0.999683137E+06 =-0.383159621E-01 = 0.243295862E+03 = 0.249328026E+01 =-0.795543919E-01 = 0.412702068E+02 0.254510830E+00 0.412702068E+02 0.859778813E+03 conic mean2000 conic mean2000 conic mean2000 H H 11 16 u 11 11 fpa anlong: vperi ש propid fpa anlong vperi propid . fpa anlong : vperl : perlod : scmass SCMASS scmass propid epoch vinfz hypta vinfz hypta tburn 0.183800755E+04 0.249327985E+01 0.300827182E+03 0.183800755E+04 0.249327985E+01 0.300827182E+03 0.183800683E+04 0.183800755E+04 0.163322957E+01 0.927014015E+02 0.183799147E+04 0.128482565E+04 0.999175488E+02 =-0.550897883E+00 = 0.253339604E+03 = 0.999175488E+02 0.860051331E+00 0.999595468E+06 tdurp bodyeq tdurp tdurp bodyed bodyeq Ħ radius speed argp rperi radius speed argp rperi radius speed argp rperi critr frame vinfy bdr altit vinfy bdr altit critr frame dvmag Wprop critr frame =-0.435350032E+03 = 0.351880260E+00 = 0.160000013E+02 =-0.999438825E-05 =-0.375184198E+05 = 0.360845359E+00 = 0.319956731E+02 = 0.224979356E+03 =-0.435350032E+03 = 0.351880260E+00 = 0.160000013E+02 =-0.999438825E-05 0.716436071E+00 0.487427692E+04 0.157280445E+02 =-0.435350032E+03 = 0.23024221E+00 = 0.16000000E+02 =-0.345410362E-01 = 0.183800855E+04 = 0.286478898E+03 =-0.649346509E+00 = 0.470871315E+04 =-0.486055217E+01 0.0000000.0 0.0000000.0 =-0.121638038E+00 = 0.876691951E+02 .375184198E+05 0.0000000.0 noom Moon HOOF . . . H H # W tdurp 1dbody tdurp 1dbody z vz inc tfp rapoap tdurp idbody vinfx bdt dec maneuver vinfx bdt dec meaan dvz dmass z vz inc tfp maneuve z vz inc tfp 2 A =-0.399028725E+06 =-0.236826329E+01 = 0.270586764E+01 9 = 0.282191705E+03 =-0.157497959E+03 =-0.246469328E+01 = 0.133048215E+01 =-0.671145151E-01 =-0.157497959E+03 =-0.246469328E+01 = 0.133048215E+01 =-0.67114515E-01 =-0.157497959E+03 =-0.161459752E+01 = 0.464584100E-05 = 0.151941342E+03 = 0.999185524E+03 = 0.343774677E+03 = 0.938906217E+00 = 0.152622667E+02 =-0.133955141E+03 =2450007.80000000 = 0.938906217E+00 = 0.297525992E+01 =-0.139689121E+03 =2450007.80000000 = earth 0.850095765E+00 0.100000000E+07 =2450007.80000000 = earth =-0.399028725E+06 =-0.151816753E+01 impuls 1mpuls before earth body: earth after earth vinfm = (btheta = (H # H 32 julian vinfm btheta 32 body: anlong julian julian secid secid secid y vy eccen truan moon y vy eccen truan eccen truan eccen ۷y ROOM moom alta long 32 oing Asymptote
= 0.999168289E+02 vinf
= 0.488085612E+04 bthe
= 0.881544884E+00 ra
e relative to secondary bo
= 0.247748464E+05 y
= 0.110257493E+01 vy
=-0.802132375E+05 ecce ra lock dvy spi ra phase for phase relative to secondary = 0.247748464E+05 y = 0.10553555E+01 vy state relative to idbody:

x ==0.177874576E+04

vx = 0.133834579E+00

sma ==0.556159178E+04

meaan ==0.835248487E=02

Incoming Asymptote state relative to idbody: x =-0.17874576E+04 vx = 0.133834579E+00 sma =-0.556159178E+04 meaan =-0.835248487E-02 phase | Asymptote | 0.999168289E+02 | 0.488085612E+04 | 0.881544884E+00 Ę id = moon f1 = 0.35000000E+01 e relative to idbody: =-0.177874576E+14 = 0.866151970E-01 = 0.183800001E+04 = 0.181941091E+03 = 0.999014743E+02 = 0.0000000000E+00 7.20 7.20 moon 0.350000000E+01 =-0.472193816E-01 = 0.100000000E+07 7.20 for for 1995 conditions 17 1995 conditions =10 17 1995 conditions = moon **=**10 **=**10 altp = bmag = c3 = Outgoing altp = bmag = c3 H initial Initial timrf1 primid פ fmpuls thrust primid timrfl state final state meaan altp bmag c3 primi date argp altp lat SHA d v v SHA ×× ××

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initial conditions for phase 35 initial conditions for phase 35

| | propid = conic | epoch = meanzoou | | ACHARA . 0 999595468E+06 | fra == 0 105008330E-03 | an]ong = 0.1252633222 03 | VDerf = 0.163324385E+01 | Deriod = 0 707092718E+04 | | | | | | |
|-------------------------------|--|--------------------------|-----------------------|--------------------------------|-------------------------|--------------------------|---|--------------------------|-------------------------------------|-----------------------|---------------------|----------------------|------------------------|--------------------------------|
| | 0.00000000 critr = tdurp | hadnog = poglet | | $radius = 0.1838007558 \pm 04$ | speed = 0.163322957E+01 | argp = 0.927014015E+02 | =-0.345410362E-01 rper1 = 0.183799147E+04 | altit = 0.999175488E+02 | | | | | | |
| | | | | =-0.435350032E+03 | = 0.230242221E+00 | = 0.16000000E+02 | =-0.345410362E-01 | 0 = 0.183800855E + 04 | longp = 0.286478898E+03 | | =-0.375184198E+05 | = 0.239207320E+00 | = 0.225267625E+02 | |
| | tdurp | 200 | | 2 | ΛZ | | - | | | | 2 | 72 | inc | meaan |
| 35 | date =10 17 1995 7.20 julian =2450007.80000000 tdurp = primid = moon secid = earth | | uoo | =-0.157497959E+03 | y =-0.161459752E+01 | ccen = 0.464584100E-05 | ruan =-0.151941342E+03 | lta = $0.999185524E+02$ | ong = 0.343774677E+03 | body: earth | 0.399028725E+06 | vy =-0.151816753E+01 | ccen = 0.161775606E+01 | nlong = 0.286629773E+03 |
| final conditions for phase 35 | =10 17 1995 7.20 j | timrf1 = 0.350000000E+01 | relative to idbody: m | =-0.177874576E+04 y | - 0.866151970E-01 V | - 0.183800001E+04 e | =-0.151941091E+03 t. | * 0.999014743E+02 a | lat = 0.000000000E+00 long = 0.3437 | relative to secondary | - 0.247748464E+05 y | - 0.10553555E+01 V | =-0.267420743E+06 e | = 0.258611030E+03 anlong $= 0$ |
| final | date | t imrf1 | state | × | ×× | SMA | тевап | altp | lat | state | × | ×× | Sma | argp |

initial conditions for phase 75

esn = 75.000 fesn= 75.000 time= 2.45000780D+06 normal termination cpu = 75.370 seconds

execution date and time Thu Oct 29

| <u>د</u> : | <u>ت</u> 1 | 824E+01 | | | | |
|--------------------|---------------|-------------------------|----------------|----------------|----------------|----------------|
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| residue | | O.0000000E+00 | 0.0000000E+00 | 0.0000000E+00 | 0.0000000E+00 | 0.00000000E+00 |
| variables | | 0.24650929E+01 | 0.13320546E+01 | 0.12200590E+01 | 0.15000000E+01 | 0.35000000E+01 |
| Dhase | | 1.0 | 1.0 | 1.0 | 15.0 | 30.0 |
| name | | ٩×× | dvy | zvb | critr | critr |
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output ***

summary

npsol

* * *

total number of iterations = 16 total number of reloaded fn evals = 17 total number of function evaluations = 198 total cpu time = 16164.980 seconds

3.4 EARTH TO JUPITER (COLLOCATION)

The following sample case is a portion of the Voyager mission, Earth to Jupiter phase, to illustrate collocation. Of particular interest is the difference between explicit optimization such as the test case described in Section 3.1, and implicit optimization, or collocation.

The mission starts (event 10) with a S/C mass of 2213689 kg and an input state corresponding to a post park orbit escape burn. Ideally, the initial state should produce a trajectory which leaves Earth and flies by Jupiter with the desired encounter conditions. This would be true for an accurate explicit propagator. With collocation, trajectories are defined as segments between events, and by Hermite cubic polynomials between segment end points, or nodes. In this case, the number of segments per phase is set to 1 for all phases. This represents a rather poor trajectory approximation, unless the events are placed very close together. More will be said about this later. An impulsive ΔV maneuver is placed at this first event (ideally the ΔV should be zero), and at every event except the final event.

The next event (#11) occurs 14 minutes later (.01 days), where another impulsive ΔV is performed (again, ideally equal to zero).

There are 6 more events in the case (#12, 13, 17, 18, 19, 20) which are planned at mission times of 0.21 days, 2.21, 666.1, 684.1, 685.6, and 686.1 days. The last event (#20) ideally corresponds to Jupiter closest approach.

The placing of event times is an attempt to normalize accelerations within each phase. If there is a large difference in accelerations, or trajectory curvature, within a segment (= phase for this case), then the Hermite polynomials are very poor representations of a real trajectory. Inaccurate Hermites will cause divergence in the optimization process.

In this case, the optimization specifies "colloc" with "autoperts". The MXITOP array indicates that Jacobian rescaling occurs immediately after it is initially calculated by finite differencing. A maximum of 150 iterations is allowed after rescaling.

The mission control variables are the ΔV components of the impulsive maneuver at each of the first seven events. Other input control variables for the collocation formulation are specified by the U(22) array elements. These correspond to the Cartesian state vectors at each event from #11 through #20, a total of 7 (components per state) x 7 (events) = 49 elements. These state vectors were obtained from a previous explicit optimization run. In practice, the state vectors could have been obtained by a "WAG" simulation run since collocation can be robust.

The constraints are TFP, B dot T and B dot R at Jupiter closest approach (event 20). Note that lower and upper bounds for the constraints may contain more than 3 elements each. This is not a problem because the collocation process overrides all non-mission constraints, that is, specifies upper and lower bounds for constraints introduced by the collocation process. The collocation process also computes weightings for the non-mission constraints.

The test case output first echoes namelist inputs. Then a summary of NPSOL parameters is displayed. The problem begins with computation of the Jacobian. IPOST will only allow non-zero elements of the Jacobian to be numerically computed. The explicit zeroing out of null elements saves a considerable amount of CP time because a collocation Jacobian will be a sparse matrix. In this case, there are a total of 126 controls and 108 constraints. Of the 13608 Jacobian elements, about 9600 are theoretically non-zero.

The first (before rescaling) iteration (0) summary follows, Of critical interest is the Jacobian condition value (COND T). A value of 3.E7 before rescaling and 3000 after rescaling indicates a poorly conditioned Jacobian. The independent (control) and dependent (constraint) parameter values are displayed after each iteration summary.

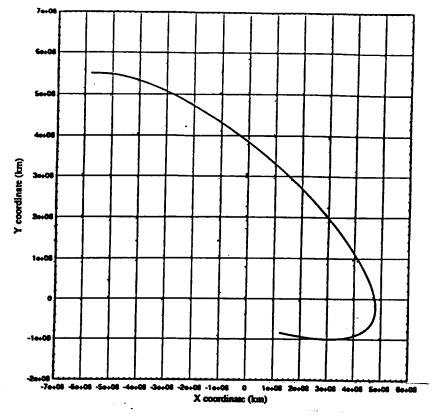
The next iteration takes place and the resultant independent and dependent parameter values are displayed after the iteration 1 summary. Noteworthy items include the Jacobian condition of 40000 (a significant worsening), norm of the nonlinear constraints of 8.84 (also degraded), and an objective (total ΔV) of 4.40 (internal units).

Intermediate iterations are omitted to save space. The final converged iteration (#140) is displayed. The Jacobian condition number has improved slightly, but is still bad. The norm of constraint violation is very small, indicating constraints have been met. However, this has occurred at the expense of an objective value increase to 5.19.

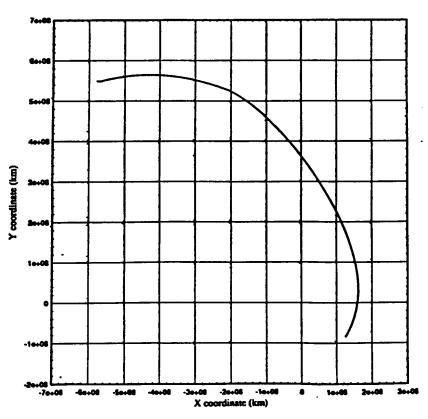
The final solution is displayed after convergence. In this case, a whopping 51.9 km/s total ΔV is required. This large ΔV indicates an aberrant solution. Figure 3 - 1a is an x-y plot of the final trajectory. This points out an interesting phenomenon. Even though NPSOL has found an optimal, and a "feasible", solution, as indicated by the TTT convergence flags, the solution is not realistic from an engineering perspective. A local optimum has been found. Sometimes the mathematical robustness of collocation is deceiving.

The problem in this case is the number of segments per phase. When they are increased to two segments per phase, then a solution illustrated in Figure 3 - 1b occurs. The total ΔV in that case is 14 km/s. The input file shown can be used for two (or more) segments per phase by changing NSEGPH to more than 1. With COINTP = 'LINEAR', IPOST will interpolate linearly between the event states to supply the internal node states.

Unfortunately, collocation is not as simple as always increasing the number of segments per phase. As with any optimization problem, particularly one with high dimensionality such as collocation, the local performance manifold is strongly determined by weightings (independent and dependent parameters), bounds, and initial conditions. These can be very tricky with the large dimensions associated with collocation, and may produce misleading solutions. Caveat emptor!



a) 1 Segment/Phase, $\Delta V = 52 \text{km/s}$



b) 2 Segments/Phase, $\Delta V = 14 \text{ km/s}$

Figure 3 - 1. Ecliptic View of Earth to Jupiter Mission

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radius = 0.656300000e+04 scm
                                                                                                                                                                                                                                                                                                                                                                                                                                                                          = 0.16441001e+04
= 0.291782080e+01
=-0.286142123e+04
p o s t - interplanetary post simulation. version 2.18 , dated 03-05-90.
                                         earth to jupiter trajectory. more events added in between. input modified for local body relative simulation more events added at end for jupiter effect.
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n (from v2collold.out)

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= 0.367619898e+02 vz

=-0.289808128e+04 z
                                                                                                                                                                                                                                                                                                                                                                                                                                              10 after launch
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                           galileo 1989 veega trajectory
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c state relative primary body: sun
c x = 0.125746521e+09 y
c vx = 0.245437654e+02 vy
c x = 0.514649030e+04 y
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indvr(4) = 'dvx','dvy','dvz',
indph(4) = 3*11,
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indvr(1) = 'dvx','dvy','dvz',
indph(1) = 3*10,
u(1) = 3*0,
wvu(1) = 3*0.01,
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0.213689293e+06,
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                                                                                                indx!(10) = 10,11,12,
indvr(10) = 'dvx','dvy','dvz',
indph(10) = 3*13,
u(10) = 3*0.,
wvu(10) = 3*0.01,
                                                                                                                                                                                                               indxi(13) = 13,14,15,
indvr(13) = 'dvx', 'dvy', 'dvz',
indph(13) = 3*17,
u(13) = 3*0.,
wvu(13) = 3*0.01,
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indvr(19) = 'dvx','dvy','dvz',
indph(19) = 3*19,
u(19) = 3*0.,
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indvr(16) = 'dvx','dvy','dvz',
indph(16) = 3*18,
indvr(7) = 'dvx','dvy','dvz',
indph(7) = 3*12,
u(7) = 3*0,
wvu(7) = 3*0.01,
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-0.1523066e-02,0.17929715e+07,0.11606819e+06,

-0.1523066e-02,0.17929715e+07,0.11606819e+06,

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0.0000000E+00 0 7.7787823E+05 phzcmi - change of reference 2.1022709E-19 -5.2990956E+05 -1.2464656E+05 4.0478631E+00 master problem target/dep parameters phzcmi - change of reference 2.1022709E-19 -5.2257046E+08 6.4215123E-01 tfp bdti bdri 20.000 20.000 evtnum

OPTIONS file

1.E-6 1.E-6 1.E-7 1.E-7 YES 200 MAJOR ITERATIONS LIMIT
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Calls to NPOPTN

major iteration limit =

Nov 1989 --- Version 4.05 NPSOL

Parameters

Function precision.... 1.00E-06 1.00E+20 1.00E+20 1.00E-07 1.00E-07 Optimality tolerance... Nonlinear feasibility.. Linear feasibility.... Infinite bound size.... Infinite step size.... 0 126 2.00E+00 108 126 Variables.....step limit..... Nonlinear constraints.. Nonlinear Jacobian vars Linear constraints....

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| The user sets 9604 out of 13608 Jacobian elements. Each iteration, 4004 Jacobian elements will be estimated numerically. | mated numerically. | | |
| The user sets 0 out of 126 objective gradien Each iteration, 126 gradient elements will be esti | gradient elements. be estimated numerically. | | |
| Verification of the constraint gradients. | | | |
| Every column contains a constant or missing element. | | | |
| //NPCRSH// Working set selected //NPCRSH// NFIXED LINACT //NPCRSH// 0 0 108 | | | |
| //NPIQP // NQPERR //NPIQP // 0 | | | |
| //NPFEAS// The maximum violation is 2.58E+02 in constraint | constraint 187 | | |
| //NPMRT // QPCURV GRDALF //NPMRT // 4.72E+06 5.30E+06 | | | |
| //NPMRT // SCALE RHONRM GRDALF //NPMRT // 1.00E+00 1.06E+02 -2.36E+06 | | | |
| Itn ItQP | Norm Gf Norm Gz C 4.6E-03 3.0E-03 1 | Cond H Cond Hz Cond T 1.E+00 1.E+00 3.E+07 | Norm C Penalty Conv 3.1E+02 1.1E+02 F FF |
| Exit NP phase. INFORM = 4 MAJITS = 0 NFUN = | 1 NGRAD = 1 | | |

| Residual | 0.1000E+14 0.1000 | 0.4248E+10 0.4248E+10 0.4248E+10 0.4680E+06 |
|-----------------|--|---|
| Lagr multiplier | 0.000000000000000000000000000000000000 | 0.0000000E+00 0.0000000E+00 0.0000000E+00 |
| Upper bound La | 00000E+1 00000E+1 00000E+1 00000E+1 | 0.4248389E+10 0.4248389E+10 0.4248389E+10 467969.2 |
| Lower bound | -0.1000000E+1 -0.10000000E+1 -0.10000000E+1 -0.10000000E+1 -0.10000000E+1 -0.10000000E+1 -0.1000000E+1 -0.100000E+1 -0.1000000E+1 -0.10000000E+1 -0.100000000E+1 -0.100000000E+1 -0.100000000E+1 -0.100000000E+1 -0.100000000E+1 -0.100000000E+1 -0.1000 | -0.4248389E+10 -0.4248389E+10 -0.4248389E+10 -467969.2 |
| Value | 00000000000000000000000000000000000000 | -0.9963593 0.7658641E-01 -0.3745247E-01 1.000000 |
| State | ###################################### | ጸተ የተ የ |
| able | 15.000 15 | |
| Variabl | VARBL | VARBL VARBL VARBL VARBL |

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4949.

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4949.

4949.

4949.

64245E+10

64245E+10

64245E+10

64243E+10

64243E+10

64243E+10

64243E+10

64243E+10

64243E+10

64243E+10

64243E+10

6421E+10

6421E+10

6421E+10

6421E+10

6421E+10

6431E+10

6431E+10
      0.0000000E+00

0.0000
    4949.378
4949.378
4949.378
4949.378
0.4244562E+10
0.4244562E+10
0.4244562E+10
0.4244562E+10
0.424387E+10
0.4243287E+10
0.7792062E+10
0.779379E+11
0.4719379E+11
0.4719379E+11
0.4248389E+10
0.4248389E+10
0.4248389E+10
 -4949.378
-4949.378
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-4949.378
-0.4244562E+10
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-0.4244562E+10
-0.4243287E+10
-0.424821E+08
-0.424831E+08
-0.4248319E+11
-0.419379E+11
-0.4248389E+10
0.8091057

0.5876627

-0.7066262E-03

-0.7106262E-03

0.7729733E-01

1.000000

0.6381483

0.753357E-01

0.753357E-01

0.753357E-01

0.7753357E-01

0.776361E-01

0.776361E-01
 VARBL 57

VARBL 58

VARBL 60

VARBL 61

VARBL 62

VARBL 65

VARBL 67

VARBL 67

VARBL 67

VARBL 71

VARBL 71

VARBL 71

VARBL 72

VARBL 73

VARBL 74

VARBL 76

VARBL 86

VARBL 76

VARBL 86

VARBL 176

VARBL 176

VARBL 86

VARBL 87

VARBL 89

VARBL 89

VARBL 89

VARBL 91

VARBL 91

VARBL 92

VARBL 93

VARBL 93

VARBL 91

VARBL 92

VARBL 93

VARBL 94

VARBL 96

VARBL 97

VARBL 100

VARBL 100
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            VARBLI12
VARBLI13
VARBLI14
```

| 4949. 0.4245E+10 0.4245E+10 0.4245E+10 0.4680E+06 7949. 7950. 0.4243E+10 0.4243E+10 0.4243E+10 | Residual | 00000000000000000000000000000000000000 | 0.0000E+00 0.0000E+00 0.0000E+00 |
|---|-----------------|--|---|
| 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 | ıgr multiplier | -2618724. -924272.6 195248.15 195248.15 -6881.528 -133743.5 643451.4 -67.19727 -152933. -67.19727 -1305610. -63943.70 -63943.70 -63943.70 -63943.70 -63943.70 -63943.70 -64.48641 -1305610. -64.48641 -14601.25 -1300678. -64.380.00 -59.06284 -1257839. -68313.29 -23909.25 -13909.25 -1344.681 -33.66281 | -29597.88 -899.9141 12767.25 |
| 4949.378 0.4244562E+10 0.4244562E+10 0.4244562E+10 467969.2 7949.562 7949.562 7949.562 0.4243287E+10 0.4243287E+10 | Upper bound Lac | -0.5062759E-05 0.11792972E-02 0.0100000E-03 0.000000E+00 0.0000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.0000000E+00 0.000000E+00 0.0000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.000000E+00 0.0000000E+00 0.000000E+00 | 0.0000000E+00 0.0000000E+00 0.0000000E+00 |
| -4949.378 -0.4244562E+10 -0.4244562E+10 -0.4244562E+10 -467969.2 -7949.562 -7949.562 -7949.562 -7949.562 -0.4243287E+10 -0.4243287E+10 -0.4243287E+10 | Lower bound | 062.75928-0 01.60688-0 00000000000000000000000000000000 | 0.0000000E+00 0.0000000E+00 0.0000000E+00 |
| -0.7006262E-03 -0.9963062 0.7729733E-01 -0.3740303E-01 1.000000 0.6381483 0.7698296 -0.1136648E-01 -0.9962885 0.753357E-01 0.7753357E-01 | Value | -0.3612631E-02 0.1046931E-01 0.4179538E-03 0.00000000E+00 0.0000000E+00 0.00000000E+00 0.0000000E+00 | |
| # # # # # # # # # # # # # # # # # # # | State | | 000 |
| VARBL115 VARBL116 VARBL117 VARBL119 VARBL120 VARBL121 VARBL122 VARBL123 VARBL124 VARBL125 | Nonlnr constr | Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z | NLCON 40 NLCON 41 NLCON 42 |

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0.0000E+00

0.000E+00

0.0000E+00

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-25045.32
-28.31639
-28.31639
-20176.43
-20178.24
-633.93.24
-21914.11
-21914.11
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0.4716660E-17

0.00000000E+00

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| | | | | | .00E-02 | .90E-14 0 | 151 | | | |
|--|-----------------|-----------------|-----------|------------|---|---|--|--|--|---|
| 0.0000E+00 -10.77 -3.343 -0.11338 0.1159E-01 0.2654E-01 -0.1277E-04 | | | | | rance 1 | ciston 9 | frequency | | | |
| 4.806 2666 2666 2611 2611 4612 | | | | | COLD start Crash tole | Function pre Verify level | Save frequ | | 1.0790953E+01 | -7.1927729E+00 |
| | | | | | 1.00E-06 1.00E+20 1.00E+20 | 1.00E-07 1.00E-07 9.00E-01 | 10 0 0 | 5.11E-05 | 5.3680124E+00 | .2487854E+01 |
| 0.0000000E+00 0.000000E+00 0.000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 | | | 1989 | | lity size size | feasibility tolerance | level level | Ľ | | 5 91134E+07 -3.2 |
| 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 | 00E+00 | | .05 Nov | | Linear feasibility Infinite bound sizo Infinite step size | Optimality toler Nonlinear feasib Linesearch toler Derivative level | print print o be sa | Central diffce inte W(770500). W(63756). | , | 1.18 |
| en en | 0.000000E+00 | | Version 4 | | Linear Infini Infini | Opt. Non Line Deri | Major Minor RUN to | Cent (590), W(594), W(| 3 464656E | 0 .6185003E+08 |
| 0.0000000E+00 -10.76769 -3.343200 -0.1337628 0.1159156E-01 0.2653756E-01 0.0000000E+00 | e value = | it = 150 | NPSOL | | 126 2.00E+00 | 108 126 126 3.55E-15 | 150 702 0 | 0-3 | -1 | S |
| E E O O O O O O O O O O O O O O O O O O | Ir objective | ration limit | A I | | ints | constraints Jacobian vars objectiv vars ne precision) | ns limit. ns limit. m file | erval ided is em we need | ge of refe -5.299095 | ge of refe -5.225704 |
| NLCON101 NLCON102 NLCON103 NLCON104 NLCON105 NLCON106 NLCON106 NLCON107 NLCON108 | Final nonlinear | major iteration | | Parameters | Linear constraints Variables | Nonlinear constraints Nonlinear Jacobian vars Nonlinear objectiv vars EPS (machine precision) | Major iterations limit Minor iterations limit RUN loaded from file | Difference interval 1.00 Workspace provided is IW(To solve problem we need IW(phzcmi - change of reference | 2.1022709E-19 0.000000E-00 0.00000000 phzcmi - change of reference 2.1022709E-19 -5.2990956E+05 | 4.0478631E+00 phzcmi - change of reference 2.1022709E-19 -5.2257046E+08 -6.4215123E-01 |

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Penalty Conv
7.8E+06 F FF
                                                                                                                                                                                                                                                                                                                                                                                         Cond T Norm C 3.E+03 1.5E+00
                                                                                                                                                                                                                                                                                                                                                                                         Cond H Cond Hz
1.E+00 1.E+00
                                                                                                                                                                                                                                                                                                                                                                                         Norm Gz
3.0E-03
 ut of 13608 Jacobian elements.
Jacobian elements will be estimated numerically.
                                                    ut of 126 objective gradient elements.
gradient elements will be estimated numerically.
                                                                                                                                                                                                                                                                        8.39E-01 in constraint 187
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             6.08E+00 in constraint 157
                                                                                                                                                                                                                                                                                                                                                                                         Norm Gf
4.6E-03
                                                                                                                                                                                                                                                                                                                                                                                        un Merit Bnd Lin Nln Nz
1 3.537582E+06 0 0 108 18
                                                                                                                                                                                                                                                                                                                                          GRDALF
-2.36E+06
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         DRMIN
9.18E-04
                                                                                                                                                        Every column contains a constant or missing element.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           GRDALF
                                                                                                                                                                                                                                                                                                                                                                                                                                                       CURVL
-1.56E+08
                                                                                                                 Verification of the constraint gradients.
                                                                                                                                                                                                                                                                                                                                       RHONRM
7.84E+06
                                                                                                                                                                                                                                                                                                  GRDALF
5.30E+06
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  CURVL
4.72E+05
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        DRMAX
9.25E+01
RCNDBD
1.49E+05
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      GRDALF
7.17E+05
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             RHONRM
                                                    out of 126
out of 13608
                                                                                                                                                                                                                                                                          //NPFEAS// The maximum violation is
                                                                                                                                                                               //NPCRSH// Working set selected....
//NPCRSH// NFIXED LINACT NLNACT
//NPCRSH// 0 108
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           //NPFEAS// The maximum violation is
                                                                                                                                                                                                                                                                                                                                                                                                                                                       min. CURVL
4.72E+05
                                                                                                                                  QPCURV
4.72E+06
                                                                                                                                                                                                                                                                                                                                        SCALE
1.00E+00
                                                                                                                                                                                                                                                                                                                                                                                       Step Nfun
0.0E+00 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    ALFA
1.00E+00
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      RFROBN
2.82E+05
COND
1.01E+05
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     QPCURV
3.45E+05
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            OMEGA (IMAX)
2.64E+06
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             SCALE
9604
4004
                                                    0
126
                                                                                                                                                                                                                                                                                                                                                                                                                             //NPSRCH// INFORM
                                                                                                                                                                                                                                   //NPIQP // NQPERR
//NPIQP // 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                    //NPUPDT// SSBFGS
//NPUPDT// T
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//NPIQP // 0
 The user sets
Each iteration,
                                                    The user sets
Each iteration,
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//NPMRT //
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//NPCORE//
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        //NPCORE//
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Ľ
                                                                                                                                                                                                                                                                                                                                          -2.16E-04
0 108 18 2.6E-03 1.8E-03 9.E+03 9.E+03 2.E+04 7.3E-08 7.8E+02 F TT
 -2.04E+05
0 108 18 2.6E-03 1.8E-03 8.E+02 8.E+02 4.E+04 8.8E+00 4.5E+04 F FF
                                                                                            F TT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         -2.34E-04
0 108 18 2.6E-03 1.8E-03 2.E+04 2.E+04 2.E+04 2.1E-08 7.8E+02 F TT
                                                                                         2.6E-03 1.7E-03 2.E+04 2.E+04 2.E+04 1.0E-07 7.8E+02
                                                                                                                                                                                                                                                                196
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               1.95E-08 in constraint 196
                                                                                                                                                                                                                                                                6.67E-08 in constraint
                                                                                           18
                                                                                                                                                                                                                                                                                                                               GRDALF
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               GRDALF
                                                                                           0 108
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2.13E-04
                                                                                                                                           CURVL
4.82E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          CURVL
2.78E-04
                                                                                                                                                                                                                                                                                                                                                        0
                                                                                         0
                                                                                                                                                                                                                                                                                        GRDALF
-2.16E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        GRDALF
-2.34E-04
 00 4.50E+04
4 2.745792E+05
                                                                                        279 5.191160E+00
                                                                                                                                                                                  CURVL
4.82E-04
                                                                                                                                                                                                                                                                                                                             //NPMRT // SCALE RHONRM
//NPMRT // 1.00E+00 7.78E+02
146 1 3.8E-01 281 5.191079E+00
                                                                                                                                                                                                                                                                                                                                                                                                                                                 CURVL
2.13E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                CURVL
2.78E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               RHONRM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         // 1.00E+00 7.78E+02
1 1.0E+00 282 5.190949E+00
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              //NPFEAS// The maximum violation is
                                                                                                                                                                                                                                                                //NPFEAS// The maximum violation is
                                                                                                                                                                                                                                                                                                                                                                                                          min. CURVL
2.16E-05
                                                                                                                                           min. CURVL
3.99E-05
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          min. CURVL
2.34E-05
                                                                                                                                                                                  ALFA
3.77E-01
                                                                                                                                                                                                                                                                                       QPCURV
2.16E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 ALFA
3.62E-01
//NPMRT // 1.00E+00
1 1 1.0E+00 4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        OPCURV
2.34E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                  ALFA
1.00E+00
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               SCALE
                                                                                                                     O O
                                                                                        145 1 1.0E+00
                                                                                                                 //NPSRCH// INFORM
                                                                                                                                           //NPUPDT// SSBFGS
//NPUPDT// F
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                                                                                                                                                                                                                                                                                                                                                                                 //NPSRCH// INFORM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  //NPSRCH// INFORM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          //NPUPDT// SSBFGS
//NPUPDT// F
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//NPIQP // 0
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                                                                                                                                                                                  //NPUPDT//
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                                                                                                                                                                                                                                                                                        //NPMRT //
//NPMRT //
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//NPMRT //
147 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      //NPMRT //
//NPMRT //
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//NPUPDT//
```

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GRDALF
-1.22E-04
0 0 108 18 2.6E-03 1.8E-03 1.E+04 1.E+04 2.E+04 1.1E-08 7.8E+02 F TT
                                                                                                               2.6E-03 1.8E-03 2.E+04 2.E+04 2.E+04 3.9E-08 7.8E+02 F TT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            0 108 18 2.6E-03 1.7E-03 1.E+04 1.E+04 2.E+04 2.7E-09 7.8E+02 T TT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  0.1000E+14
0.1000E+14
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Residual
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 0.0000000E+00
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         Upper bound Lagr multiplier
                         3.54E-08 in constraint 196
                                                                                                                                                                                                                                                                           9.18E-09 in constraint 196
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        2.28E-09 in constraint 164
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       NGRAD =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                0.1000000E+14
0.1000000E+14
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    286
                                                                                      GRDALF
-1.13E-04
0 108 18 ;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      GRDALF
-1.26E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                -0.1000000E+14
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       NEON
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           Lower bound
                                                                                                                                                               CURVL
1.40E-04
                                                                                                                                                                                                                                                                                                                                                                                                             CURVL
1.66E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     150
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   RHONRM
7.78E+02
5.190844E+00
                                                                                                                                                                                                                                                                                                  GRDALF
-1.22E-04
                                                   GRDALF
-1.13E-04
                                                                                      / SCALE RHONRM
/ 1.00E+00 7.78E+02
3.6E-01 284 5.190925E+00
                                                                                                                                                                                                   CURVL
1.40E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                               CURVL
1.66E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  GRDALF
-1.26E-04
                                                                                                                                                                                                                                                                                                                                     3CALE RHONRM
1.00E+00 7.78E+02
+00 285 5.190874E+00
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                         The maximum violation is
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         //NPFEAS// The maximum violation is
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                                                                                                                                                                                                                                                                                                                                                                                                           min. CURVL
1.22E-05
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                                                                                                                                                              min. CURVL
1.13E-05
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                                                                                                                                                                                                   ALFA
1.00E+00
                                                 QPCURV
1.13E-04
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     // SCALE
// 1.00E+00
1 1.0E+00 286
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1.22E-04
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1.00E+00
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1.26E-04
                                                                                                                                         II
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//NPMRT // 1.0
149 1 1.0E+00
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..1000E+14
..1000E+16
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0.4248E+10
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0.0000000E+0
      -0.1000000E+14
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-275.2018

2.840364

-4.892074

-4.892074

-5.168941

0.1183573

-194.5295

63.57746

0.32183456-01

-0.250806066-01

0.120843546-02

-0.250806066-01

0.120843546-02

-0.268896-02

-0.10897466-02

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0.4245E+10
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7950.
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0.4680E+08
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0.1524E+08
0.1524E+08
0.1522E+05
0.3752E+05
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0.4949E+08
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2046.
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     0.4244562E+10

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0.3551310

-0.5644899E-01

0.1625220E-04

0.3440113E-01

0.141276

-0.8878891E-02

-0.9648763

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| 0.4680E+06 7950. 7949. 7950. 0.4243E+10 0.4243E+10 0.4243E+10 | Residual -0.1268E-10 0.3884E-10 0.1881E-10 | 0.0000E+00 0.0000E+00 0.0000E+00 -0.3303E-14 0.4931E-13 0.3500E-14 | 0.0000E+00 0.0000E+00 0.0000E+00 -0.3798E-12 -0.2801E-13 -0.6768E-11 | 0.000E+00 0.1088E+14 0.0000E+00 -0.2860E-12 -0.3876E-14 -0.7307E-11 | 0.1909E-16 0.1494E-14 0.2061E-15 0.6417E-16 -0.7821E-11 -0.1214E-15 0.1384E-15 0.6068E-18 | 0.3563E-14 -0.2281E-08 0.0000E+00 0.1269E-17 -0.8581E-17 -0.4468E-13 0.1198E-14 -0.6884E-10 |
|---|--|--|--|--|--|--|
| 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 | Lagr multiplier -0.8430971E-01 -0.8995378E-01 -0.7799870E-02 | 0.2098225 -0.5181035E-01 -0.1551691 0.8943637 -1.286776 0.8019190E-01 | 6.373173 -4.276942 -0.7959879 0.7218794 -1.070901 0.7493884E-01 0.69193824E-01 | 0.2819703 -0.6630108E-01 -0.1597573E-01 0.6942502 -1.062504 0.7629208E-01 0.8599938E-11 16.71425 | -0.9740813 70.62834 -158.9018 14.26755 0.9418140E-11 3.313150 -6.233249 0.7410129 0.271528 | 0.5703453E-01 0.162285E-10 0.1049116 -0.2634109E-01 0.3027199E-01 0.8340031E-02 -0.4853620E-01 0.5060694E-02 0.1922204E-10 |
| 467969.2 7949.562 7949.562 7949.562 0.4243287E+10 0.4243287E+10 | oper bound L. 8179635E-03 1420342 9064885E-02 | 0000000E+00 0000000E+00 0000000E+00 0000000E+00 | 00000000000000000000000000000000000000 | 0.00000000E+000 0.0000000E+000 0.0000000E+000 0.0000000E+000 | 0.000000000000000000000000000000000000 | |
| -467969.2 -7949.562 -7949.562 -7949.562 -0.4243287E+10 -0.4243287E+10 -0.4243287E+10 | Lower bound -0.8179635E-03 0.1420342 0.9064885E-02 | | 0.0000000E+00 0.0000000E+00 0.0000000E+00 0.0000000E+00 | 0.0000000E+000 0.0000000E+000 0.0000000E+000 0.0000000E+000 | 0.000000000000000000000000000000000000 | |
| 0.1625223E-04 0.3440113E-01 0.1141276 -0.8878891E-02 -0.9648763 0.2806577 -0.5143806E-01 | Value -0.8179635E-03 0.1420342 0.9064885E-02 | 0.0000000E+00 0.0000000E+00 0.0000000E+00 -0.3303124E-14 0.4931092E-13 0.350033E-14 | 0.0000000E+00 0.0000000E+00 0.0000000E+00 -0.3798315E-12 -0.2902643E-13 -0.282034E-13 | 0.0000000E+00 0.1088014E+14 0.0000000E+00 -0.2859650E+12 -0.3875615E+14 -0.7230234E+13 -0.73307027E+14 | 0.1909300E-16 0.149435E-14 0.2061330E-15 0.6416931E-16 -0.7820812E-16 -0.1213614E-15 0.1381520E-15 0.138520E-18 | |
| | State EQ EQ | | | | | |
| VARBL119 VARBL120 VARBL121 VARBL122 VARBL123 VARBL124 VARBL125 VARBL125 | ы | NLCON 4 NLCON 5 NLCON 7 NLCON 8 NLCON 9 | | NLCON 19 NLCON 19 NLCON 20 NLCON 21 NLCON 23 NLCON 23 NLCON 24 | | NLCON 37 NLCON 38 NLCON 39 NLCON 40 NLCON 41 NLCON 43 NLCON 44 NLCON 45 |

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0.1152E-16

0.7923E-17

0.8638E-12

0.1221E-12

0.1221E-12

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0.000
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0.23169266

0.31769265

0.13169265

0.1921239E-01

0.1701638E-02

0.1451955E-10

0.1701638E-02

0.1451955E-10

0.1351948E-01

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  0.1152367E-16
-0.8637661E-12
-0.8825403E-12
-0.8825403E-12
-0.8074238E-02
0.1221174E-12
-0.8074238E-03
0.0000000E+00
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0.2839055E-14
-0.1560821E-13
0.5839055E-14
-0.1560821E-13
0.5839055E-14
-0.2580658E-10
0.3939056E-12
0.197246E-20
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0.197246E-10
0.107393308E-12
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   NICON 47
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NICON 67
NICON 68
NICON 76
NICON 88
NICON 99
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| | | propid = 1step epoch = mean2000 | scmass = 0.213689293E+06 fpa = 0.000000000E+00 anlong = 0.337753198E+02 vperi = 0.000000000E+00 | tburn = 0.526378248E+05 | | ed on 10-1 | inc radius rai |
|--|---|--------------------------------------|--|--|------------------------------------|---|---|
| -0.5211E-10 -0.2467E-10 -0.3177E-11 -0.6526E-18 | | <pre>= timrf1 = ecliptic</pre> | = 0.0000000000E+00 = 0.000000000E+00 = 0.293974405E+03 = 0.65630000E+04 | = 0.492657578E+02 = 0.786316794E+06 | | sing ipost loaded | sma eccen rapoap period hypta c31 |
| 0.5715803E-02 0.1436729E-01 -0.1123698E-02 -0.9678218E-11 | | 0.00000000 critr * | radius speed argp rperi | dvmag wprop | | 3583executed 10/30/92 00:32:55using | vz tfp bdri |
| 0.0000000E+00 0.0000000E+00 0.0000000E+00 | maneuver | tdurp = 0.00 idbody = earth | z =-0.286142123E+04 vz = 0.291946710E+01 inc = 0.28500000E+02 tfp = 0.00000000E+00 | dvz =-0.275201773E+01 dmass = 0.213683206E+06 | ø | 3583executed 10 | vx vy rperi vperi vinfzi bdti |
| 0.0000000E+00 0.0000000E+00 0.0000000E+00 | le = 5.190844 10 before impuls man | | 289808128E+04 121185055E+02 273328701E+01 00000000E+00 | 429264518E+02 48000000E+03 | this data file are | kent pid | z truan i vinfyi |
| -0.5210694E-10 -0.2467057E-10 -0.3177492E-11 -0.6525769E-18 | tive value = r phase 10 bef | julian =244 secid = ea | earth y vy = 0. eccen = 0. truan = 0. | nt block +02 dvy =-0. +06 spi = 0. | - | 0 profil made by | as coning vs-5.0 y x y meaan argp meaan d btheti vinfxi |
| NLCON105 EQ -0.5210694E-10 NLCON106 EQ -0.2467057E-10 NLCON107 EQ -0.3177492E-11 NLCON108 EQ -0.6525769E-18 Exit NPSOL - Optimal solution found. | Final nonlinear objective value = initial conditions for phase 10 | date = 8 20 1977 0 primid = earth | state relative to idbody: x = 0.514649030E+04 sma =-0.378644735E+04 meaan =-0.107441109E-07 | s maneuver print block = 0.240179315E+02 dvy :t = 0.20000000E+06 spi | the file id and parameter list for | ipost file 1.d. 0 10 33std profil made by | time x time x anlong a speed b deci b |
| NLCON105 NLCON106 NLCON107 NLCON108 Exit NPS | Final initi | date primi | state x vx sma meaan | impuls dvx thrust | the | ipo | |

0.601462472E+01 0.897506528E+02 0.316591022E+03 11 11 11 11 scmass fpa anlong vperi radius = 0.779852234E+06 speed = 0.426162002E+02 argp = 0.267531086E+03 rperi = 0.318230194E+04 0.119391909E+05 0.817934336E+00 0.116807583E+03 z vz inc tfp =-0.540219371E+06 =-0.295793904E+02 = 0.154913381E+02 = 0.934517600E+02 earth y vy eccen truan state relative to idbody: exx = 0.562307739E+06 y vx = 0.306680807E+02 vysma =-0.219600282E+03 error = 0.203175025E+06 to Incoming Asymptote

| page 3 | vinfz =-0.408695791E+01 hypta = 0.862988577E+02 | vinfz = 0.817727397E+00 hypta = 0.862988577E+02 | | propid = 1step epoch = mean2000 | scmass = 0.601462472E+01 fpa = 0.897506528E+02 anlong = 0.316591022E+03 vper1 = 0.454491921E+02 | vinfz =-0.408695791E+01 hypta = 0.862988577E+02 | vinfz = 0.817727397E+00 hypta = 0.862988577E+02 | | propid = 1step epoch = mean2000 | scmass = 0.601462472E+01 fpa = 0.897506528E+02 anlong = 0.316591022E+03 vper1 = 0.454491921E+02 | tburn = 0.184050876E-02 | | propid = 1step epoch = mean2000 | scmass = 0.593693257E+01 fpa = 0.899752317E+02 anlong = 0.316667461E+03 vperi = 0.453877303E+02 | vinfz =-0.373245976E+01 hypta = 0.864419184E+02 |
|-------------------------|---|---|---------------------------|--|--|--|--|------------------------|---|--|--|--------------------------|---|--|---|
| | =-0.276078065E+02 = 0.302635915E+04 = 0.773474094E+06 | =-0.295710727E+02 = 0.302981142E+04 = 0.773474094E+06 | | = timrf1 = ecliptic | s = 0.779852234E+06 = 0.426162002E+02 = 0.267531086E+03 = 0.318230194E+04 | =-0.276078065E+02 = 0.302635915E+04 = 0.773474094E+06 | =-0.295710727E+02 = 0.302981142E+04 = 0.773474094E+06 | | <pre>= timrf1 = ecliptic</pre> | s = 0.779852234E+06 = 0.426162002E+02 = 0.267531086E+03 = 0.318230194E+04 | = 0.612011171E-01 = 0.786316644E+06 | | <pre>= timrfl = ecliptic</pre> | = 0.815073990E+07 = 0.426543175E+02 = 0.267720382E+03 = 0.331128057E+04 | =-0.275097491E+02 = 0.302740525E+04 = 0.814436176E+07 |
| | vinfy bdr altit | vinfy bdr altit | | critr frame | radiu: speed argp rperi | vinfy bdr altit | vinfy bdr altit | | critr frame | radius speed argp rperi | dvmag wprop | | critr frame | radius speed argp rperi | vinfy bdr altit |
| | = 0.321904344E+02 =-0.153813676E+04 =-0.550476362E+01 | = 0.306594399E+02 =-0.153132531E+04 = 0.109977890E+01 | | = 0.20000000 = earth | = 0.119391909E+05 = 0.817934336E+00 = 0.116807583E+03 = 0.211550656E+00 | = 0.321904344E+02 =-0.153813676E+04 =-0.550476362E+01 | = 0.306594399E+02 =-0.153132531E+04 = 0.109977890E+01 | | = 0.20000000 = earth | = 0.119391909E+05 = 0.81793433EE+00 = 0.116807583E+03 = 0.211550656E+00 | = 0.118357286E-02 = 0.776936929E-01 | • | = 2.00000000 = earth | = 0.153429146E+06 = 0.818783041E+00 = 0.120643834E+03 = 0.221128689E+01 | = 0.323817146E+02 =-0.180287980E+04 =-0.502021452E+01 |
| | vinfx bdt dec | vinfx bdt dec | | tdurp idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | maneuver | tdurp idbody | z vz inc tfp | dvz dmass | maneuver | tdurp idbody | z vz inc tfp | vinfx bdt dec |
| oct 29 | vinfm = 0.426042049E+02 btheta = 0.116941799E+03 ra =-0.406177133E+02 | vinfm = 0.426042049E+02 btheta = 0.116812917E+03 ra =-0.425714892E+02 | 11 | julian =2443375.71000000 secid = earth | -0.540219371E+06 y =-0.295793904E+02 ccen = 0.154913381E+02 ruan = 0.934517600E+02 | vinfm = 0.426042049E+02 btheta = 0.116941799E+03 ra =-0.406177133E+02 | ifm = 0.426042049E+02 leta = 0.116812917E+03 =-0.425714892E+02 | 12 before impuls m | julian =2443375.71000000 secid = earth | =-0.540219371E+06 =-0.295793904E+02 en = 0.154913381E+02 an = 0.934517600E+02 | =-0.516894090E-01 = 0.480000000E+03 | 12 after impuls man | julian =2443377.71000000 secid = earth | th =-0.565807241E+07 =-0.296162861E+02 en = 0.161133523E+02 an = 0.935333129E+02 | vinfm = 0.426531710E+02 btheta = 0.120774636E+03 ra =-0.403494245E+02 |
| Thu Oct | | | e | 34 Ju] | au >₁> au ⊥ | 4 vinfm 4 bthet 4 ra | 4 vinfm 4 btheta 4 ra | phase | | | block 1 dvy 6 spi | phase | | y: earth 7 y 2 vy 3 eccen 7 truan | |
| execution date and time | | | final conditions for phas | date = 8 20 1977 5.04 primid = earth timrfl = 0.21000000E+00 | state relative to idbody: x = 0.562307739E+06 vx = 0.306680807E+02 sma =-0.219600282E+03 meaan = 0.203175025E+06 | altp =-0.319583806E+0 bmag = 0.33948069E+0 c3 = 0.181511828E+0 Outcoing Assumption | | initial conditions for | date = 8 20 1977 5.04 primid = earth | | <pre>impuls maneuver print dvx = 0.327472271E-01 thrust = 0.20000000E+06</pre> | initial conditions for p | date = 8 22 1977 5.04 primid = earth timrf1 = 0.221000000E+01 | 9 11 11 11 15 | =-0.306685943E+0 =-0.352357178E+0 = 0.18192929E+0 ing Asymptote |

| = 0.81876124 = 0.86441918 |
|--|
| vinfz hypta |
| <pre>x = 0.306846113E+02 vinfy =-0.296154901E+02 vinfz = 0.81876124; =-0.179629473E+04 bdr = 0.303131710E+04 hypta = 0.86441918; = 0.109990522E+01 altit = 0.814436176E+07</pre> |
| vinfy bdr altit |
| = 0.306846113E+02 =-0.179629473E+04 = 0.109990522E+01 |
| vinfx bdt dec |
| vinfm = 0.426531710E+02 vinfx = 0.306846113E+02 vinfy =-0.296154901E+02 vinfz = 0.81876124; btheta = 0.120650090E+03 bdt =-0.179629473E+04 bdr = 0.303131710E+04 hypta = 0.86441918 ra =-0.424452406E+02 dec = 0.109990522E+01 altit = 0.814436176E+07 |
| =-0.30685943E+04 = 0.352357178E+04 = 0.181929299E+04 |
| altp bmag c3 |

final conditions for phase 12

| page 5 | 84E+0 24E+0 12E+0 28E+0 | vinfz =-0.101096802E+01 hypta = 0.89999889E+02 | vinfz =-0.101096876E+01 hypta = 0.89999889E+02 | | | propid = 1step epoch = mean2000 | scmass = 0.347283284E+01 fpa = 0.400266924E+02 anlong = 0.198067566E+03 vperi = 0.554771728E+02 | tburn = 0.738519014E-05 | | propid = 1step epoch = mean2000 | scmass = 0.347300639E+01 fpa =-0.836287051E+02 anlong = 0.198104300E+03 vper1 = 0.218322171E+02 | vinfz =-0.122922185E+01 hypta = 0.809071946E+02 | vinfz =-0.808984256E+00 hypta = 0.809071946E+02 | |
|-------------------------|--|--|--|--|----------------------------|---|--|--|---------------------------|--|--|---|---|--|
| | <pre>s = 0.871384688E+09 = 0.554771702E+02 = 0.118056982E+03 = 0.667258354E+09</pre> | = 0.260649290E+01 =-0.228178105E+08 = 0.871378309E+09 | = 0.260647140E+01 =-0.228178058E+08 = 0.871378309E+09 | | | <pre>= timrf1 = ecliptic</pre> | s = 0.871384688E+09 = 0.554771702E+02 = 0.234372329E+03 = 0.667258354E+09 | = 0.425312158E-03 = 0.786314180E+06 | | <pre>timrf1 = ecliptic</pre> | = 0.202205889E+08 = 0.189494785E+02 = 0.232179956E+03 = 0.194761397E+07 | = 0.891779366E+01 = 0.141381020E+06 = 0.201491909E+08 | = 0.339691602E+01 = 0.181267921E+06 = 0.201491909E+08 | |
| | radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | | | critr frame | radius speed argp rperi | dvmag wprop | | critr frame | radius speed argp rperi | vinfy bdr altit | vinfy bdr altit | |
| Thu Oct 29 | = 0.126012838E+08 =-0.101096878E+01 = 0.222041445E+01 = 0.116920439E+03 | =-0.554066751E+02 = 0.666868227E+09 =-0.104416674E+01 | =-0.554066761E+02 = 0.66888227E+09 =-0.104416750E+01 | = 0.125942687E+08 =-0.100981216E+01 = 0.420767629E+01 = 0.670882663E+02 | | = 663.92102000 = Jupiter | = 0.208687118E+07 =-0.125359388E+01 = 0.519097747E+01 = 0.116920439E+03 | = 0.120843234E-03 = 0.313769080E-03 | | = 8.36897999 = jupiter | = 0.118696987E+07 =-0.125008973E+01 = 0.518742040E+01 =-0.120643189E+02 | =-0.162946104E+02 = 0.227972642E+07 =-0.378603454E+01 | =-0.182854823E+02 = 0.227690208E+07 =-0.249066353E+01 | = 0.118765607E+08 =-0.100799717E+01 = 0.205774462E+01 = 0.238645951E+09 |
| | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | 17 before impuls maneuver | tdurp idbody | z vz inc tfp | dvz dmass | maneuver | tdurp idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan |
| | th 0.692481418E+09 = 0.260647562E+01 en = 0.515210557E+07 an = 0.400266995E+02 | .nfm = 0.554771620E+02 heta =-0.195968910E+01 n = 0.177306624E+03 | fm = 0.554771620E+02 sta =-0.195968870E+01 = 0.177306646E+03 | = 0.540935347E+09 = 0.223474083E+00 :cen = 0.219732241E+01 long = 0.327905974E+03 | | lan =2444041.63102000 d = earth +5r | cen = 0.899503265E+01 cen = 0.54509052E+01 uan = 0.40026695E+02 | =-0.250805969E-03 = 0.480000000E+03 | 17 after impuls man | an =2444049.99999999999999999999999999 | ter =-0.764803680E+07 = 0.906121698E+01 n = 0.632774920E+01 n =-0.926648783E+02 | ta = 0.186159168E+02 ta = 0.354874801E+01 = 0.151308779E+03 | m | ay: earth = 0.692846601E+09 =-0.159616862E+01 n = 0.539249615E+07 ng = 0.331015066E+03 |
| | Fearth y y y y eccen truan | vinfm btheta | vinfm btheta ra vinfm btheta l ra cody: sur | | hase | be y vy tr | | block dvy spi | hase | julia | : jupiter y vy eccen truan | vinfm btheta ra | א בא כ | ary body y vy eccen anlong |
| execution date and time | x =-0.528792935E+09 y x =-0.528792935E+09 y vx =-0.554066841E+02 vy sma =-0.129511803E+03 ecce mean = 0.247931494E+09 trua | altp = 0.667251976E+09 bmag = 0.667258484E+09 c3 = 0.307771550E+04 | altp = 0.667251976E+09 bmag = 0.667258484E+09 c3 = 0.307771550E+04 | x =-0.540226210E+09 y vx =-0.261902913E+02 vy sma =-0.390455646E+09 ecce argp = 0.102782260E+03 anl | initial conditions for pha | date = 6 17 1979 3.14 primid = jupiter state relative to idhody | = 0.306159895±08 =-0.169190675£+02 =-0.350695774£+06 | <pre>impuls maneuver print dvx = 0.321533374E-03 thrust = 0.20000000E+06</pre> | initial conditions for ph | <pre>date = 6 25 1979 12.00 primid = jupiter timrf1 = 0.67450000E+03</pre> | relative to idbody = 0.186807615E+08 =-0.165956126E+02 =-0.365560370E+06 =-0.304133670E+04 | į 7 | 5 | , de |

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| 0.400902528E+07 scmass = 0.347300639E+01 0.214256092E+02 fpa =-0.654695124E+02 0.235579637E+03 anlong = 0.198104300E+03 0.150072415E+07 vper1 = 0.237631927E+02 | 0.880444576E+01 vinfz =-0.126183563E+01 0.115734708E+06 hypta = 0.798766643E+02 0.393762728E+07 | 0.211438961E+01 vinfz =-0.740183280E+00 0.147806537E+06 hypta = 0.798766643E+02 0.393762728E+07 | | | timrfl propid = 1step ecliptic epoch = mean2000 | 0.400902528E+07 scmass = 0.347300639E+01 0.214256092E+02 fpa =-0.654695124E+02 0.235579637E+03 anlong = 0.198104300E+03 0.150072415E+07 vper1 = 0.237631927E+02 | 0.135201308E-03 tburn = 0.234777502E-05 0.786314179E+06 | | timrfl propid = 1step ecliptic epoch = mean2000 | 0.339586092E+07 scmass = 0.347292135E+01 0.217051035E+02 fpa =-0.609143874E+02 0.235440158E+03 anlong = 0.198101505E+03 0.150804658E+07 vperi = 0.237594770E+02 | 0.883876677E+01 vinfz =-0.126493716E+01 0.116034426E+06 hypta = 0.799312752E+02 0.332446292E+07 | 0.218387031E+01 vinfz =-0.746443395E+00 0.148178602E+06 hypta = 0.799312752E+02 0.332446292E+07 | |
|--|---|---|--|----------------------------|--|--|---|------------------------------|--|--|---|---|--|
| radius = speed = argp = rperi = | vinfy = bdr = altit = | vinfy = bdr = altit = | | | critr = frame = | radius = speed = argp = rper1 = | dvmag ≕ wprop ≕ | | critr = frame = | radius = speed = argp = rperi = | vinfy = bdr = altit = | vinfy = bdr = altit = | |
| = 0.118554270E+06 =-0.133644213E+01 = 0.518742040E+01 =-0.200330331E+01 | =-0.17973574E+02 = 0.178866738E+07 =-0.363620316E+01 | =-0.197696209E+02 = 0.178630310E+07 =-0.213202986E+01 | = 0.110087801E+08 =-0.109701403E+01 = 0.195356479E+01 = 0.252008105E+09 | | = 18.0000000 = jupiter | = 0.118554270E+06 =-0.133644213E+01 = 0.518742040E+01 =-0.200330331E+01 | =-0.119825393E-03 = 0.997512448E-04 | | = 0.36897999 = jupiter | = 0.756523965E+05 =-0.13472661E+01 = 0.518815080E+01 =-0.163216608E+01 | =-0.177981954E+02 = 0.179566534E+07 =-0.364219107E+01 | =-0.197780979E+02 = 0.179329895E+07 =-0.214832454E+01 | = 0.109735083E+08 =-0.110802104E+01 = 0.195626056E+01 |
| z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | maneuver | tdurp idbody | z vz inc tfp | dvz dmass | maneuver | tdurp 1dbody | z vz inc tfp | vinfx bdt dec | vinf x bdt dec | z vz inc |
| <pre>jupiter y</pre> | vinfm = 0.198961410E+02 btheta = 0.370213015E+01 ra = 0.153678157E+03 | | ry body: earth y = 0.689535677E+09 vy =-0.633027797E+01 eccen = 0.620007279E+07 anlong = 0.332172854E+03 | se 18 before impuls | julian =2444059.63102000 secid = earth | Jupices y y = 0.917226734E+01 eccen = 0.568922792E+01 truan =-0.746707772E+02 | ock dvy =-0.262868944E-04 spi = 0.48000000E+03 | se 18 after impuls | julian =2444059.999999999999999999999999999999999 | <pre>jupiter y</pre> | vinfm = 0.199122983E+02 btheta = 0.369726599E+01 ra = 0.153590533E+03 | vinfm = 0.199122983E+02 btheta = 0.472356563E+01 = 0.173004672E+03 | = 0. = 0. cen = 0. |
| 0.684131020E+03 lative to idbody: 0.400676179E+07 -0.193168363E+02 -0.320029687E+06 -0.616540578E+03 | = 0.142932615E+07 = 0.179240774E+07 = 0.395856425E+03 | = 0.142932615E+07 = 0.179240774E+07 = 0.395856425E+03 | 176 CO SECONDA 614919953E+09 569046839E+02 121546103E+03 124190309E+03 | initial conditions for pha | | = 0.40e co labody: = 0.400676179E+07 =-0.193168363E+02 =-0.320029687E+06 =-0.616540578E+03 | <pre>impuls maneuver print bl dvx =-0.568354464E-04 thrust = 0.20000000E+06</pre> | initial conditions for phase | = 7 5 1979 12.00 = jupiter = 0.684500000E+03 | lative to idbody: 0.338717581E+07 -0.196128868E+02 -0.319510537E+06 -0.503543424E+03 | = 0.14364858E+07 = 0.173941046E+07 = 0.396499624E+03 | altp = 0.143664858E+07 bmag = 0.179941046E+07 less = 0.396499624E+03 | =-0.616737092E+09 x =-0.571539629E+02 ma =-0.120428273E+03 |

| page 7 | epoch = mean2000 | +07 scmass = 0.347292135E+01 +02 fpa =-0.300686698E+02 +03 anlong = 0.198101505E+03 +07 vper1 = 0.237081486E+02 | +01 vinfz =-0.125800774E+01 +06 hypta = 0.798458881E+02 +07 | +01 vinfz =-0.735907290E+00 +06 hypta = 0.798458881E+02 +07 | | | propid = 1step epoch = mean2000 | +07 scmass = 0.347292135E+01 +02 fpa =-0.30066698E+02 +03 anlong = 0.198101505E+03 +07 vper1 = 0.237081486E+02 | -03 tburn = 0.390906267E-05 | | <pre>propid = 1step epoch = mean2000</pre> | 107 scmass = 0.347292780E+01 102 fpa =-0.336020078E+00 103 anlong = 0.198100321E+03 107 vperi = 0.237123840E+02 | +01 vinfz =-0.125809966E+01 +06 hypta = 0.798479314E+02 +07 | 101 vinfz =-0.736002003E+00 106 hypta = 0.798479314E+02 107 |
|----------------------------|--|--|---|--|---|----------------------------|---|---|--|----------------------------|--|--|---|--|
| | = ecliptic | is = 0.177951034E+07 = 0.231511912E+02 = 0.235628108E+03 - = 0.150385483E+07 | = 0.877464073E+0. = 0.116090929E+0 = 0.170811234E+0 | = 0.208210946E+01 = 0.148308338E+06 = 0.170811234E+07 | | | <pre>= timrf1 = ecliptic</pre> | s = 0.177951034E = 0.231511912E = 0.235628108E = 0.150385483E | = 0.225116683E = 0.786314179E | | <pre>= timrf1 = ecliptic</pre> | s = 0.150360260E+07 = 0.237123121E+02 = 0.235630953E+03 = 0.150357218E+07 | = 0.877538735E+01 = 0.116068190E+06 = 0.143220460E+07 | = 0.208269245E+01 = 0.148267847E+06 = 0.143220460E+07 |
| | frame | radiu speed argp rperi | vinfy bdr altít | vinfy bdr altit | | | critr frame | radiu speed argp rperi | dvmag wprop | | critr frame | radiu speed argp rperi | vinfy bdr altit | vinfy bdr altit |
| | $\gamma = \text{jupiter}$ | =-0.563321704E+05 =-0.132991307E+01 = 0.518815080E+01 =-0.505059258E+00 | =-0.177487458E+02 = 0.179337373E+07 =-0.363557154E+01 | =-0.197159362E+02 = 0.179099723E+07 =-0.212579147E+01 | = 0.108648744E+08 =-0.109125315E+01 = 0.186109955E+01 = 0.267119008E+09 | | = 1.50000000 / = jupiter | =-0.563321704E+05 =-0.132991307E+01 = 0.518815080E+01 =-0.505059258E+00 | = 0.108976392E-03 = 0.166084969E-03 | | = 0.50000000 r = jupiter | =-0.111690319E+06 =-0.121222216E+01 = 0.518786447E+01 =-0.506275878E-02 | =-0.177531353E+02 = 0.179297150E+07 =-0.363505538E+01 | =-0.197201609E+02 = 0.179059635E+07 =-0.212560823E+01 = 0.108198206E+08 |
| | idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec | z vz inc meaan | maneuver | tdurp idbody | z vz inc tfp | dvz dmass | maneuver | tdurp idbody | z vz inc tfp | vinfx bdt dec | vinfx bdt dec z |
| Thu Oct 29 | secid = earth | jupiter y = 0.110761256E+07 vy = 0.836672893E+01 eccen = 0.567226417E+01 truan =-0.351362761E+02 | vinfm = 0.198392258E+02 btheta = 0.370377496E+01 ra = 0.153693088E+03 | 1 # 11 | ary body: earth y = 0.68850230E+09 vy ==0.78736652E+01 eccen = 0.679019400E+07 anlong = 0.333220656E+03 | se 19 before impuls | julian =2444061.13102000 secid = earth | Jupiter y = 0.110761256E+07 vy = 0.836672893E+01 eccen = 0.567226417E+01 truan =-0.351362761E+02 | lock dvy =-0.781759852E-04 sp1 = 0.480000000E+03 | se 19 after impuls | julian =2444061.63102000 secid = earth | <pre>jupiter y = 0.143564622E+07 vy = 0.661415878E+01 eccen = 0.56739385E+01 truan =-0.395247099E+00</pre> | vinfm = 0.198434889E+02 btheta = 0.370387995E+01 ra = 0.153696780E+03 | vinfm = 0.198434889E+02 btheta = 0.473349896E+01 ra = 0.173308983E+03 ry body: earth y = 0.688271391E+09 |
| execution date and time Th | rimid = jupiter imrf1 = 0.685631020E+03 | | = 0.143245683E+07 = 0.179712728E+07 = 0.393594880E+03 | Joing Asymptote = 0.143245683E+07 = 0.179712728E+07 = 0.393594880E+03 | = 161219 | initial conditions for pha | id = jupiter | x = 0.139164583E+07 vx = 0.139164583E+07 vx =-0.215454596E+02 sma =-0.321868536E+06 meaan =-0.154107901E+03 | impuls maneuver print bl dvx =-0.180804265E-03 thrust = 0.20000000E+06 | initial conditions for pha | | = 0.432742394E+06 = 0.227388911E+02 =-0.321730253E+06 =-0.154578733E+01 | ounting Asymptotice p = 0.143217418E+07 q = 0.179672442E+07 = 0.393764051E+03 | Outgoing Asymptote altp = 0.143217418E+07 bmag = 0.179672442E+07 c3 = 0.393764051E+03 state relative to secondar x ==0.624966617E+09 |

œ

page

esn = 20.000 fesn= 20.000 time= 2.44406163D+06 normal termination cpu = 1.770 seconds

| | objective function name phase value | dvsum 20.0 0.519084431E+02 |
|--------------|--|--|
| ** | residual | 0.78496517E-10 0.49024238E-03 0.24088510E-03 0.000000000E+00 0.000000000E+00 0.49737992E-13 0.52707838E-05 0.00000000E+00 0.00000000E+00 0.00000000E+00 0.00000000E+00 0.00000000E+00 0.3481428E-12 0.3481428E-12 0.3481428E-12 0.14462317E-05 0.00000000E+00 0.365953E-11 0.49737992E-13 0.26775524E-08 0.00000000E+00 0.28812792E-08 0.1672538E-05 0.11026859E-05 0.11026859E-05 0.1672538E-05 0.11026859E-05 0.1672538E-10 0.3313257E-10 0.4656129E-09 0.4656129E-09 0.4656129E-00 0.4656129E-00 0.4656129E-00 0.4656129E-00 0.4656129E-00 0.4656129E-00 0.4656129E-00 0.4655746E-10 0.2819965E-13 0.00000000E+00 0.2819965E-13 0.000000000E+00 0.23283064E-00 |
| mary output | constraints phase value | 20.0 |
| *** npsolsum | residual name p | 0.0000000E+00e 10x 0.0000000E+00e 10x 0.0000000E+00e 10x 0.0000000E+00e 10x 0.0000000E+00e 10x 0.0000000E+00e 11x 0.0000000E+00e 11x |
| | variables ase value | 10.0 0.24017931E+02 10.0 0.27520177E+01 11.0 0.284036452E+02 111.0 0.284036452E+02 111.0 0.284036452E+02 112.0 0.1783205E-01 113.0 0.1783205E-01 113.0 0.11835729E-02 113.0 0.11835729E-02 113.0 0.11835729E-03 117.0 0.12084323E-03 117.0 0.2508694E-04 118.0 0.2896494E-04 118.0 0.2896494E-04 118.0 0.2896494E-02 118.0 0.2896494E-02 118.0 0.2896494E-02 118.0 0.289649E-02 118.0 0.289649E-03 |
| | name ph | ************************************** |

```
0.28770319E-11
0.17253781E-03
0.00000000E+00
0.00000000E+00
0.00000000E+00
0.00000000E+00
0.00000000E+00
0.4460892E-12
0.72230499E-10
0.72230439E-12
0.195537E-13
0.1955397E-13
0.1955397E-13
0.1955397E-13
0.1955397E-13
0.1955397E-13
0.1955397E-14
0.1055349E-13
0.1955397E-14
0.10553131534E-14
0.10553131534E-14
0.1231609E-18
0.3613135049E-19
0.4533730E-15
0.351609E-18
0.4533730E-15
0.351609E-18
0.4533730E-15
0.12351609E-18
0.12351609E-18
0.12351609E-18
0.12351609E-19
0.14363859E-14
0.14363859E-19
0.60070486E-19
0.60070486E-10
0.6017558E-10
0.6017558E-10
0.6017558E-10
0.6017558E-10
0.6147538E-10
0.6017588E-10
0.28770319E-11

-0.17253781E-03

0.58207661E-10

0.000000000E+00

0.000000000E+00

0.00000000E+00

0.00000000E+00

0.27021499E-10

-0.45337246E-09

0.10683757E-17

0.105549139E-12

0.1055498E-12

0.1055498E-12

0.1055498E-12

0.1055498E-13

0.24789846E-13

0.2677668E-10

0.10612817E-13

0.2677329E-10

0.10612817E-13
 0.63941886E+05
0.11316842E+06
0.1911683627E+06
0.19126836421E+01
0.1912693E+01
0.191364421E+01
0.191364421E+01
0.191364421E+01
0.19136462E+07
0.13299131E+01
0.191299131E+01
0.19139131E+01
0.19139131E+01
0.19139131E+01
0.19139131E+01
0.19139131E+01
0.19139131E+01
0.19139131E+01
0.19139131E+01
0.19139191E+02
0.19139191E+03
111 CO
111 CO
111 CO
111 CO
112 CX
112 CX
113 CX
11
                                                                                                                                                                                                                                                                                                                                                                        8x0
8y0
8z0
```

3.5 OTHER CASES

The following cases contain only the IPOST input, and related discussion. The input corresponds to executable IPOST runs, and are shown to expand the envelope of IPOST usage.

3.5.1 TRAJECTORY SIMULATION

The input file described here performs explicit trajectory propagation. A Cowell, or numerical integration of the equations of motion, is emphasized. There is no targeting or optimization. This rather simple case can be used to compare propagators or effects of forces, to perform sensitivity analyses, to generate initial guesses, such as for collocation runs, or to debug a simulation.

```
= 'conic',
= 10000.d0, .1d0, 28.5d0, 0.d0, 0.d0, 0.d0,
p$top
c test of cowell trajectory propagation
                                                                                                 = 'eartheg','mean2000',
                                                                                                                                      = 'cowell',
= .001,
                                                                                                                                                                                                                                                                                                 = 90,
= 'tdurp',
= 0.,
= 'none',
                       = 'none',
= 90,
                                                                                                               = 3,10,
= 3,
                                                                                                                                                                                                         $
p$traj
c end trajectory
                                                                                                                                                           iforce (1) = 1,
npert (1) = 10,
                                                                                                                                                                                                                                                                          p$traj
c Let's quit
                                                straj
event
iepoch
date
                                                                                                                                                                                 inputx
x
                                                                                                idfram
                      srchm
fesn
iephem
                                                                                                               1pbody
1dbody
                                                                                                                                     iprop
dt
                                                                                                                                                                                                                                     event
critr
value
                                                                                                                                                                                                                                                                                                event
critr
value
namlst
$
```

3.5.2 COMPLETE VOYAGER II

This case is an extension of the Voyager 2 case (Section 3.1). The mission continues beyond Saturn, and includes flybys of Uranus and Neptune. In addition, the Newton-Raphson full rank subproblem targeting is replaced by NPSOL optimization for each subproblem. The master problem remains the same, although central differencing with input perturbation values is used to form the Jacobian.

In the subproblem setup MODELT is set to 'SUBOPT' for each subproblem. Each subproblem still has 3 controls and 3 constraints, but now target error is minimized except for the first subproblem where ΔV is minimized.

```
indxi(5) = 5,6,7,8,9,10,
indvr(5) = 8hdepsvl05,8hdepsvl06,5hcritr,8hdepsvl08,8hdepsvl09,5hcritr,
indph(5) = 30,30, 40,40,50,
u(5) = .359699d6,-.178342d5,3099,.13756d6,.275594d5,4486.,
indph(5) = .18d6,-.34d5,2800,.27d6,4000,,
indph(5) = .71d6,-.85d4,3500,.27d6,55d5,5000.,
pert(5) = .001,.001,.001,.001,.001,.001,.001,
wvu(5) = .359699d6,.178342d5,3.099,.13756d6,.275594d5,4.486,
                                                                                                                                                                                                            c master controls are Jupiter TCA, arrival BDT, arrival BDR, c
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    1,1,1, 2,2,2,
5hvinfx,5hvinfy,5hvinfz, 3hdvx,3hdvy,3hdvz,
3*10, 3*2,2,38521,9.44533,3.19406, 3*0.,
3*1.d-7,3*1.d-5,
                                                                                                                                                                                                                                          = 1,2,3,4,
= 5hcritr,8hdepsv102,8hdepsv103,5hcritr,
= 3*20,30,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          = 'nraph','nraph','nraph','nraph',
= 20,30,40,50,
= 1.0d0,
= 1.0d0,
                                                                                                                                                                                                                                                                                     = 706...175565d7,.121609d6,1487.,

= 650.,88d6,.6d5,1300.,

= 800.,.26d7,.182d6,1600.,

= .001,.001,.001,.001,

= .708,.175565d6,.121609d6,1.487,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                c minimize delta-v for total mission
c
p$top
c... Galileo 1989 VEEGA trajectory
erchm = 'npsol',
                                                                                           = 'forward',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          = 5hdvsum,
                                                                                                                                                                   = 300,
= 1.d-6,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      c
c subrproblem setup
c
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          c
c controls
c
                                                                                                                                                                                                                                                                                                                     c indpub
pert
                                                                                                       npad (1)
ideb
isub
                              srchm
iprint
ipro
fesn
                                                                                                                                                    mxitop
mxitar
ftol
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              modelt
spfesn
tolf
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 indsvr
indsph
usub
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            pertsb
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            optvar
                                                                                                                                                                                                                                                                                                     indplb
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        opt
optph
wopt
etanl
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     indxsi
                                                                                                                                                                                                                                                          indvr
indph
                                                                                            istm
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           tolu
npi
                                                                                                                                                                                                    υ
```

```
= 1,1,1, 2,2,2,

= 3htfp,3hbdt,3hbdr, 3htfp,3hbdt,3hbdr,

= 3*20, 3*30,

= -0001,.175565d7,.121609d6, -.0001,.359627d6,-.178304d5,

= .00001,.01,.01,.01,.001,.1,.1,
                                                                                                                                                              indxsd(7) = 3,3,3, 4,4,
depsvr(7) = 3htfp,3hbdt,3hbdr, 3htfp,5hrper1,
depsph(7) = 3*40, 2*50,
depsvl(7) = -.0001,137566d6,.275594d5, -.0001,.66936d5,
depstl(7) = .00001,1.11, .00001,10.,
indxsi(7) = 3,3,3,4,4,4,
indsvr(7) = 3hdvx,3hdvy,3hdvz, 3hdvx,3hdvy,3hdvz,
indsph(7) = 3*33, 3*43,
usub(7) = 3*0., 3*0.,
pertsb(7) = 3*1.d-6, 3*1.d-5,
                                                                                                                                                                                                                                                                                                                                                                                                               = 'conic',
= 6563.,0.,0.,0.,0.,0.,
                                                                                                                                                                                                                                                                                                        = 'ecliptic',
= 3,
= 3,
= 'conic',
                                                                                                                                                                                                                                                            = 5,
= 'calend',
= 1977,7,31,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    = 10,
= 6htimrf1,
= 20.,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    = 'launch',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  = 'lstep',
= 0,3,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     = 6563.,
= 6563.,
= 28.5,
                                                                                                                                                                                                                                                                                                                                                                 = 1.d6,
= 2.d5,
= 480.,
                                                                                                                                                                                                                                                                                                                                                                                                                                           p$traj
c earth escape
c
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 p$traj
c change idbody
c
                                                                                                                                                                                                                              c
p$traj
event
iepoch
date
                                                                     c targets
c
                                                                                                      depsvr
depsph
depsvl
depstl
                                                                                                                                                                                                                                                                                                        idfram
ipbody
idbody
iprop
                                                                                                                                                                                                                                                                                                                                                                  scmass
thrust
spi
                                                                                                                                                                                                                                                                                                                                                                                                               inputx
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     mantyp
ilnch
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     rperi
rapoap
inc
                                                                                         indxsd
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   iprop
ipbody
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    event
critr
value
                                                             υ
```

```
event = 15,
critr = 5htdurp,
yalue = 20.
ipbody = 0,5,
idbody = 5,
c event = 6htimrfl,
c value = 690.,
s pstraj
c oritr = 6htimrfl,
value = 70.,
mantyp = 'impuls',
dvx = 31,
critr = 5htdurp,
value = 25,
critr = 5htdurp,
value = 26,
critr = 6htimrfl,
s pstraj
c event = 25,
critr = 5htdurp,
value = 100.,
ipbody = 6,
s pstraj
c event = 25,
critr = 6htimrfl,
value = 1487.,
s pstraj
c saturn TCA
c 8/25/1981
c event = 30,
critr = 6htimrfl,
value = 1487.,
pstraj
c event = 33,
critr = 6htimrfl,
value = 1487.,
pstraj
c event = 33,
critr = 5htdurp,
value = 1487.,
pstraj
c event = 33,
critr = 5htdurp,
value = 1487.,
pstraj
c event = 33,
critr = 5htdurp,
value = 135,
critr = 5htdurp,
value = 135,
critr = 5htdurp,
value = 0.40,
s pstraj
critr = 5htdurp,
value = 0.40,
ipbody = 0,7,
```

```
idbody = 7,

p$traj

c event = 40,

critr = 6htimrf1,

straj

critr = 5htdurp,

value = 1000,

mantyp = 1mpuls',

straj

c event = 45,

critr = 5htdurp,

value = 0.40,

ipbody = 8,

idbody = 8,

straj

c event = 50,

critr = 6htimrf1,

value = 0.48,

p$traj

c event = 50,

critr = 6htimrf1,

value = 1486.,

straj

c event = 50,

critr = 6htimrf1,

value = 60,

critr = 60
```

3.5.3 HOHMANN TRANSFER

The Hohmann transfer problem is a classic orbital mechanics solution: The optimal two impulse solution for transferring from one circular orbit to another circular orbit in the same plane is to perform the impulses 180° apart in the direction of travel (for raising an orbit).

This case uses finite burns and collocation. Although the case assumes a low enough thrust such that "impulse" is not a good approximation, and only one segment per phase is assumed, the Hohmann transfer solution in principle is validated.

The first burn occurs in the phase between the first event (# 10) and the second event (# 20), followed by a coasting phase, and then the second burn starting at event 30 and ending at the last event (# 40). Simple thrust tables are input, in this case constant thrust (5000 newtons).

There are 7 mission controls: Thrust direction relative to velocity, throttle, and stop time of the first burn, and start time, thrust direction relative to velocity, throttle, and stop time of the second burn. Invalid guesses of the states are input at each event. There are a total of 49 additional, collocation introduced controls. The constraints are Cartesian position at the end of the second burn. Final mass is maximized.

```
0.00920918
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   0.03637768
                                                                                                                                                                                                                                                                                              'critr', 'critr', 'yaw0','th10', 'critr',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  c date = 7 1 1992 0.22 julian =2448804.50920918 tdurp c state relative to idbody: earth c
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              c date = 7 1 1992 1.09 julian =2448804.54558686 tdurp
c state relative to idbody: earth
c
                                                                                                                                                                                                                                                                                                          indph = 10,10, 20, 30,30,30, 40,

u = 0.11, .007, .035,0.11, .007,

wvu = 180.11, .01, .07, 180.11, .01,
indplb = -180.00, .0001, .01, -180.00, .0001,
indpub = 180.11, .01, .01, .180.11, .1,
                                                                                                                                                                                                                                                                                                                                                                                                             depvr = 'x2', 'y2', 'z2',
depph = 40,40,40,
indxd = 1,2,3,
depvlb = -0.733663153E+04,-0.521113415E+04,0.,
depvub = -0.733663153E+04,-0.521113415E+04,0.,
wvnlc(1) = 1.1.1.,
                         c hohmann transfer orbit test case
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  c initial conditions for phase 20
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 c initial conditions for phase 10
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               u(8) = 0.57790518E+04,
0.56101708E+04,
-0.11805884E-14,
-0.49046907E+01,
0.53057448E+01,
-0.80100503E-18,
0.19999984E+05,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 -0.58963384E+04,
0.61478585E+04,
-0.10105050E-14,
-0.50762013E+01,
0.10379708E+01,
0.10379708E-17,
                                                                        optvar = 'scmass',
opt = 1.
                                                               = 40,
= 'colloc',
                                                                                                                                                                                                               = 40.
= 10000.,
= .5,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  namlst = 'traj',
                                                                                                                            mxitop = 5
ipro = 0
ideb = 0
                                                                                                                                                                                                            optph
wopt
etanl
                                                                  fesn
                                                                                                                                                                                                                                                                                                indvr
                                                                                                                                                                                                                                                                                 Indxi
p$top
```

```
0.00832050
c initial conditions for phase 30 c date = 7 1 1992 1.29 julian =2448804.55390736 tdurp c state relative to idbody: earth c
                                                                                                                                                                                                                                                                                                                    0., 0., 0., 0.,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      table = 'thrstt',0.,5000.,
namlst = 'traj',
                                                            -0.7336315E+04,
-0.52111341E+04,
0.00000000E+00,
0.3590416E+01,
-0.5761545E+01,
0.19999915E+05,
                                                                                                                                                                                                                                                                                            spi = 320.,
inputx = 'conic',
x = 8000., 0., 0
wrop = 10000.,
icord = 1,
iforce(5) = 1,
pitch0 = 0.,
                                                                                                                                                                                                      calend',
1992, 7, 1,
1.d-8,
ecliptic',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               p$traj
event = 20.,
critr = 'tdurp',
value = .007,
iforce(5) = 0,
nsegph = 1,
nsgph0 = 0,
nsgpwd = 0,
nsgpwd = 0,
cointp = 'linear',
$
                                                                                                                                                                                                                                                                                                                                                                                                                                 nsegph = 1,
nsgph0 = 0,
nsgpwd = 0,
nsgpw1 = 0,
cointp = 'linear',
                                                                                                                                                                                                                                                                            20000.,
                                                                                                                                                                                                                                                                                                                                                                               yaw0 = 90.,
thl0 = 1.d0,
namlst = 'table'
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  p$traj
event = 30.,
                                                                                                                                                                                          event
lepoch = 1
tol
tol
idfram = 1
ldfram = 3
idbody = 3
scmass = 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         p$tab
```

```
critr = 'tdurp',
value = .028,
   iforce(5) = 1,
   pitch0 = 0.,
   nam1st = 'table',
   nsgpwd = 0,
   nsgpwd = 0,
   cointp = 'linear',
   $
   pstab
   table = 'thrstt',0.,5000.,
   nam1st = 'ttaj',
   s
   pstraj
   cvent = 40.,
   critr = 'tdurp',
   value = .007,
   iforce(5) = 0,
   nam1st = 'none',
   critr = 'none',
   iforce(5) = 0,
   nam1st = 'none',
   inam1st = 'non
```

3.5.4 LOW THRUST TO JUPITER

This case illustrates a nuclear powered low thrust mission from Earth to Jupiter. There is one long continuous burn. The control parameters are thrust throttle level, and pitch and yaw thrust directions (UVW relative). Constraints are TFP, and closest approach distance at Jupiter arrival. S/C mass at arrival is maximized.

```
= 1,2,3,

= 'pitch0','yaw0','th10',

= 3*15,

= 0.40',90.40',0540,

= 90.40', -179.9999940, 0.40,

= 90.40', 180.40', 1.40',

= 1,1,1,1,1
p$top
c... Galileo 1989 VEEGA trajectory
srchm = 'npsol',
iprint = 0,
ipro = 0,
fesn = 90,
istm = 'central',
npad(1) = 0,
mxitop = 30,
ftol = 1.d-6,
                                                                                                                                                                                                                                                                                                                                                                              = 1977,7,31,
= 'ecliptic','mean2000',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                       = 'conic',
= 6563.,0.,0.,0.,0.,0.,0.,
                                                                                                                                                                            c maximize s/c mass at the end c
                                                                                                                                                                                                                                                                           = 1,2,3,
= 'tfp','rperi',
                                                                                                                                                                                                                                                                                              = 3*20,
= -1.d0,1.0d6,
= 1.d0,2.0d6,
= 1.d0,2.0d6,
                                                                                                                                                                                                     = 6hscmass,
                                                                                                                                                                                                                                                                                                                                                                                               = 3,
= 3,
= 'conic',
                                                                                                                                                                                                                                                                                                                                                                                                                                   = 1.5d5,
= 2.d5,
= 480.,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  p$traj
c earth escape
                                                                                                                                                                                                                                                                                                                               s
c
p$traj
event
lepoch
date
idfram
ipbody
idbody
iprop
                                                                                                                                                                                                                                                 c targets
c indxd
depvr
depph
depvlb
depvub
                                                                                                  indxi
indvr
indph
u
indplb
indpub
pert
                                                                                                                                                                                                     optvar
opt
optph
wopt
etanl
                                                                                                                                                                                                                                                                                                                                                                                                                                    scmass
thrust
spi
                                                                                                                                                                                                                                                                                                                                                                                                                                                                        inputx
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            event
```

```
= 5,6,7,8,9,10,

= 8hdepsv105,8hdepsv106,5hcritr,8hdepsv108,8hdepsv109,5hcritr,

= 30,30, 40,40,40, 50,

= .359699d6,..178342d5,3099,..13756d6,.275594d5,4486.,

= .18d6,-.34d5,2800.,.65d5,.14d5,4000.,

= .71d6,-.85d4,3500.,.27d6,.55d5,5000.,

= .001,.001,.001,.001,.001,.001,

= .359699d6,.178342d5,3.099,.13756d6,.275594d5,4.486,
                                                                                                                                                                                                    master controls are Jupiter TCA, arrival BDT, arrival BDR,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         1,1,1,2,2,2,
5hvinfx,5hvinfy,5hvinfz, 3hdvx,3hdvy,3hdvz,
3*10,3*2,3851,9.44533,3.19406,3*0.,
3*1.d-7,3*1.d-5,
                                                                                                                                                                                                                              1,2,3,4,
5hcritr,8hdepsvl02,8hdepsvl03,5hcritr,
3*20,30,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             indxsi(7) = 3,3,3, 4,4,4,
indsvr(7) = 3hdvx,3hdvy,3hdvz, 3hdvx,3hdvy,3hdvz,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      'nraph','nraph','nraph','nraph',
20,30,40,50,
1.0d0,
1.0d0,
                                                                                                                                                                                                                                                                       = 706., 175565d7, 121609d6,1487.,

= 650., 88d6, 6d5,1300.,

= 800., 26d7, 182d6,1600.,

= .001, .001, .001, .001,

= .708, 175565d6, 121609d6,1.487,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          c minimize delta-v for total mission c
p$top
c... Galileo 1989 VEEGA trajectory
                                                                                   'forward',
                           'npsol',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      = 5hdvsum,
                                                                                                                                                                       = 1.d-6,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            subrproblem setup
                                                                                                                                                                                                                                                                                                                                                                                                                     indplb(5)
indpub(5)
                                                                                                                                                                                                                                                                                                                                                             indxi (5)
indvr (5)
indph (5)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                controls
                                                                                                                                                                                                                                                                                                     indpub
pert
                                                                     fesn
1stm
npad(1)
ideb
isub
                                                                                                                                           mxitop
mxitar
ftol
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```

```
= 1,1,1, 2,2,2,
= 3htfp,3hbdt,3hbdr,3hbdt,3hbdr,
= 3*20, 3*30,
= -0001,.17556547,.12160946, -.0001,.35962746,-.17830445,
= .00001,.01,.01,.01,.1,.1,.1,.1,...
                                                                                                                                                                                                                                                                                                                                                                                     = 3,3,3, 4,4,

= 3htfp,3hbdt,3hbdr, 3htfp,5hrperi,

= 3*40, 2*50,

= -.0001,.137566d6,.275594d5, -.0001,.66936d5,

= .00001,1.,1., .00001,10.,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      = 'conic',
= 6563.,0.,0.,0.,0.,0.,
indsph(7) = 3*33, 3*43,
usub(7) = 3*0., 3*0.,
pertsb(7) = 3*1.d-6, 3*1.d-5,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               = 5,
= 'calend',
= 1977,7,31,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          = 'ecliptic',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       = 'launch',
= 2,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    = 10,
= 6htimrf1,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               = 'lstep',
= 0,3,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 = 15,
= 5htdurp,
= 20.,
= 0,5,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        = 'conic',
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     = 6563.,
= 6563.,
= 28.5,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             = 20.,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    = 1.d6,
= 2.d5,
= 480.,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             pštraj
c change idbody
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              p$traj
c earth escape
                                                                                                                                                                                                                                                                                                                                                                                  indxsd(7) = depsvr(7) = depsvr(7) = depsvl(7) = depsvl(7) = depstl(7) = depstl
                                                                                                   c
c targets
c
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             c
p$traj
event
iepoch
date
                                                                                                                                                                                                                           depsvr
depsph
depsvl
depstl
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ipbody
idbody
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critr
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        iprop
```

```
= 18,
= 6htimrf1,
= 690.,
                                                                            = 20,
= 6htimrf1,
= 708.,
                                                                                                                          = 23,
= 5htdurp,
= 70.,
= 'impuls',
= 3*0.,
                                                                                                                                                                                                                                                      = 30,
= 6htimrf1,
= 1487.,
                                                                                                                                                                                                                                                                                             = 33,
= 5htdurp,
= 100.,
= 'impuls',
= 3*0.d0,
                                                                                                                                                                                    = 25,
= 5htdurp,
= 0,
= 0,6,
= 6,
                                                                                                                                                                                                                                                                                                                                          = 35,
= 5htdurp,
= 0.d0,
= 0,7,
                                                                                                                                                                                                                                                                                                                                                                                               = 40,
= 6htimrf1,
                                                                       event = 20,
critr = 6htime
value = 708.,
$
p$traj
c powered swingby
c
                                                                                                                                                           $
p$traj
c change idbody
c
                c event = 1
c event = 6
c critr = 6
c value = 6
c $
p$traj
c Jupiter TCA
c 7/9/1979
                                                                                                                                                                                                                           pštraj
c Saturn TCA
c 8/25/1981
c
idbody
$
                                                                                                                                                                                                                                                                                            event
critr
value
mantyp
dvx
$
p$traj
event
critr
value
ipbody
idbody
                                                                                                                         event
critr
value
mantyp
dvx
                                                                                                                                                                                    event
critr
value
ipbody
idbody
$
                                                                                                                                                                                                                                                   event
critr
value
$
p$traj
                                                                                                                                                                                                                                                                                                                                                                                 p$traj
c
                                                                                                                                                                                                                                                                                                                                                                                               event
critr
```

```
pstraj
c event = 43,
critr = 5hdurp,
value = 100.

pstraj
c event = 45,
critr = 5hdurp,
value = 0.40,
ipbody = 0.8,
ipbody = 8,
s straj
c event = 50,
critr = 6htimrfl,
value = 4486.,
s straj
c This is the end
c event = 90,
critr = 6htimrfl,
value = 50,
critr = 6htimrfl,
value = 6,
critr = 6htimrfl,
value = 6,
critr = 6,
critr = 6,
event = 50,
critr = 5,
event = 50,
event = 50,
critr = 5,
event = 50,
event = 50,
critr = 50,
event = 50,
```

4.0 REFERENCES

 "Interplanetary Program to Optimize Simulated Trajectories," Final Report, Volumes I, II, III, Fitzgerald, Hong, Kent, Milleur, and Olson, Martin Marietta Corporation, March 1990.

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IPOST is intended to support many analysis phases, from early interplanetary feasibility studies through spacecraft development and operations. The IPOST output provides information for sizing and understanding mission impacts related to propulsion, guidance, communications, sensor/actuators, payload, and other dynamic and geometric environments. IPOST models three degree of freedom trajectory events, such as launch/ascent, orbital coast, propulsive maneuvering (impulsive and finite burn), gravity assist, and atmospheric entry. Trajectory propagation is performed using a choice of Cowell, Encke, Multiconic, Onestep, or Conic methods. The user identifies a desired sequence of trajectory events, and selects which parameters are independent (controls) and dependent (targets), as well as other constraints and the coat function. Targeting and optimization is performed using the Stanford NPSOL algorithm. IPOST structure allows sub-problems within a master optimization problem to aid in the general constrained parameter optimization solution. An alternate optimization method uses implicit simulation and collocation techniques.

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